

BECKHOFF

Product Overview | 2026



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IPC



10 The IPC Company

I/O



24 The I/O Company

Motion



80 The Motion Company

Automation



100 The Automation Company

MX-System



118 The System Company

Vision



128 The Vision Company

New Automation Technology



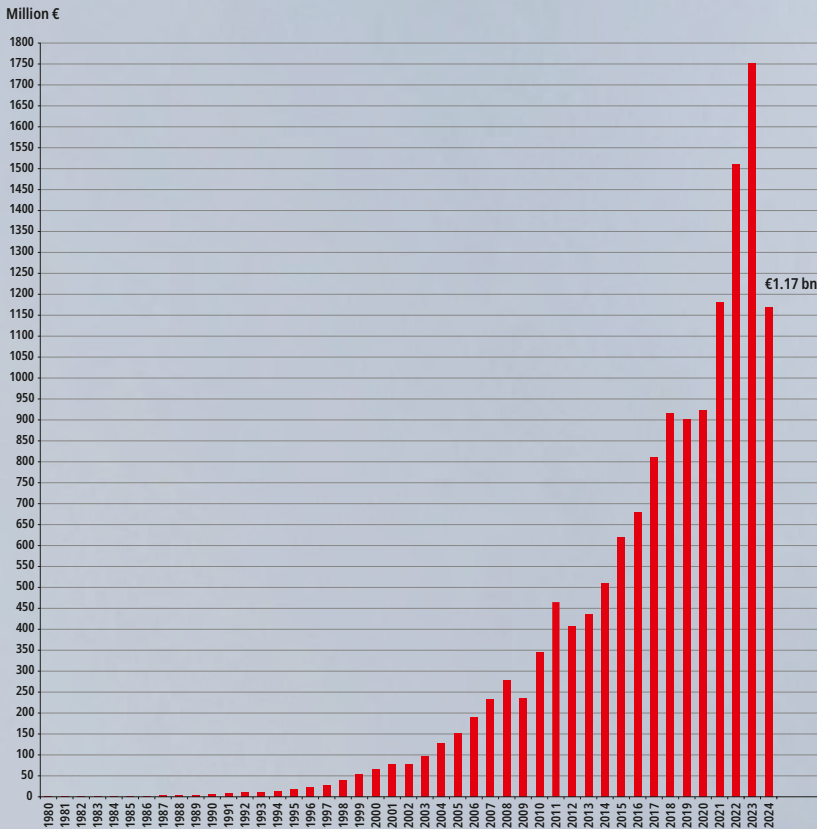
Beckhoff implements open automation systems using proven PC-based control technology. The main areas that the product range covers are industrial PCs, I/O and fieldbus components, drive technology, automation software, control cabinet-free automation, and hardware for machine vision. Product ranges that can be used as separate components or integrated into a complete and mutually compatible control system are available for all sectors. Our New Automation Technology stands for universal and industry-independent control and automation solutions that are used worldwide in a large variety of different applications, ranging from CNC-controlled machine tools to intelligent building control.

Since the foundation of the company in 1980, continuous development of innovative products and solutions using PC-based control technology has been the basis for the continued success of Beckhoff. Many automation technology standards that are taken for granted today were conceptualized by Beckhoff at an early stage and successfully introduced to the market.

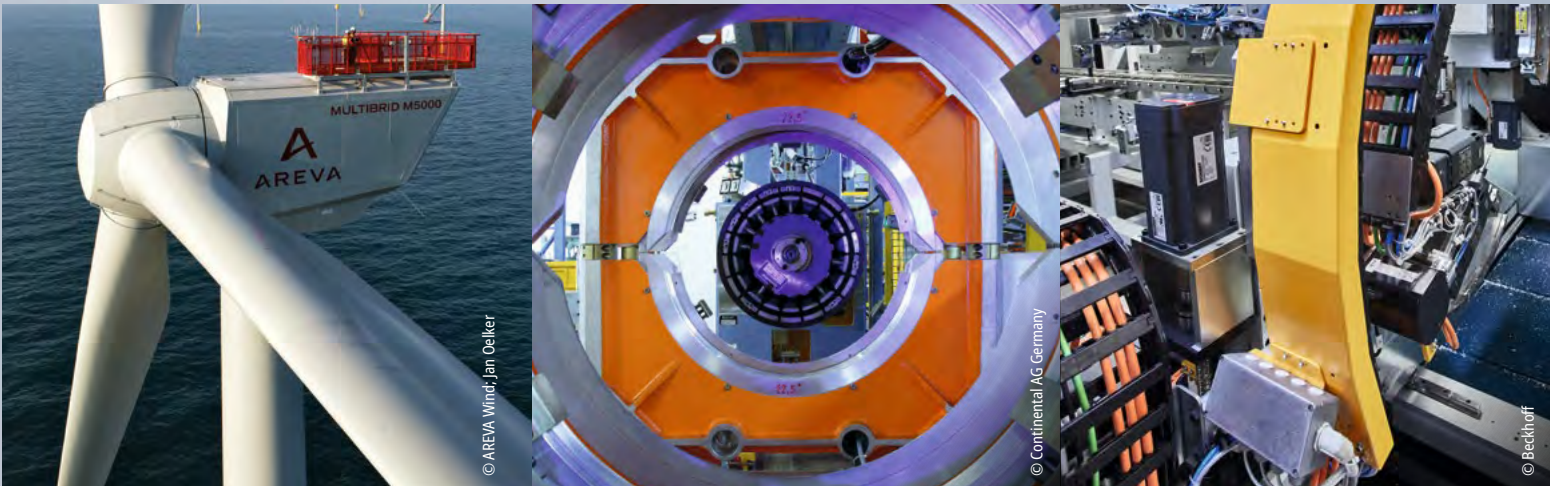
The Beckhoff PC Control philosophy and the invention of the Lightbus system, the Bus Terminals and TwinCAT automation software represent milestones in automation technology and have become accepted as high-performance alternatives to traditional control technology. EtherCAT, the real-time Ethernet solution, makes forward-looking, high-performance technology available for a new generation of leading edge control concepts.

Global presence

The central divisions of Beckhoff, such as development, production, administration, distribution, marketing, support and service are located at the Beckhoff Automation GmbH & Co. KG headquarters in Verl, Germany. Rapidly growing presence in the international market is taking place through subsidiaries. Through worldwide co-operation with partners, Beckhoff is represented in more than 75 countries.

