# **BECKHOFF** New Automation Technology

Manual | EN

CX2500-0031

Serial Interface RS422/RS485





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Version: 1.3





## 1 Foreword

#### 1.1 Notes on the documentation

This description is only intended for the use of trained specialists in control and automation engineering who are familiar with applicable national standards.

It is essential that the documentation and the following notes and explanations are followed when installing and commissioning the components.

It is the duty of the technical personnel to use the documentation published at the respective time of each installation and commissioning.

The responsible staff must ensure that the application or use of the products described satisfy all the requirements for safety, including all the relevant laws, regulations, guidelines and standards.

#### **Disclaimer**

The documentation has been prepared with care. The products described are, however, constantly under development.

We reserve the right to revise and change the documentation at any time and without prior announcement. No claims for the modification of products that have already been supplied may be made on the basis of the data, diagrams and descriptions in this documentation.

#### **Trademarks**

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#### **Patent Pending**

The EtherCAT Technology is covered, including but not limited to the following patent applications and patents:

EP1590927, EP1789857, EP1456722, EP2137893, DE102015105702 with corresponding applications or registrations in various other countries.



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## 1.2 Safety instructions

#### **Safety regulations**

Please note the following safety instructions and explanations!

Product-specific safety instructions can be found on following pages or in the areas mounting, wiring, commissioning etc.

#### **Exclusion of liability**

All the components are supplied in particular hardware and software configurations appropriate for the application. Modifications to hardware or software configurations other than those described in the documentation are not permitted, and nullify the liability of Beckhoff Automation GmbH & Co. KG.

#### **Personnel qualification**

This description is only intended for trained specialists in control, automation and drive engineering who are familiar with the applicable national standards.

#### **Description of symbols**

In this documentation the following symbols are used with an accompanying safety instruction or note. The safety instructions must be read carefully and followed without fail!

#### **A DANGER**

#### Serious risk of injury!

Failure to follow the safety instructions associated with this symbol directly endangers the life and health of persons.

#### WARNING

#### Risk of injury!

Failure to follow the safety instructions associated with this symbol endangers the life and health of persons.

#### **A CAUTION**

#### Personal injuries!

Failure to follow the safety instructions associated with this symbol can lead to injuries to persons.

#### NOTE

#### Damage to the environment or devices

Failure to follow the instructions associated with this symbol can lead to damage to the environment or equipment.



#### Tip or pointer



This symbol indicates information that contributes to better understanding.



# 1.3 Documentation issue state

Version	Changes
1.0	first Version
1.1	notes on DIP-Switch for RS422/RS485 changed
1.2	DIP-Switch information added
1.3	Technical data updated



## 2 Product overview

## 2.1 Intended use

The CX20x0 device series is a modular control system designed for DIN rail installation. The system is scalable, so that the required modules can be assembled and installed in the control cabinet or terminal box as required.

#### Only switch the PC off after closing the software

Before the Embedded PC is switched off, the software currently running on it should be stopped properly in order to avoid data loss on the hard disk. Please read the section on "Switching off".

Switch off all system components and uncouple the Industrial PC from the system if the PC is not used for control purposes, e.g. during a function test. To disconnect first pull the first terminal behind the power supply unit (optional), then pull the connectors of the fieldbus connections.

System components that have been switched off must be secured against being switched on again.

The Embedded PC's power supply unit must be supplied with 24 V<sub>DC</sub>.

#### NOTE

#### Damage to the environment or devices

Do not exchange any parts when under power! The exchange of controller parts when live can lead to short-circuits or overvoltages. These can damage the controller itself and connected peripherals (terminals, monitors, input devices, etc.).

When components are being fitted or removed, the supply voltage must be switched off.

#### Software knowledge

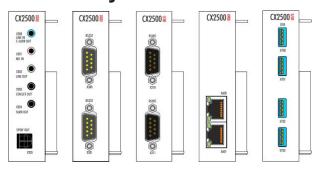
#### NOTE

#### System malfunctions

Mandatory software knowledge! Every user must be familiar with any of the functions of the software installed on the PC that he can reach.