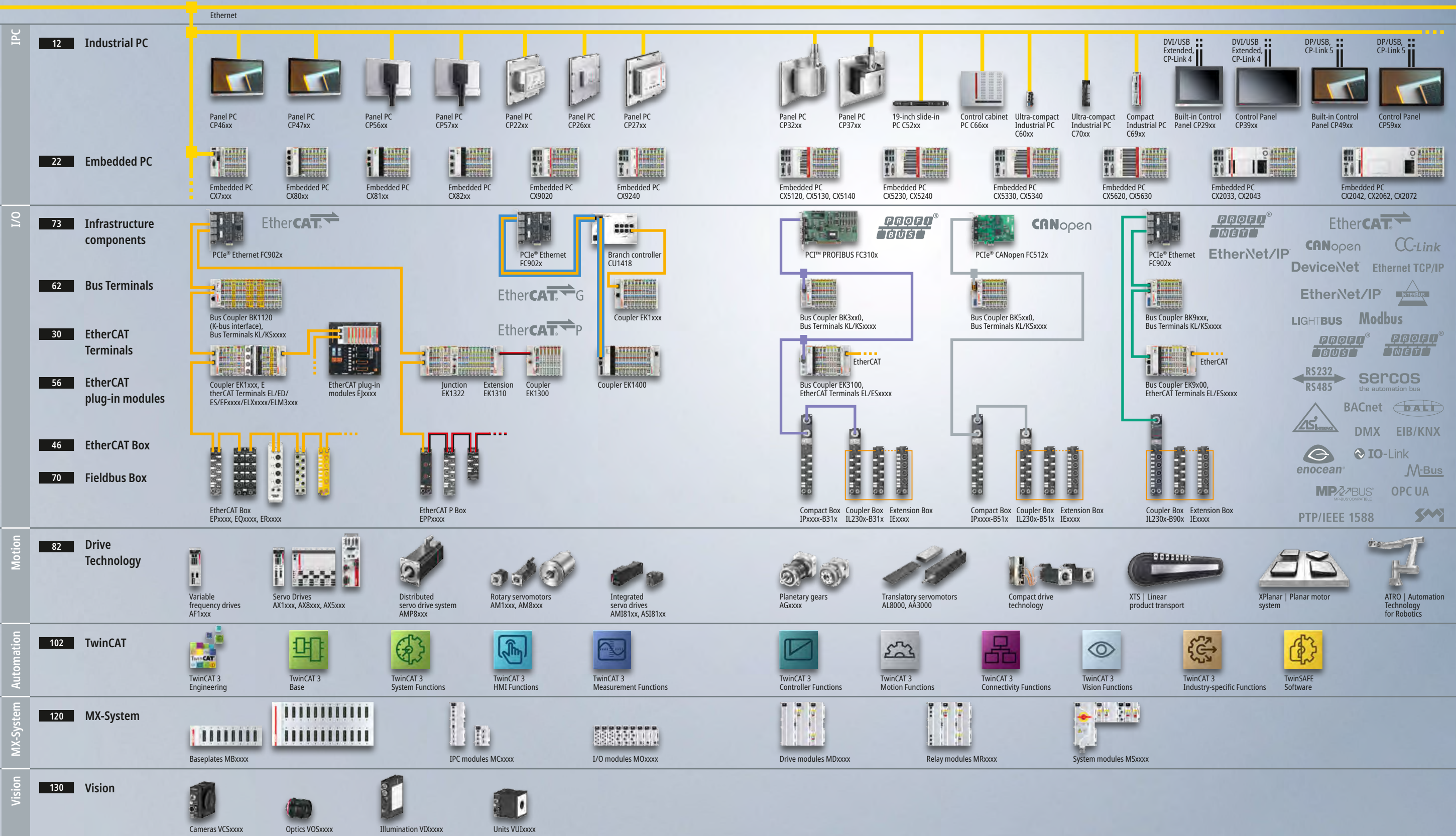


Sales from 1980 through 2024.
Status: March 2025



- Beckhoff Automation at a glance
- 2024 global sales: €1.17 billion
 - Headquarters: Verl, Germany
 - Managing owner: Hans Beckhoff
 - Employees worldwide: 5,300 (March 2025)
 - Engineers: 2,000
 - Subsidiaries/representative offices worldwide: 41
 - Sales offices in Germany: 23
 - Representatives worldwide: > 75

System overview

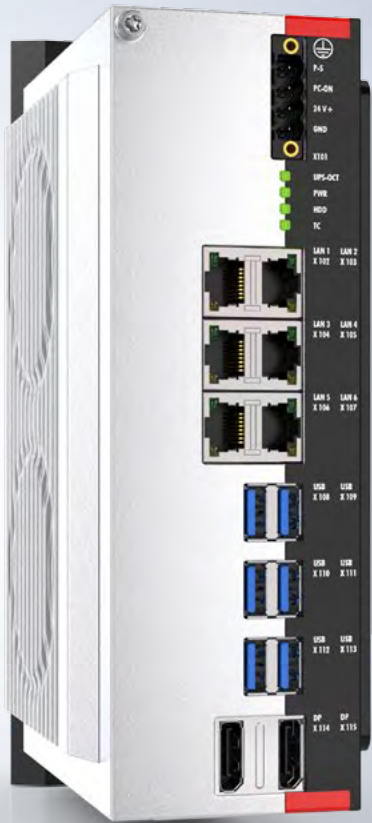


The IPC Company

The Industrial PC (IPC) is the hardware centerpiece of PC-based control technology. Beckhoff supplies Industrial PCs suitable for any application, which are based on open standards, enabling individual configuration to meet a wide range of control requirements.

Whether in the form of an Embedded PC with a compact form-factor for DIN rail mounting, a control cabinet PC, or as a Panel PC, in-house motherboard development enables Beckhoff to respond quickly to IT trends and customer-specific requirements.

► www.beckhoff.com/ipc



Ultra-compact
Industrial PC

Next multi-touch panels 14

- high-quality industrial displays with multi-finger touch function
- Control Panels or Panel PCs
- display sizes from 7-inch to 23.8-inch
- easy installation in the front of a control cabinet or on mounting arms

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Multi-touch Panel PCs 15

- large model variety
- high computing power
- display sizes from 7-inch to 24-inch
- easy installation in the front of a control cabinet or on mounting arms
- special versions for explosion protection
- customer-specific implementations

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Multi-touch Control Panels 16

- large model variety
- display sizes from 7-inch to 24-inch
- landscape and portrait orientation
- easy installation in the front of a control cabinet or on mounting arms
- special versions for explosion protection
- customer-specific implementations

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Industrial PCs 19

- scalable performance range
- highest computing power
- industrial-strength housing designs
- multiple features
- high flexibility in terms of display connections

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Embedded PCs 22

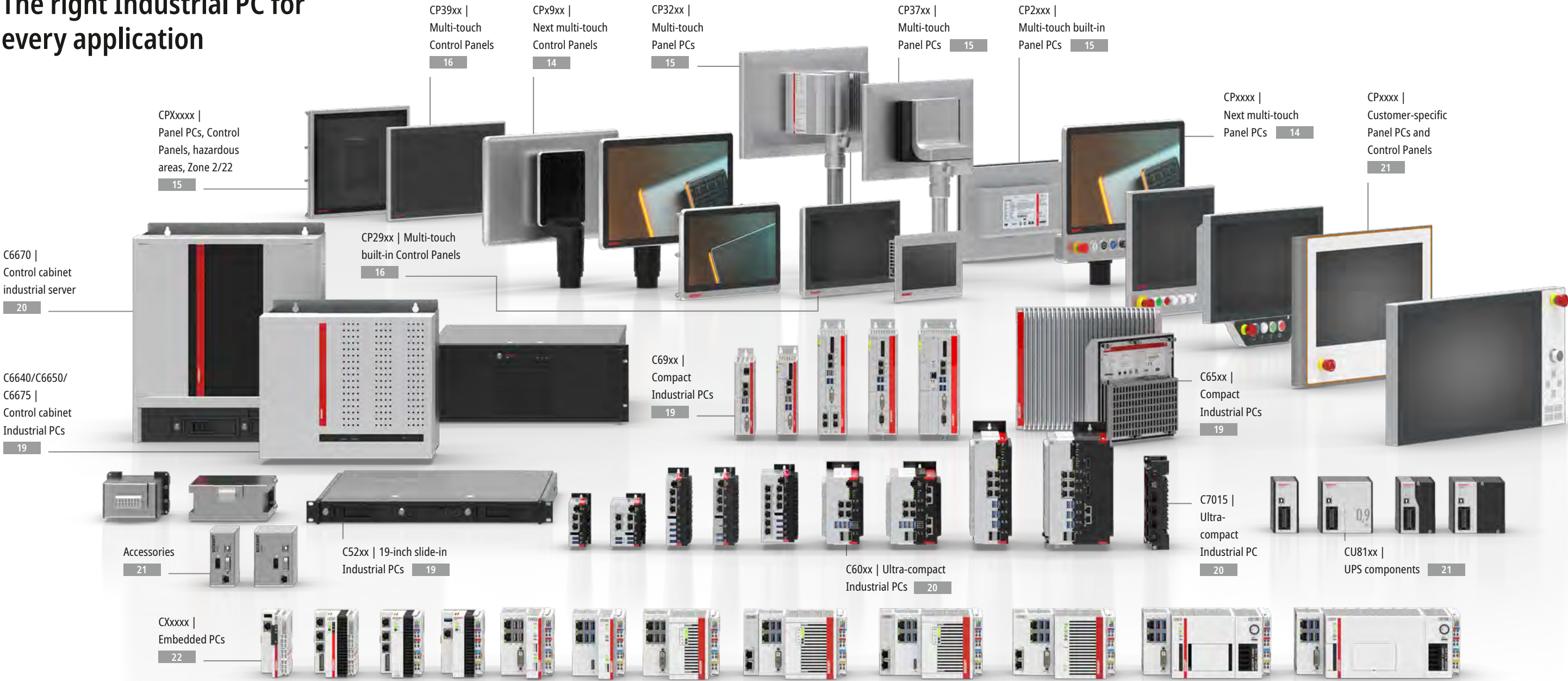
- scalable performance range
- up to 12 cores
- compact design
- direct I/O interface
- modular extension options
- DIN rail mounting

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- large model variety of Industrial PCs and Embedded PCs
- high-performance PCs, featuring a wide range of processors, from Intel® Celeron® to top of the line Intel® Core™ i9 processors
- long-term availability of all Industrial PCs and Embedded PCs
- As the inventor of PC-based control technology, Beckhoff closely cooperates with global technology partners Intel and Microsoft.