## 2.2 System overview

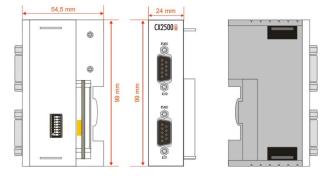


#### CX2500-00xx System modules

The system modules for the CX2000 family are connected to the CPU on the left-hand side via a multi-pin connector. Internally they are connected via PCI Express. Up to four modules can be connected in any order. The CX2500-0020 audio module has jack plug (5 x 3.5 mm) and cinch plug for digital signals (SPDIF). Up to 7.1 multi-channel audio can be used. Serial interfaces can be added with the modules CX2500-0030 (RS232) and CX2500-0031 (RS422/RS485). The CX2500-0060 module provides two further independent Gbit Ethernet interfaces. The CX2500-0070 module can be used to add up to four further USB 3.0 interfaces.

The expansion modules for the CX2000 family are connected to the CPU on the right-hand side via a multipin connector. Up to two CX2550-0010 CFast modules can be connected, so that a total of up to three CFast slots are available.

## 2.3 CX2500-0031 - Technical data



The system interface CX2500-0031 expands a CX20x0 by two serial RS485/RS422 interfaces.

Technical data	CX2500-0031
Interfaces	2x D Sub RS485 / RS422
Power supply	via system bus (via power supply module CX2100-0xxx)
max. Power loss	1.2 W
Current supply	500 V (supply/internal electronics)
Electrical isolation	500 V
Dimensions (W x H x D)	24 mm x 99 mm x 54.5 mm
Weight	approx. 203 g
Operating/storage temperature	-25° C +60° C / -40° C +85° C
Relative humidity	95% no condensation
Vibrations/shock resistant	conforms to EN 60068-2-6 / EN 60068-2-27
EMC immunity/emission	conforms to EN 61000-6-2/EN 61000-6-4
Protection class	IP 20

Further Information: <a href="https://www.beckhoff.de/CX2000">www.beckhoff.de/CX2000</a>



# 3 Mounting and wiring

## 3.1 Unpacking, installation and transport

The specified storage conditions must be adhered to (see "Technical data").

#### Dimensions and weight of the individual modules

Dimensions (W x H x D): 24 mm x 99 mm x 54.5 mm

Weight: approx. 203 g (system interface)

#### Unpacking

Proceed as follows to unpack the unit:

- 1. Remove packaging.
- 2. Do not discard the original packaging. Keep it for transporting the device in the future.
- 3. Check the delivery for completeness by comparing it with your order.
- 4. Please keep the associated paperwork. It contains important information for handling the unit.
- 5. Check the contents for visible shipping damage.
- 6. If you notice any shipping damage or inconsistencies between the contents and your order, you should notify Beckhoff Service.

#### NOTE

#### Danger of damage to the device!

During transport in cold conditions, or if the device is subjected to extreme temperature differences, condensation on and inside the device must be avoided. Prior to operation, the device must be allowed to slowly adjust to room temperature. Should condensation occur, a delay time of approximately 12 hours must be allowed before the unit is switched on.

#### Installation

The devices are designed for installation in control cabinets.

#### **Shipping and relocation**

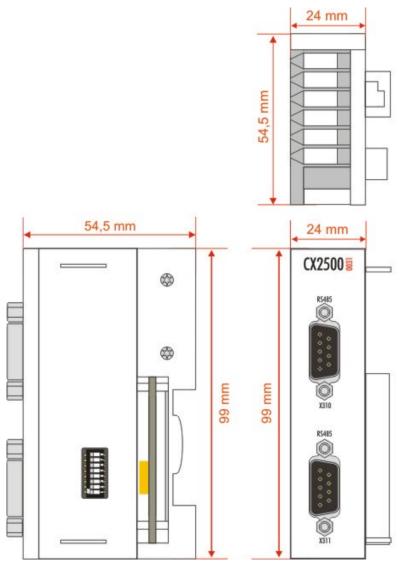
Despite the robust design of the unit, the components are sensitive to strong vibrations and impacts. During transport, your computer should therefore be protected from excessive mechanical stress. Therefore, please use the original packaging.

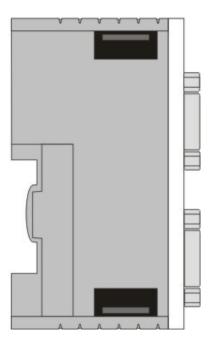


# 3.2 Dimensions

The following drawings show the dimensions of the CX2500-0031 interface.

#### **Dimensions**







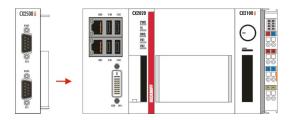
## 3.3 Attaching the system interface to the CX20x0 system

#### **Opening the PCI Express bus cover**

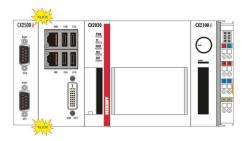
The system interfaces for the CX20x0 system are connected via the internal PCI Express bus, which has a protective cap. The cap can be removed with a screwdriver. To this end insert the screwdriver into the recess in the short side (see diagram) and lever off the cap. The bus connector is then accessible, as shown in the diagram.



Once the bus connector is accessible, the module can be attached on the left-hand side.



The module audibly locks into place.



Further modules can be connected to the system in the same way. Once all modules are connected, the system is placed on the DIN rail as a block. For details please refer to the section on DIN rail mounting.



#### Maximum number of system interfaces

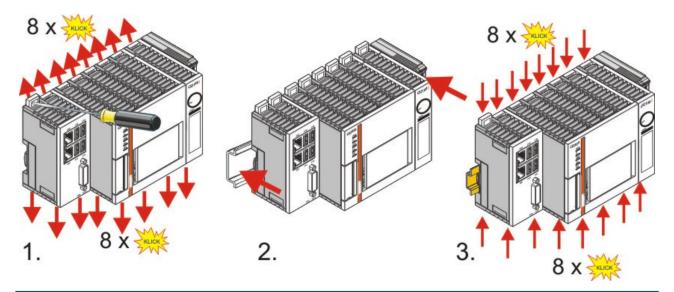


Up to four system interfaces can be attached on the left-hand side of the system.

## 3.4 Installation on the mounting rail

#### Snapping onto the mounting rail

The CX20x0 can simply be snapped onto the mounting rail. The bar clips are inserted on the top side and underside Then simply position the block on the mounting rail and push it slightly until it engages on the right-hand side. This is indicated by a distinct click. The bars are then engaged again. The engagement of the individual bars is indicated by a distinct click.



#### NOTE

#### Avoid damage!

Do not force the module or apply excessive pressure!

#### Installation position

#### NOTE

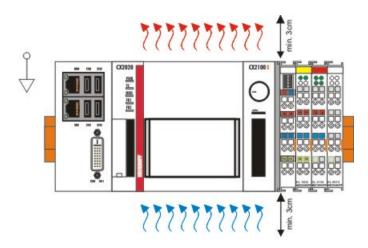
#### Comply with the permitted installation position and minimum distances!

The maximum ambient temperature for CPU modules mounted on a DIN rail is 60°C. The orientation in which the device is fitted must be selected in such a way that cooling air can flow vertically through the ventilation holes. The images below show the permitted and two incorrect installation positions. Mounting must provide a clearance of 30 mm both above and below a CX20x0 device combination to ensure adequate ventilation of the base CPU module and the power supply unit.

#### **Correct installation position**

The high performance and the compact design of the CX20x0 systems may result in increased heat generation. The heat is dissipated via a passive ventilation system. This system requires the unit to be mounted correctly. Ventilation openings are located at the top and bottom of the housing. The system therefore has to be installed horizontally. This ensures optimum air flow.