The right Industrial PC for every application



Industrial PCs							
	Compact motherboard Intel® Core™	Compact motherboard Intel Atom®	ATX motherboard Intel® Core™	3½-inch motherboard Intel® Core™	3½-inch motherboard Intel Atom®	3½-inch motherboard Arm® Cortex®-A8	Control Panels
Next multi-touch Panel PCs/Control Panels					CP47xx <i>i</i> CP57xx <i>i</i>	CP46xx <i>i</i> CP56xx <i>i</i>	CP49xx <i>i</i> CP59xx <i>i</i>
Multi-touch Panel PCs/Control Panels				CP22xx CP32xx	CP27xx/CPX27xx CP37xx/CPX37xx	CP26xx	CP29xx/CPX29xx CP39xx/CPX39xx
Single-touch Panel PCs/Control Panels		CP77xx		CP62xx CP72xx	CP67xx	CP66xx	CP69xx CP79xx
19-inch slide-in Industrial PCs			C5240	C5210			
Control cabinet Industrial PCs	C6025/C6027 C6030/C6032 C6040/C6043	C6015 C6017 C6025-0020 <i>i</i>	C6640/C6650 C6675	C6515/C6525 C6920/C6930	C6905/C6915 C6925		
IP65 Industrial PCs		C7015					

Control cabinet industrial server			
SSI EEB motherboard 2 x Intel® Xeon® C6670			
Embedded PCs			
Arm® CPU	Intel Atom® CPU	Intel® CPU	AMD CPU
CX7xxx CX80xx CX81xx CX82xx CX9020 CX9240	CX51xx CX52xx CX53xx	CX20x2	CX56xx CX20x3

Next multi-touch panels

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CP4xxx



CP5xxx

Next multi-touch built-in Panel PCs, front side IP65											
	Display	7-inch		10.1-inch		15.6-inch		18.5-inch		21.5-inch	
	Resolution	800 x 480		1280 x 800		1920 x 1080		1920 x 1080		1920 x 1080	
	Format	5:3		16:10		16:9		16:9		16:9	
CP46xx – Arm® Cortex®	multi-finger touch screen	CP4607	i	CP4610	i	CP4616	i	CP4618	i	CP4621	i
CP47xx – Intel Atom®	multi-finger touch screen	CP4707	i	CP4710	i	CP4716	i	CP4718	i	CP4721	i

Next multi-touch Panel PCs, all sides IP65						
	Display	15.6-inch		18.5-inch		23.8-inch
	Resolution	1920 x 1080		1920 x 1080		1920 x 1080
	Format	16:9		16:9		16:9
CP56xx – Arm® Cortex®	multi-finger touch screen	CP5616	i	CP5618	i	CP5624
CP57xx – Intel Atom®	multi-finger touch screen	CP5716	i	CP5718	i	CP5724

Next multi-touch built-in Control Panels, front side IP65								
	Display	7-inch		10.1-inch		15.6-inch		23.8-inch
	Resolution	800 x 480		1280 x 800		1920 x 1080		1920 x 1080
	Format	5:3		16:10		16:9		16:9
CP49xx-0020 – DP/USB	multi-finger touch screen	CP4907-0020	i	CP4910-0020	i	CP4916-0020	i	CP4924-0020
CP49xx-0030 – CP-Link 5	multi-finger touch screen	CP4907-0030	i	CP4910-0030	i	CP4916-0030	i	CP4924-0030

Next multi-touch Control Panels, all sides IP65						
	Display	15.6-inch		18.5-inch		23.8-inch
	Resolution	1920 x 1080		1920 x 1080		1920 x 1080
	Format	16:9		16:9		16:9
CP59xx-0020 – DP/USB	multi-finger touch screen	CP5916-0020	i	CP5918-0020	i	CP5924-0020
CP59xx-0030 – CP-Link 5	multi-finger touch screen	CP5916-0030	i	CP5918-0030	i	CP5924-0030

Multi-touch Panel PCs

► www.beckhoff.com/multi-touch



CP22xx



CP26xx



CP27xx



CP32xx



CP37xx

Multi-touch built-in Panel PCs, front side IP65											
	Display	7-inch		12-inch		12.1-inch		15-inch		15.6-inch	
	Resolution	800 x 480		800 x 600		1280 x 800		1024 x 768		1366 x 768	
	Format	5:3		4:3		16:10		4:3		16:9	
CP22xx – up to Intel® Core™ i3/i5/i7	multi-finger touch screen			CP2212		CP2213		CP2215		CP2216	
CP26xx – Arm® Cortex®-A8	dual-finger touch screen	CP2607		CP2612		CP2613		CP2615		CP2616	
CP27xx – Intel Atom®	multi-finger touch screen, only horizontal			CP2712		CP2713		CP2715 CPX2715		CP2716	

Multi-touch Panel PCs, all sides IP65										
	Display	7-inch		12-inch		12.1-inch		15-inch		15.6-inch
	Resolution	800 x 480		800 x 600		1280 x 800		1024 x 768		1366 x 768
	Format	5:3		4:3		16:10		4:3		16:9
CP32xx – up to Intel® Core™ i3/i5/i7	multi-finger touch screen, only horizontal			CP3212				CP3215		CP3216
CP32xx-1600 – up to Intel® Core™ i3/i5/i7	multi-finger touch screen, only horizontal, mounting arm adapter selectable							CP3215-1600		CP3216-1600
CP37xx – Intel Atom®	multi-finger touch screen, only horizontal			CP3712		CP3713		CP3715 CPX3715		CP3716
CP37xx-1600 – Intel Atom®	multi-finger touch screen, only horizontal, fanless without cooling fins							CP3715-1600		CP3716-1600

Multi-touch Control Panels

► www.beckhoff.com/multi-touch-control-panel



Multi-touch built-in Control Panels, front side IP65										
	Display	7-inch	12-inch	12.1-inch	15-inch	15.6-inch	18.5-inch	19-inch	21.5-inch	24-inch
	Resolution	800 x 480	800 x 600	1280 x 800	1024 x 768	1366 x 768	1366 x 768	1280 x 1024	1920 x 1080	1920 x 1080
	Format	5:3	4:3	16:10	4:3	16:9	16:9	5:4	16:9	16:9
CP29xx-0000 – DVI/USB Extended interface	multi-finger touch screen	CP2907- 0000	CP2912- 0000	CP2913- 0000	CP2915- 0000 CPX2915- 0000	CP2916- 0000	CP2918- 0000	CP2919- 0000 CPX2919- 0000	CP2921- 0000 CPX2921- 0000	CP2924- 0000
CP29xx-0010 – CP-Link 4	multi-finger touch screen	CP2907- 0010	CP2912- 0010	CP2913- 0010	CP2915- 0010	CP2916- 0010	CP2918- 0010	CP2919- 0010	CP2921- 0010	CP2924- 0010

Multi-touch Control Panels, all sides IP65										
	Display	7-inch	12-inch	12.1-inch	15-inch	15.6-inch	18.5-inch	19-inch	21.5-inch	24-inch
	Resolution	800 x 480	800 x 600	1280 x 800	1024 x 768	1366 x 768	1366 x 768	1280 x 1024	1920 x 1080	1920 x 1080
	Format	5:3	4:3	16:10	4:3	16:9	16:9	5:4	16:9	16:9
CP39xx-0000 – DVI/USB Extended interface	multi-finger touch screen	CP3907- 0000	CP3912- 0000	CP3913- 0000	CP3915- 0000	CP3916- 0000	CP3918- 0000	CP3919- 0000	CP3921- 0000	CP3924- 0000
CP39xx-0010 – CP-Link 4	multi-finger touch screen	CP3907- 0010	CP3912- 0010	CP3913- 0010	CP3915- 0010 CPX3915- 0010	CP3916- 0010	CP3918- 0010	CP3919- 0010 CPX3919- 0010	CP3921- 0010 CPX3921- 0010	CP3924- 0010
CP39xx- 14xx-0010 – CP-Link 4	multi-finger touch screen, stainless steel housing			CP3913- 14xx-0010		CP3916- 14xx-0010	CP3918- 14xx-0010		CP3921- 14xx-0010	