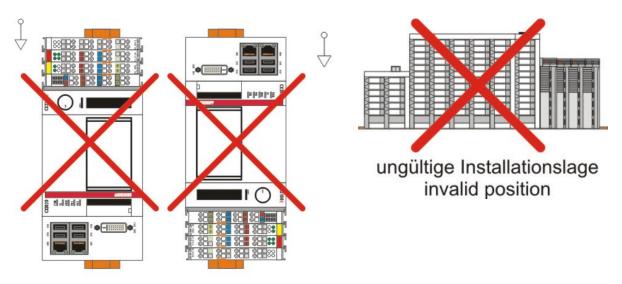




# gültige Installationslage valid position

#### **Incorrect installation positions**

The CX20x0 system must not be operated vertically on the DIN rail. A vertical position would lead to insufficient CPU ventilation, since the ventilation openings are located on the top and bottom of the housing. Installation of the system on its side would also lead to inadequate ventilation.



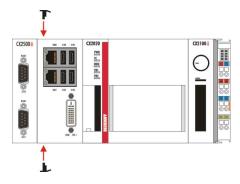
ungültige Installationslage invalid position



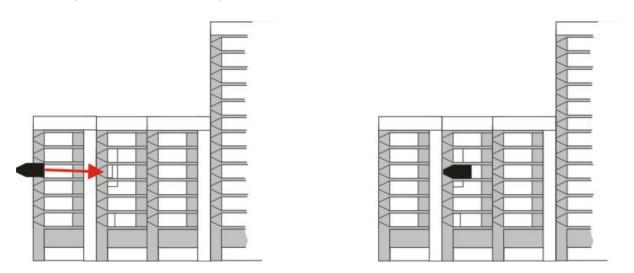
## 3.5 Mounting the module lock

#### Mounting the lock

The CX20x0 controller system is fully modular, i.e. all system interfaces of the system are field-configurable. As a rule the latching of the modules to each other is sufficiently strong. However, it is possible for the controller and its modules to be exposed to vibrations, shocks or impacts. The modules can be securely connected to one another with the aid of bar clips.



The bar clips are inserted on the top side and underside.

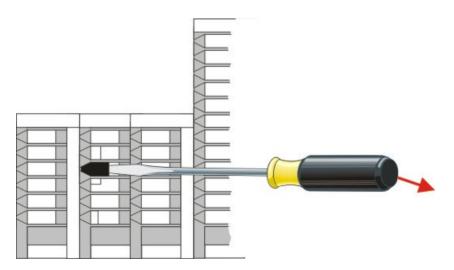


If all system interfaces are locked, then the entire assembly can be snapped onto the support rail.

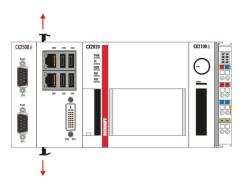
#### **Dismounting the lock**

In order to dismantle the assembly it must first be removed from the support rail. Afterwards the bar clips can be removed with the aid of a screwdriver:



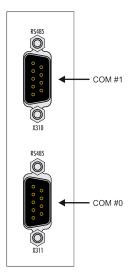


Once the bar clips have been raised they can be pulled out. Subsequently, the system interfaces can be separated again.





## 3.6 Connections CX2500-0031



The CX2500-0031 system interface features two RS422 / RS 485 interfaces. The interfaces are realized via two 9 pin Sub-D plug connectors (X310 and X310). If there is need for more than two serial interfaces up to four modules further RS422 / RS485 interfaces can be added to the system. Thus 9 serial interfaces (four CX2500-0031 modules and the optional interface CX20x0-N031) can be added to the CX20x0 system. The optional interface CX20x0-N031 is shown in the system as COM1. The pin assignment for all interfaces is equal and described below.

The maximum baud rate on both channels is 128 kBit. The interface parameter can be set in the operating system or in the PLC program.

#### COM Interface RS422/RS485 (connector) (X310, X311)

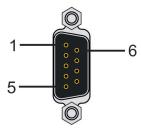


Table 1: Pin assignment COM interface:

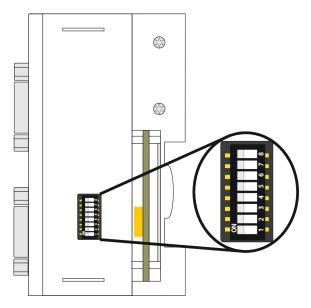
PIN	Signal	Туре	Description
2	TxD+	Data-Out +	Transmit 422
3	RxD+	Data-In +	Receive 422
5	GND	Ground	Ground
6	VCC	VCC	+5V
7	TxD-	Data-Out -	Transmit 422
8	RxD-	Data-In -	Receive 422

For RS 485 Pin 2 and 3 (Data +) as well as Pin7 and 8 (Data -) have to be connected.