Single-touch panels

► www.beckhoff.com/single-touch



Single-touch built-in Panel PCs, front side IP54/65								
	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
	Format	4:3	4:3	5:3	17:10	4:3	4:3	5:4
	Protect. rating front	IP65	IP65	IP54	IP54	IP65	IP65	IP65
CP62xx – 3½-inch motherboard – up to Intel® Core™ i3/i5/i7	without keys function keys numerical alphanumeric					CP6201 CP6211 CP6221 CP6231	CP6202 CP6212 CP6222 CP6232	CP6203 CP6213 CP6223 CP6233
CP66xx – 3½-inch motherboard – Arm® Cortex®-A8	without keys function keys numerical alphanumeric	CP6607	CP6609 CP6619 CP6629			CP6601 CP6611 CP6621 CP6631	CP6602 CP6612 CP6622 CP6632	CP6603 CP6613 CP6623 CP6633
CP6606, CP6600 – 3½-inch motherboard – Arm® Cortex®-A8	without keys			CP6606	CP6600			
CP67xx – 3½-inch motherboard – Intel Atom®	without keys function keys numerical alphanumeric	CP6707				CP6701 CP6711 CP6721 CP6731	CP6702 CP6712 CP6722 CP6732	CP6703 CP6713 CP6723 CP6733
CP6706, CP6700 – 3½-inch motherboard – Intel Atom®	without keys			CP6706	CP6700			
CP6706-1400, CP6700-1400 – 3½-inch motherboard – Intel Atom®	without keys, stainless steel front			CP6706- 1400	CP6700- 1400			



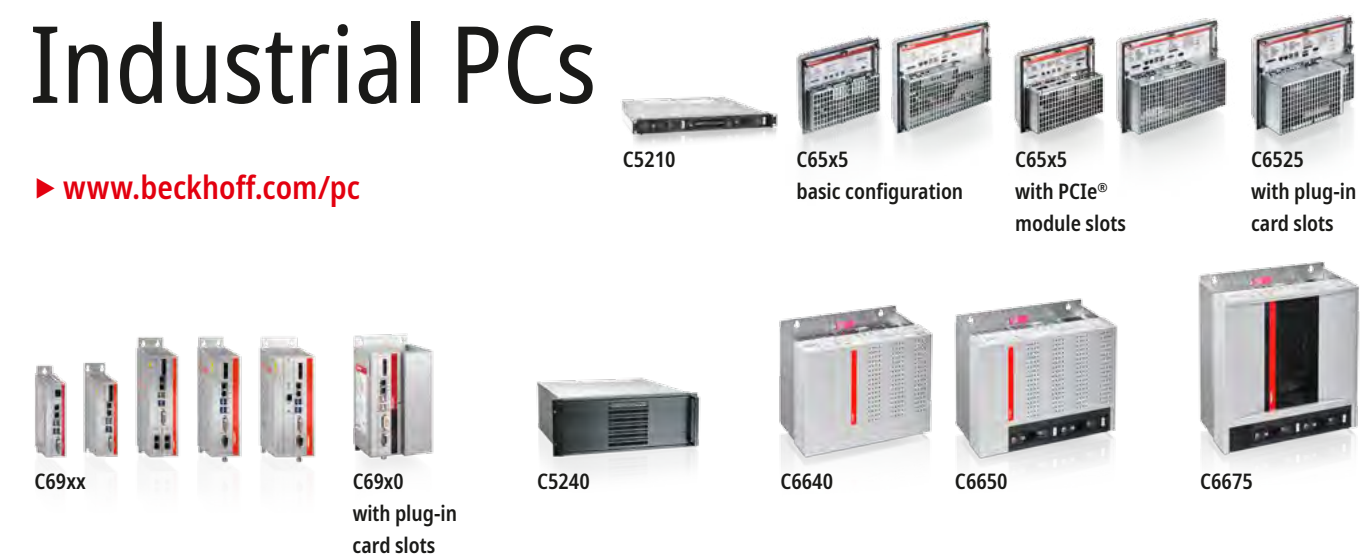
Single-touch Panel PCs, all sides IP65								
	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
	Format	4:3	4:3	5:3	17:10	4:3	4:3	5:4
CP72xx – 3½-inch motherboard – up to Intel® Core™ i3/i5/i7	without keys					CP7201	CP7202	CP7203
	function keys					CP7211	CP7212	CP7213
	numerical					CP7221	CP7222	CP7223
	alphanumeric					CP7231	CP7232	CP7233
CP77xx – CP motherboard – Intel Atom®	without keys					CP7701	CP7702	CP7703
	function keys					CP7711	CP7712	CP7713
	numerical					CP7721	CP7722	CP7723
	alphanumeric					CP7731	CP7732	CP7733

Single-touch built-in Control Panels, front side IP54/65								
	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
	Format	4:3	4:3	5:3	17:10	4:3	4:3	5:4
	Protect. rating front	IP65	IP65	IP54	IP54	IP65	IP65	IP65
CP69xx – DVI/USB Extended interface	without keys	CP6907	CP6909	CP6906	CP6900	CP6901	CP6902	CP6903
	function keys		CP6919			CP6911	CP6912	CP6913
	numerical		CP6929			CP6921	CP6922	CP6923
	alphanumeric					CP6931	CP6932/42	CP6933
CP69xx-1400 – DVI/USB Extended interface	without keys, stainless steel front			CP6906-1400	CP6900-1400			

Single-touch Control Panels, all sides IP65								
	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
	Format	4:3	4:3	5:3	17:10	4:3	4:3	5:4
CP79xx – DVI/USB Extended interface	without keys		CP7909			CP7901	CP7902	CP7903
	function keys		CP7919			CP7911	CP7912	CP7913
	numerical		CP7929			CP7921	CP7922	CP7923
	alphanumeric					CP7931	CP7932/42	CP7933
CP790x-14xx – DVI/USB Extended interface	without keys, stainless steel housing					CP7901-14xx	CP7902-14xx	CP7903-14xx

Industrial PCs

► www.beckhoff.com/pc



Control cabinet Industrial PCs with 3½-inch motherboard					
	Processor	Intel Atom®	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 6 th /7 th generation	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 8 th /9 th generation	Intel® Celeron®, Intel® Core™ i3/i5/i7 11 th generation
C5210, 19-inch slide-in Industrial PCs	1 rack unit		C5210-0030	C5210-0040	C5210-0050
C65xx	fanless		C6515-0060	C6515-0070	C6515-0080
	fanless, RAID		C6525-0060	C6525-0070	C6525-0080
C69xx, compact Industrial PCs, connectors on front	fanless	C6905-0010 C6905-0020 C6905-0030			
	fanless, 1 CFast card slot	C6915-0010			
	fanless, 2 PCIe® module slots	C6915-0020 C6925-0030 C6925-0040			
	optional plug-in card slots		C6920-0060	C6920-0070	C6920-0080
	2 PCIe® module slots, optional plug-in card slots		C6930-0060	C6930-0070	C6930-0080

Control cabinet Industrial PCs with ATX motherboard				
	Processor	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 6 th /7 th generation	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 8 th /9 th generation	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7/i9 12 th /13 th generation
C5240, 19-inch slide-in Industrial PCs	7 slots, 4 rack units	C5240-0010	C5240-0020	C5240-0030
C6640/C6650, connectors on top	7 slots	C6640-0050	C6640-0060	C6640-0070
	7 slots, 2 removable frames	C6650-0050	C6650-0060	C6650-0070
C6675, connectors on top	7 slots, 2 removable frames		C6675-0060	C6675-0070



Control cabinet Industrial PCs with compact industrial motherboard							
	Processor	Intel Atom®	Intel® Celeron®, Intel® Core™ i3/i5/i7 8 th generation, series U	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 6 th /7 th generation	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 8 th /9 th generation	Intel® Celeron®, Intel® Core™ i3/i5/i7 11 th generation	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7/i9 12 th /13 th generation
C60xx	fanless, without slots	C6015-0010 C6015-0020 C6015-0030 C6015-0040 C6025-0020	C6025-0000			C6025-0010	
	optional interfaces and/or an optional 1-second UPS	C6017-0010 C6017-0020 C6017-0030 C6017-0040	C6027-0000			C6027-0010	
	up to 2 M.2 SSDs and up to 2 PCIe® compact module slots			C6030-0060 C6032-0060	C6030-0070 C6032-0070	C6030-0080 C6032-0080	
	up to 2 M.2 SSDs up to 2 M.2 SSDs, 1 PCIe® compact module slot, MXM graphics card slot						C6040-0090 C6043-0090

IP65 Industrial PCs with compact industrial motherboard		
	Processor	Intel Atom®
C70xx, IP65	fanless	C7015-0020 C7015-0030

Control cabinet industrial server with SSI EEB motherboard		
	Processor	2 x Intel® Xeon® 5 th generation Scalable
C6670	6 slots, 2 removable frames	C6670-0020

Customization options for Panel PCs and Control Panels

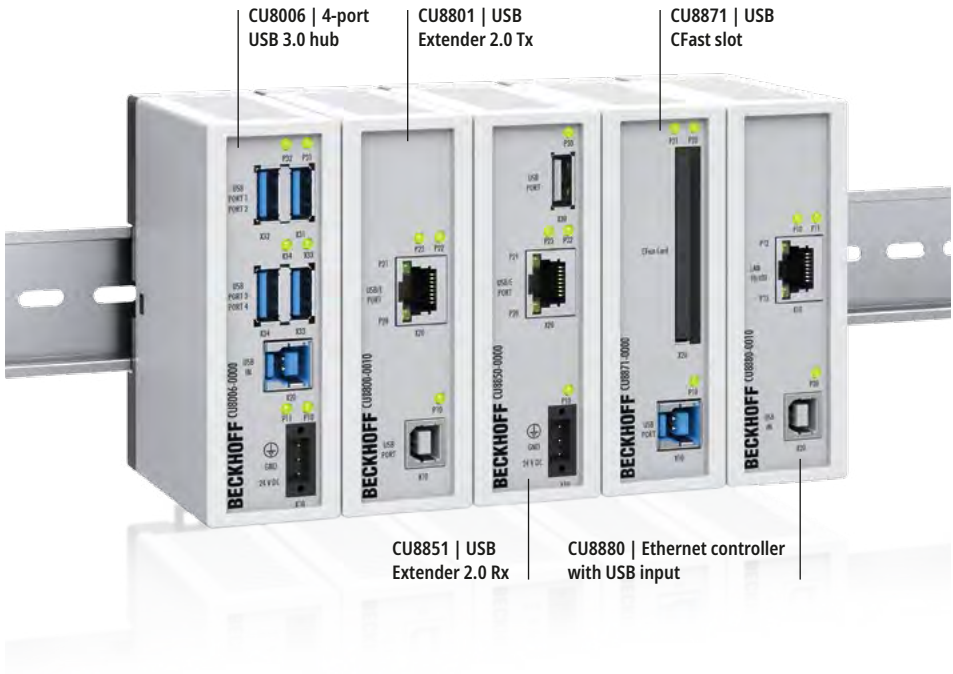
- stainless steel housings
- special membrane keyboards
- integration of electro-mechanical keyboards
- flush-mounted touch screens
- adaptation of membrane colors
- integration of customer logos



Industrial PC accessories

CU8xxx modules

Different modules enable the use of various technologies in the industrial environment. All modules are intended for DIN rail mounting. In addition, there are a variety of uninterruptible power supplies (UPS).



Embedded PC

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CX70xx



CX72xx



CX80xx



CX81xx



CX82xx



CX9020



CX9240



CX51xx



CX52xx



CX53xx



CX56xx



CX20x3



CX20x2

Embedded PC													
Basic CPU	CX70xx	CX72xx	CX80xx	CX81xx	CX82xx	CX9020	CX9240	CX51xx	CX52xx	CX53xx	CX56xx	CX20x3	CX20x2
Processor	Arm® Cortex®-M7, 480 MHz	Arm® Cortex®-A9, 720 MHz	Arm9™, 400 MHz	Arm® Cortex®-A9, 800 MHz	Arm® Cortex®-A53, 1.2 GHz	Arm® Cortex®-A8, 1 GHz	Arm® Cortex®-A53, 1.2 GHz	CX5120: Intel Atom® E3815, 1.46 GHz, CX5130: Intel Atom® E3827, 1.75 GHz, CX5140: Intel Atom® E3845, 1.91 GHz	CX5230: Intel Atom® x5-E3930, 1.3 GHz, CX5240: Intel Atom® x5-E3940, 1.6 GHz	CX5330: Intel Atom® x6214RE, 1.4 GHz, CX5340: Intel Atom® x6425RE, 1.9 GHz	CX5620: AMD Ryzen™ R1102G, 1.2 GHz, CX5630: AMD Ryzen™ R1505G, 2.0 GHz	CX2033: AMD Ryzen™ V1202B 2.3 GHz, CX2043: AMD Ryzen™ V1807B 3.35 GHz	CX2042: Intel® Xeon® D-1527 2.2 GHz, CX2062: Intel® Xeon® D-1548 2.0 GHz, CX2072: Intel® Xeon® D-1567 2.1 GHz
Number of cores	1	1	1	1	2	1	4	1, 2, 4	2, 4	2, 4	2	2, 4	4, 8, 12
Flash memory	slot for microSD card, 512 MB included (optionally expandable)	slot for microSD card, 512 MB included (optionally expandable)	slot for microSD card, 512 MB included (optionally expandable)	slot for microSD card, 512 MB included (optionally expandable)	slot for microSD card, card not included (requires a microSD card with a minimum capacity of 16 GB)	2 x slot for microSD card, 512 MB included (optionally expandable)	slot for microSD card, card not included (requires a microSD card with a minimum capacity of 16 GB)	slot for CFast card and microSD card, cards not included	slot for CFast card and microSD card, cards not included	slot for CFast card and microSD card, cards not included	slot for M.2 SSD (SATA) and microSD card (storage media not included)	slot for CFast card, card not included	slot for CFast card, card not included
Main memory	32 MB SDR (not expandable)	512 MB DDR3 RAM (not expandable)	64 MB DDR2 RAM (not expandable)	512 MB DDR3 RAM (not expandable)	1 GB LPDDR4 RAM (not expandable)	1 GB DDR3 RAM (not expandable)	2 GB LPDDR4 RAM (not expandable)	CX5120: 2 GB DDR3 RAM (not expandable), CX5130: 4 GB DDR3 RAM (not expandable), CX5140: 4 GB DDR3 RAM (not expandable)	CX5230: 4 GB DDR4 RAM (internal, not expandable), CX5230: 8 GB DDR4 RAM (internal, not expandable)	CX5330: 4 GB LPDDR4 RAM (expandable ex factory to 8 GB), CX5340: 8 GB LPDDR4 RAM (expandable ex factory to 16 GB)	CX5620: 4 GB DDR4 RAM, CX5630: 8 GB DDR4 RAM	CX2033: 8 GB DDR4 RAM (expandable ex factory to 16 GB), CX2043: 8 GB DDR4 RAM (expandable ex factory to 32 GB)	8 GB DDR4 RAM (expandable ex factory to 64 GB)
Interfaces	1 x RJ45 10/100 Mbit/s, 1 x USB, 1 x bus interface	1 x RJ45 10/100/1000 Mbit/s, 1 x bus interface	1 x RJ45 10/100 Mbit/s, 1 x USB device (behind the front flap), 1 x bus interface	1 x RJ45 10/100 Mbit/s, 1 x bus interface	1 x RJ45 10/100/1000 Mbit/s, 1 x USB 3.0, 1 x bus interface	2 x RJ45 10/100 Mbit/s (internal switch), 1 x DVI-D, 4 x USB 2.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DisplayPort, 4 x USB 3.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-I, 4 x USB 2.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-D, 4 x USB 3.1, 1 x optional interface, 1 x extension module	2 x RJ45 10/100/1000/2500 Mbit/s, 1 x DisplayPort, 4 x USB 3.1, 1 x optional interface, 1 x extension module	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-D, 4 x USB 3.0, 1 x optional interface, 1 x extension module	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-D, 4 x USB 3.2 Gen. 2, 1 x optional interface, 4 x extension module	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-I, 4 x USB 3.0, 1 x optional interface, 4 x extension module
TwinCAT support	TwinCAT 3	TwinCAT 3	TwinCAT 2	TwinCAT 3	TwinCAT 3	TwinCAT 3, TwinCAT 2	TwinCAT 3	TwinCAT 3, TwinCAT 2	TwinCAT 3	TwinCAT 3	TwinCAT 3, TwinCAT 2	TwinCAT 3, TwinCAT 2	TwinCAT 3
Operating system	TwinCAT/RTOS	TwinCAT/RTOS	Windows CE	Windows Embedded Compact 7	Beckhoff RT Linux®	Windows Embedded Compact 7	Beckhoff RT Linux®	Windows Embedded Compact 7; Embedded Standard 7; Windows 10 IoT Enterprise 2016, 2019, 2021; TwinCAT/BSD	Windows 10 IoT Enterprise 2019, 2021; TwinCAT/BSD, Beckhoff RT Linux®	Windows 10 IoT Enterprise 2021, Windows 11, TwinCAT/BSD, Beckhoff RT Linux®	Windows 10 IoT Enterprise 2019, 2021; Windows 11; TwinCAT/BSD, Beckhoff RT Linux®	Windows 10 IoT Enterprise 2019, 2021; Windows 11; TwinCAT/BSD, Beckhoff RT Linux®	Windows 10 IoT Enterprise 2016, 2019, 2021; Windows 11; TwinCAT/BSD
1-second UPS	–	integrated (1 MB on microSD card)	integrated (1 MB on microSD card)	integrated (1 MB on microSD card)	integrated (1 MB on microSD card)	as an option: CX9020-U900	integrated (1 MB on microSD card)	integrated (1 MB on CFast card)	integrated (1 MB on CFast card)	integrated (1 MB on CFast card)	integrated (1 MB on M.2 SSD)	CX2100-0914	–
NOVRAM	4 kB	–	–	–	–	128 kB	–	–	–	–	–	128 kB	128 kB