#### **Setting the interface parameter**

If the system interface CX2500-0031 is disconnected from the CX20x0 unit it is easy to access the dip switches. Details on the disconnection procedure can be found in the chapter decommissioning. The dip switches for the configuration of the RS422/485 interfaces can be found at the left side of the module. On the left side you can see the switch:





The switch sets the parameters for RS422 or RS485 mode. The mode is set for both interfaces. If you need RS422 and RS485 you need two interface modules CX2500-0031.

A small screwdriver helps to set the switches carefully. The system must be powered down, if the settings of the switches are changed!

#### **Setting DIP-Switches for RS485-mode:**

For the RS485-mode is no echo and no termination available. The mode for send and receive is controlled automatically. If a termination is needed it must be realized via the connector.

DIP	Status	Function
1	on	RS485-Mode
2	on	RS485-Mode
3	on	RS485-Mode
4	on	RS485-Mode
5	on	RS485-Mode
6	on	RS485-Mode
7	on	RS485-Mode
8	on	RS485-Mode

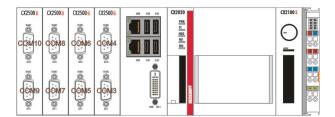
#### **Setting DIP-Switches for RS422-mode:**

As RS422 is full duplex, there can be no echo selected either. The termination is the same as RS485, but on the receiving ends of each pair. This has to be done at the connector.

DIP	Status	Function
1	off	RS422-Mode
2	off	RS422-Mode
3	off	RS422-Mode
4	off	RS422-Mode
5	off	RS422-Mode
6	off	RS422-Mode
7	off	RS422-Mode
8	off	RS422-Mode

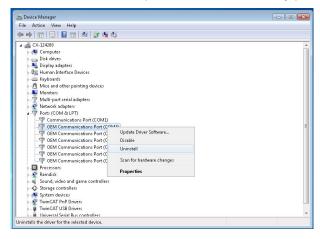
The order of the system interfaces in the operation system is counted from right to left (CPU view) and up to down (X311 -> COM n and X310 -> COM n + 1 for  $n=\{3, 5, 7, 9\}$ ).





If the configuration of the system interfaces is changed the order in the operation system. For a proper order of the system interfaces is a good advice to remove the interfaces manually in the device manager.

To remove the driver open the context menu by pressing the right mouse button and select "uninstall"

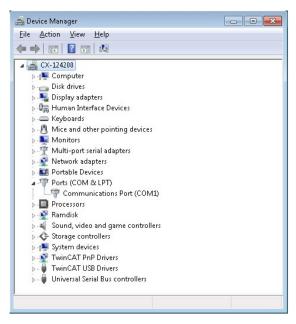


In the following dialog it is very important to leave the driver in the system folders. To do so do NOT select the box in the dialog.



If all serial interfaces are removed in the device manager (except COM1) the system must be shut down. Disconnect the power supply to perform a cold start later.





Change the module configuration. If you have changed the configuration, power the system. The operating system restarts and all modules are ordered in the way described above.



# 4 Commissioning / Configuration

## 4.1 Switching on and off

#### **Switching on**

The power supply for the basic CPU module comes from the power supply unit. The basic CPU module starts automatically when the power supply unit is connected to the mains.

#### Switching on for the first time

When you switch on the PC for the first time, the pre-installed operating system (optional) will be started.

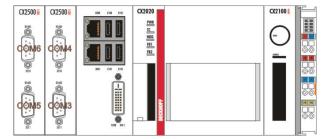
#### **Switching off**

The Embedded PC switches off when the power supply unit is switched off. The control software typically running on Embedded PCs should be shut down or stopped correctly. A user who may not close software may also not switch the Embedded PC off, since data can be lost from the hard disk by switching off while software is running.

Once the software has been stopped, the operating system can be shut down. Only then should the power supply be interrupted.

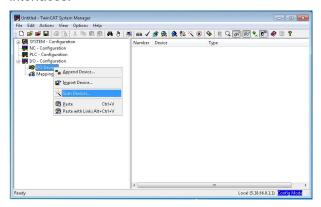


## 4.2 PLC-Interface CX2500-0031

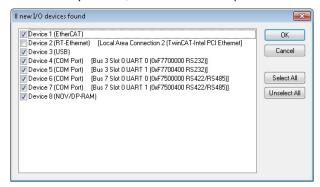


The CX2500-0031 system interface provides two RS422/RS485 interfaces. They can be connected to the PLC via the TwinCAT System Manager.

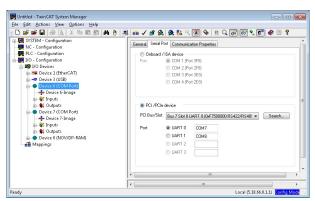
In the System Manager you can open the Scan Devices... context menu, which searches for the serial interfaces.



A window opens in which the interfaces can be selected. At the same time one can automatically search for further components, such as Bus Couplers. The configuration found by the system should always be verified.



Once the scan is complete, the interfaces can be parameterised. Usually no settings are required in the Serial Port tab.

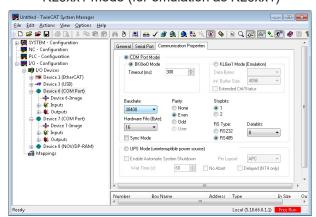


In the Communication Properties tab the interface parameters can be set, e.g.:

• baud rate (50, ..., 460800)



- parity (none, even, odd)
- stop bits (1, 2)
- RS type (RS232, RS485, is default)
- hardware FIFO (16, 32, 64, 138, 256)
- data bits (8, 7, 6, 5)
- COM port mode BK8xx0 mode (for Bus Coupler operation) KL6xx1 mode (for emulation as KL6xx1)



Connection of the interface to TwinCAT is now complete.



# 5 Error handling and diagnostics

## 5.1 Faults

Please also refer to the Safety instructions section.

#### Possible faults and their correction

Fault	Cause	Measures
no function after the Embedded PC has been switched on	no power supply for the Embedded PC other causes	1.Check the fuse     2. Measure voltage at connection, check plug wiring, call Beckhoff support
Embedded PC does not boot fully	Hard disk damaged (e.g. due to switching off while software is running), incorrect setup, other causes	Check setup Call Beckhoff Support
Computer boots, software starts, but control does not operate correctly	Cause of the fault is either in the software or in parts of the plant outside the Embedded PC	Call the manufacturer of the machine or the software.
CF card access error	Faulty CFast card, faulty CFast slot	Use a different CFast card to check the CFast slot Call Beckhoff Support
Embedded PC only works partially or temporarily	Defective components in the Embedded PC	Call Beckhoff support

Please make a note of the following information **before** contacting Beckhoff service or support:

- 1. Precise device ID: CXxxxx-xxxx
- 2. Serial number
- 3. Hardware version
- 4. Any interfaces (N030, N031, B110, ...)
- 5. TwinCAT version used
- 6. Any components / software used

The quickest response will come from support / service in your country. Therefore please contact your regional contact. For details please refer to our website at <a href="https://www.beckhoff.de">www.beckhoff.de</a> or ask your distribution partner.



# 6 Decommissioning

## 6.1 Disassembly and disposal

The disassembly of a CX20x0 hardware configuration with system interfaces takes place in 3 steps

#### 1. Switching off and disconnecting the power supply

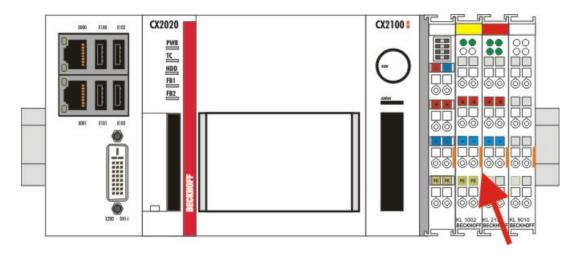
Before a CX20x0 system can be dismantled, the system should be switched off, and the power supply should be disconnected.