The I/O Company

Beckhoff supplies a complete range of fieldbus components for all common I/O and bus systems. With Bus Terminals offering IP20 protection and Fieldbus Box modules in IP67, a comprehensive range of devices is available for a wide variety of signal types and fieldbus systems. In addition to components for conventional bus systems, Beckhoff offers an integrated product range optimized for EtherCAT. Invented by Beckhoff, this real-time Ethernet solution for industrial automation has global acceptance and is characterized by outstanding performance and simple handling. The result is high-precision machine and plant control and significantly increased production efficiency.

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► www.beckhoff.com/ethercat

EtherCAT plug-in modules 56

- very compact EtherCAT I/O system in IP20 for plug-in into a circuit board (signal distribution board)
- optimized for high-volume production
- application-specific connector interface
- Use of cable harnesses avoids wiring errors.

► www.beckhoff.com/ethercat-plug-in-modules

Bus Terminals 62

- open, fieldbus-neutral IP20 I/O system
- more than 400 different Bus Terminals
- support for more than 20 fieldbus systems
- gateways for subordinate bus systems
- system-integrated safety I/O terminals available

► www.beckhoff.com/busterminal

Fieldbus Box 70

- open, fieldbus-neutral IP67 I/O system
- 8 fieldbus systems, 24 signal types
- compact and robust
- can be mounted directly on machines, outside of control cabinets and terminal boxes while reducing machine footprint
- IO-Link box modules for inexpensive point-to-point connections

► www.beckhoff.com/fieldbusbox

Infrastructure Components 73

- PC cards for all common fieldbus systems
- Industrial Ethernet switches
- EtherCAT junctions and media converters in IP20 and IP67 ratings
- EtherCAT G/G10 components

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Measuring transformers and power supplies 74

- for new installations and for retrofitting
- different designs and power classes
- high efficiency
- high reliability
- wide range input

► www.beckhoff.com/sct
► www.beckhoff.com/ps

EtherCAT Terminals 30

- IP20 EtherCAT I/O system
- real-time Ethernet performance retained into each terminal
- standard digital and analog signals
- complex automation functions directly in the terminal system
- highly precise measurement technology
- condition monitoring
- drive technology, also in a robust metal housing
- process technology
- electronic overcurrent protection
- gateways for subordinate fieldbus systems
- TwinSAFE PLC and safety I/Os

► www.beckhoff.com/ethercat-terminal



EtherCAT Box 46

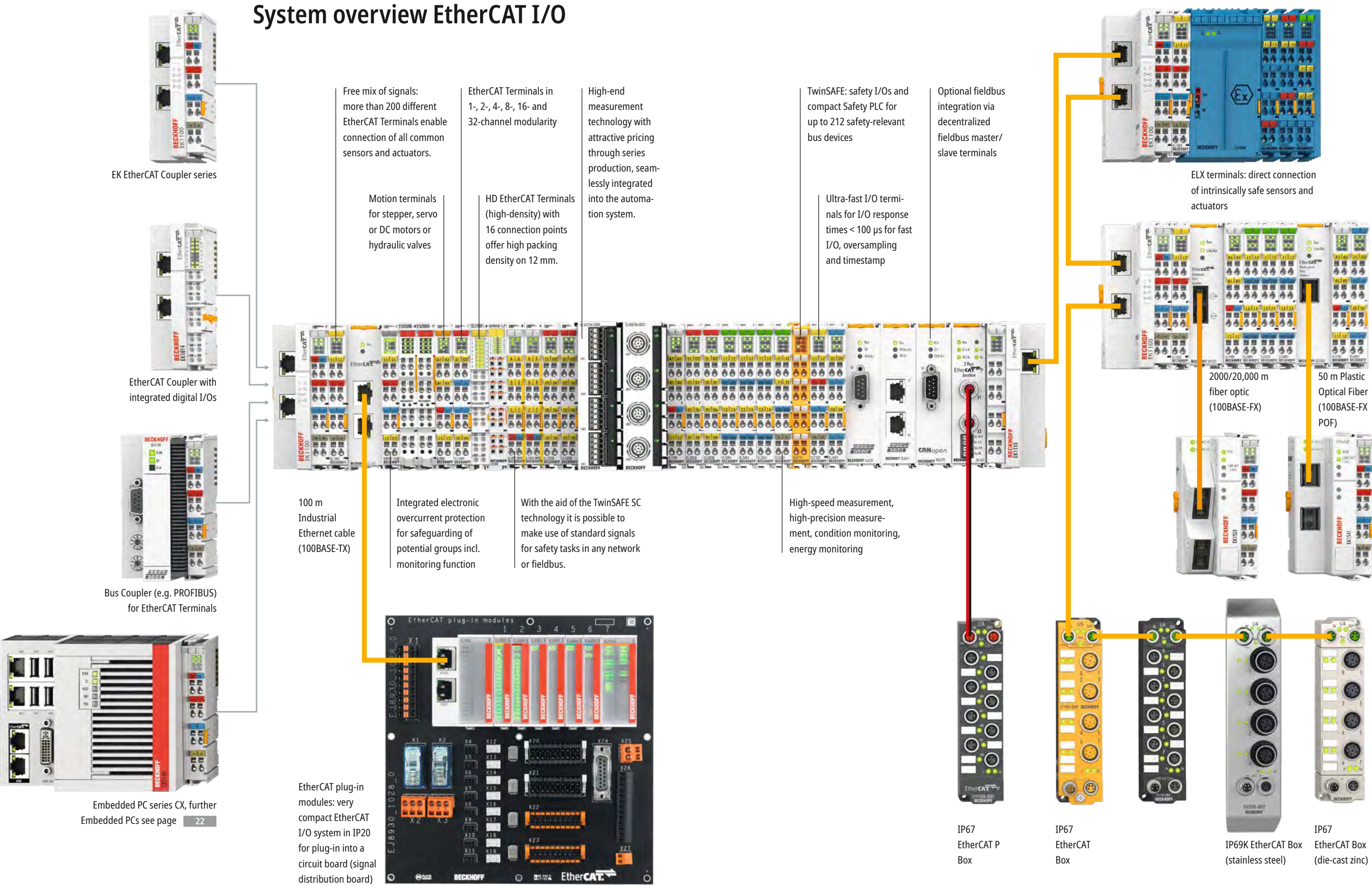
- IP67 EtherCAT I/O system
- high performance for harsh environments
- compact and robust
- can be mounted directly on machines, outside of control cabinets and terminal boxes
- integrated sensor/actuator supply directly via EtherCAT P

► www.beckhoff.com/ethercat-box



- comprehensive, modular I/O system for all signal types and fieldbus systems
- universal product range optimized for EtherCAT
- high investment security: mature I/O technology based on more than 25 years of success in the field
- Beckhoff is the I/O pioneer, developing the Bus Terminal concept and EtherCAT.

System overview EtherCAT I/O



Product overview fieldbus systems

► www.beckhoff.com/fieldbus-systems

Fieldbus	EtherCAT Terminals	EtherCAT Box	EtherCAT plug-in modules	Bus Terminals		Fieldbus Box			Fieldbus Modules	Infrastructure components	Embedded PC	Drive Technology
	Couplers/gateways	Modules		Bus Couplers/ master terminals	PLC (IEC 61131-3)	Compact Box	Coupler Box	IO-Link box	For thermo- couples/mV	Interfaces	Master/slave	Servo drives
EtherCAT➔	EK1xxx, EKM1xxx	EPxxxx	EJ1xxx	BK1120			IL230x-B110		FM33xx-B110	FC90xx, FC11xx	CXxxxx	AX8000
	EL6695 bridge	ERxxxx		BK1150						CUxxxx	CXxxxx-M112	AX5000
		EQxxxx		BK1250						EP9xxx		AMI8100
EtherCAT➔P	EK13xx	EPPxxxx										
		EP1312										
LIGHTBUS	EL6720 master			BK2020								
PROFINET	EK3100			BK3xx0	BC3150	IPxxxx-B31x	IL230x-B31x		FM33xx-B310	FC31xx	CXxxxx	
	EL673x master/slave				BX3100						CX2500-M/B310	
INTERBUS	EL6740-0010 slave			BK40x0								
CANopen	EL675x master/slave			BK51xx	BC5150	IPxxxx-B51x	IL230x-B51x			FC51xx	CXxxxx	
					BX5100						CX2500-M/B510	
DeviceNet	EL675x master/slave			BK52x0	BX5200	IPxxxx-B52x	IL230x-B52x			FC52xx		
CC-Link	EL6711-0010 slave			BK7150								
Modbus	EK90x0			BK7350							CXxxxx	
sercos				BK75x0						FC75xx	CXxxxx	
RS485	EL1262-0010	EP600x	EJ2522	BK8000	BC8050						CXxxxx	
	EL6021, EL6022	EPP600x	EJ5112	KL6021	BX8000							
	ED6011, ED6012		EJ6002	KL6041								
RS232	EL6001, EL6002	EP600x	EJ6002	BK8100	BC8150						CXxxxx	
	ED6011, ED6012	EPP600x		KL6001	BX8000							
				KL6031								
Ethernet TCP/IP				BK9xx0	BC9xxx		IL230x-B90x			FC9xxx	CXxxxx	
	EL6601, EL6614 switch port	EP6601 switch port			BX9000					CU2xxx, CU2508 Ethernet Switch		
PROFINET	EK93x0	EP9300		BK9xx3			IL230x-B903			CU2508	CXxxxx	
	EL663x RT controller/device											
	EL663x IRT controller											
EtherNet/IP	EK95x0			BK9xx5			IL230x-B905			CU2508	CXxxxx	
	EL665x scanner/adapter											
AS-Interface	EL6201			KL62x1								
IO-Link	EL6224, ED6224 master	EP622x, EPP622x master	EJ6224 master	KL6224 master				EPIxxxx, ERIxxxx devices				
KNX/EIB				KL6301								
MP-Bus				KL6771								
M-Bus	ED6781			KL6781								
DALI/DSI	EL6821 master			KL6811								
DALI-2				KL6821								
IEEE 1588	EL6688											
DMX	EL6851											
EnOcean				KL658x								
SMI				KL6841								
BACnet	EL6861										CXxxxx	

EtherCAT Terminals

► www.beckhoff.com/ethercat-terminal



EC1xxx EtherCAT Couplers	
	EtherCAT
EtherCAT Couplers E-bus	EC1100 2 x RJ45, push-in
Extensions	EC1110 extension end terminal, push-in

EK1xxx, BK1xx0 EtherCAT Couplers							
	EtherCAT				EtherCAT P	EtherCAT G	Ethernet/TSN
EtherCAT Couplers E-bus	EK1100 2 x RJ45	EK1101 ID switch	EK1101-0010 ID switch, Extended Distance	EK1101-0080 ID switch, Fast Hot Connect	EK1300 EtherCAT P	EK1400 EtherCAT G	EK1000 Ethernet/TSN
	EK1100-0008 M8 connection	EK1101-0008 ID switch, M8 connection		EKM1101 ID switch and diagnostics			
	EK1501 ID switch, multi-mode fiber optic	EK1501-0010 ID switch, single-mode fiber optic	EK1501-0100 ID switch, multi-mode fiber optic to RJ45	EK1541 ID switch, POF			
EtherCAT Couplers E-bus with integrated digital I/Os	EK1814 4 inputs + 4 outputs	EK1818 8 inputs + 4 outputs	EK1828 4 inputs + 8 outputs	EK1828-0010 8 outputs			
	EK1914 4 standard inputs, 4 standard outputs, 2 safe inputs, 2 safe outputs	EK1960 TwinSAFE Logic, 20 safe inputs, 24 safe outputs					
EtherCAT Couplers K-bus	BK1120 Bus Coupler (Economy plus)	BK1150 Bus Coupler (Compact)	BK1250 E-bus to K-bus interface				

EK1xxx, BK1xx0 EtherCAT Couplers							
	EtherCAT				EtherCAT P	EtherCAT G	Ethernet/TSN
Extensions	EK1110 extension end terminal	EK1110-0008 extension end terminal, M8	EK1110-0043 EtherCAT EJ coupler, CX and EL terminal connection	EK1110-0044 EtherCAT EJ coupler, CX and EL terminal connection, EtherCAT junction	EK1310 EtherCAT P extension with feed-in		
Junctions	EK1122 2-port junction	EK1122-0008 2-port junction, M8	EK1121-0010 1-port junction, Extended Distance	EK1122-0080 2-port junction, Fast Hot Connect	EK1322 EtherCAT P junction with feed-in		
	EK1521 multi-mode fiber-optic junction	EK1521-0010 single-mode fiber-optic junction		EK1561 POF junction			

EKxxxx Bus Couplers		
Fieldbus	Standard	
IoT	EK9160 IoT (MQTT, OPC UA)	
EtherNet/IP	EK9500 100 Mbit/s	EK9520 100/1000 Mbit/s
Modbus	EK9000 100 Mbit/s	EK9020 100/1000 Mbit/s
PROFINET	EK3100 12 Mbaud	
PROFINET	EK9300 100 Mbit/s	EK9320 100/1000 Mbit/s

Embedded PCs with E-bus interface see page 22 , Infrastructure Components see page 73

ED1xxx EtherCAT Terminals, digital input					
Signal	8-channel	16-channel	32-channel		
24 V DC, filter 3 ms	ED1008 push-in	ED1809 push-in	ED1829 positive/ground switching, push-in		
		ED1889 ground switching, push-in	ED1859 8 inputs, 8 outputs, I _{max} = 0.5 A, push-in		
24 V DC, filter adjustable		ED1839 push-in	ED1837 push-in	ED1897 ground switching, push-in	
24 V DC, filter 10 µs		ED1819 push-in			