#### 2. Removing from the DIN rail

Before the individual modules are disconnected, the whole CX20x0 hardware block should be removed from the DIN rail. Proceed as follows:

#### 2.1. Release and remove the first Terminal next to the power supply unit on the DIN rail.

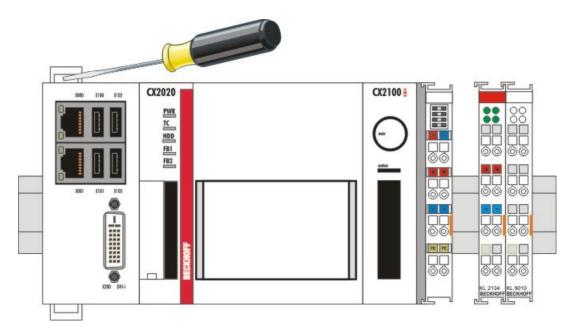
First remove any wiring from power supply unit *and* then from the first terminal on the DIN rail next to the power supply unit. If the wiring is to be reused for another system, it is advisable to make a note of the connections. Then pull the orange terminal release (see arrow) to release the terminal and pull it out.



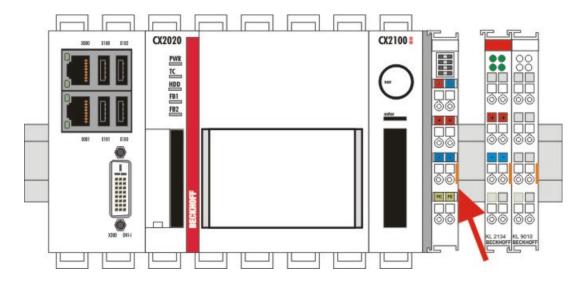
#### 2.2. Releasing the CX20x0 systems

In order to release the CX20x0 block, the DIN rail fastening above and below the device must be released. To do this, press the hooks outwards using a screwdriver. An audible click indicates that the device is released.





After pulling on the terminal release of the power supply unit (see arrow) the block can be **carefully** removed from the DIN rail.



#### **Disposal**

The device must be fully dismantled in order to dispose of it.

Electronic parts must be disposed of in accordance with national electronics scrap regulations.

#### 3. Disconnecting the system interface

Disconnecting the system modules from the basic module

If the modules are locked, i.e. attached with tie clips, the clips must be released. To this end lift the tie clips with a screwdriver and pull them out. Subsequently, the system interfaces can be separated again.

#### NOTE

#### Do not use force to open the device!

Opening the module housing by force would destroy it. The devices may only be opened by Beckhoff service personnel.



## 7 Appendix

### 7.1 Certifications

All products of the Embedded PC family are CE, UL and EAC certified. Since the product family is continuously developed further, we are unable to provide a full listing here. The current list of certified products can be found at <a href="https://www.beckhoff.com">www.beckhoff.com</a>.

#### **FCC Approvals for the United States of America**

#### FCC: Federal Communications Commission Radio Frequency Interference Statement

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

#### **FCC Approval for Canada**

#### **FCC: Canadian Notice**

This equipment does not exceed the Class A limits for radiated emissions as described in the Radio Interference Regulations of the Canadian Department of Communications.



## 7.2 Support and Service

Beckhoff and their partners around the world offer comprehensive support and service, making available fast and competent assistance with all questions related to Beckhoff products and system solutions.

#### **Beckhoff's branch offices and representatives**

Please contact your Beckhoff branch office or representative for <u>local support and service</u> on Beckhoff products!

The addresses of Beckhoff's branch offices and representatives round the world can be found on her internet pages:

http://www.beckhoff.com

You will also find further documentation for Beckhoff components there.

#### **Beckhoff Headquarters**

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#### **Beckhoff Support**

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