ED2xxx EtherCAT Terminals, digital output					
Signal	2-channel	4-channel	8-channel	16-channel	32-channel
24 V DC, I _{max} = 0.5 A			ED2008 push-in	ED2809 push-in	ED2807 push-in
				ED2889 ground switching, push-in	ED2887 ground switching, push-in
				ED1859 8 inputs, 8 outputs, I _{max} = 0.5 A, push-in	
24 V DC, I _{max} = 2.0 A	ED2032 with channel diagnostics, push-in	ED2034 with channel diagnostics, push-in	ED2828 push-in		
			ED2838 with channel diagnostics, push-in		
PWM		ED2504 5...24 V DC, 1 A, push-in			

ED3xxx EtherCAT Terminals, analog input				
Signal	1-channel	2-/3-channel	4-channel	8-channel
±10 V/±20 mA		ED3072 16 bit, single-ended, 2 ksps, push-in	ED3074 16 bit, single-ended, 2 ksps, push-in	ED3078 16 bit, single-ended, 2 ksps, push-in
		ED3172 16 bit, 10 ksps, push-in	ED3174 16 bit, 10 ksps, push-in	
Multi-function			ED3274 RTD/TC, push-in	
Measurement bridge, strain gauge	ED3361 24 bit, sensor supply 5/10 V DC, 1 x DI, 1 x DO, push-in	ED3362 24 bit, sensor supply 5/10 V DC, 1 x DI, 1 x DO, push-in		
	ED3361-0100 24 bit, sensor supply 10 V DC, push-in	ED3362-0100 24 bit, sensor supply 10 V DC, push-in		

ED4xxx EtherCAT Terminals, analog output			
Signal	2-channel	4-channel	8-channel
±10 V/±20 mA	ED4072 16 bit, 2 ksps, push-in	ED4074 16 bit, 2 ksps, push-in	ED4078 16 bit, 2 ksps, push-in
	ED4172 16 bit, 10 ksps, push-in	ED4174 16 bit, 10 ksps, push-in	

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.

ED5xxx EtherCAT Terminals, position measurement	
Signal	2-channel
Absolute position measurement	ED5002 SSI, push-in
Incremental position measurement	ED5112 incremental, 5 V DC (DIFF RS422, TTL, open collector), 5 MHz, push-in

ED6xxx EtherCAT Terminals, communication			
Signal	1-channel	2-channel	4-channel
Serial	ED6011 RS232/RS422/RS485, push-in	ED6012 RS232/RS422/RS485, push-in	
Master/slave			ED6224 IO-Link, master, push-in
Sub systems	ED6781 M-Bus, master, push-in		

ED7xxx EtherCAT Terminals, compact drive technology	
Motor type	3...5 A
Servomotor	ED7211-0010 48 V DC, 4.5 A, OCT, push-in
Stepper motor	ED7062 48 V DC, 3 A, push-in

ED8xxx EtherCAT Terminals, multi-functional	
Multi- functional	ED8601-8411 8 x digital input, 1 x counter, 4 x digital output, 2 x PWM, 1 x analog input, 1 x analog output, 1 x encoder, push-in

ED9xxx EtherCAT Terminals, system	
Signal	System
Potential distribution	ED9184 push-in
Potential supply, 24 V DC	ED9100 push-in
Power supply	ED9410 2 A, with diagnostics, push-in

EL1xxx EtherCAT Terminals, digital input						
Signal	2-channel	4-channel		8-channel	16-channel	32-channel
5 V DC	EL1252-0050	EL1124				
	T_{ON}/T_{OFF} 1 µs, timestamp	filter 0.05 µs				
	EL1262-0010					
	T_{ON}/T_{OFF} 0.1 µs, oversampling					
	EL1262-0050					
	T_{ON}/T_{OFF} 1 µs, oversampling					
10 V DC	EL1252-0060					
	T_{ON}/T_{OFF} 1 µs, timestamp					
12 V DC		EL1144				
		filter 10 µs				
24 V DC, filter 3 ms	EL1002	EL1004	EL1004-0020	EL1008	EL1809	
	type 3	type 3	functional isolation 2500 V	type 3, 1-wire	type 3	
		EL1104	EL1804	EL1808	EL1409	EL1429
		type 3, with sensor supply	type 3, 8 x 24 V, 4 x 0 V	type 3, 8 x 24 V DC, 2-wire	1-wire	positive/ground switching
		EL1084	EL1024	EL1088	EL1852	EL1859
		ground switching	type 2	ground switching	type 3, 8 inputs, 8 outputs, I_{max} = 0.5 A, flat-ribbon cable	type 3, 8 inputs, 8 outputs, I_{max} = 0.5 A
					EL1862	EL1862-0010
					type 3, flat-ribbon cable	flat-ribbon cable, ground switching
					EL1489	EL1889
					ground switching	ground switching
24 V DC, filter adjustable						EL1417
						1-wire
24 V DC, filter 10 µs	EL1012	EL1014	EL1034	EL1018	EL1819	
	type 3	type 3	type 1, potential-free inputs	type 3	type 3	
	EL1252-0010	EL1114	EL1814		EL1872	EL1872-0010
	type 3, timestamp	type 3, with sensor supply	type 3, 8 x 24 V, 4 x 0 V, 3-wire		type 3, flat-ribbon cable	flat-ribbon cable, ground switching
			EL1094	EL1098	EL1899	
			ground switching	ground switching	ground switching	
24 V DC, XFC: T _{ON} /T _{OFF} 1 µs	EL1202					
	type 3					
	EL1252	EL1254		EL1258	EL1259	
	type 3, timestamp	type 3, timestamp		multi-timestamping	8 inputs, 8 outputs, multi-timestamping, I_{max} = 0.5 A	
	EL1262	EL1264		EL1258-0010		
	type 3, oversampling	type 3, oversampling		multi-timestamping, ground switching		
24 V DC, counter	EL1502					
	type 1, 100 kHz, 32 bit					
	EL1512					
	type 1, 1 kHz, 32 bit					

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.

EL1xxx EtherCAT Terminals, digital input						
Signal	2-channel	4-channel		8-channel	16-channel	32-channel
24 V DC, safe input		EL1904	EL2911	EL1918	EL1957	
		TwinSAFE, 4 safe inputs	TwinSAFE Logic, 4 safe inputs, 1 safe output	TwinSAFE Logic, 8 safe inputs	TwinSAFE Logic, 8 safe inputs, 4 safe outputs	
48 V DC		EL1134				
		type 1				
120 V AC/DC	EL1712					
	power contacts					
120 V DC	EL1712-0020					
	power contacts					
120... 230 V AC	EL1702					
	power contacts					
	EL1722					
	no power contacts					
220 V DC	EL1702-0020					
	power contacts					
Thermistor	EL1382					
NAMUR	EL1052	EL1054				
Ex i, NAMUR	ELX1052	ELX1054		ELX1058		

EL2xxx EtherCAT Terminals, digital output						
Signal	1-channel	2-channel	4-channel	8-channel	16-channel	32-channel
5 V DC			EL2124			
			I_{max} = ±20 mA			
12 V DC			EL2024-0010			
			I_{max} = 2.0 A			
24 V DC, I _{max} = 0.5 A		EL2002	EL2004	EL2008	EL2809	EM2042
		4-wire	2-wire	1-wire	I_{max} = 0.5 A	D-sub connection
			EL2014	EL2068	EL2409	EL2407
			with diagnostics	with channel diagnostics	1-wire	1-wire
				EL2878-0005	EL2872	EL2872-0010
				flat-ribbon cable, with diagnostics	flat-ribbon cable	flat-ribbon cable, ground switching
				EL2808	EL1852	EL1859
				8 x 0 V	type 3, 8 inputs, 8 outputs, I_{max} = 0.5 A, flat-ribbon cable	type 3, 8 inputs, 8 outputs, I_{max} = 0.5 A
					EL2819	EL2869
					with diagnostics	with channel diagnostics
			EL2084	EL2088	EL2889	EL2489
			ground switching	ground switching	ground switching	ground switching

EL2xxx EtherCAT Terminals, digital output						
Signal	1-channel	2-channel	4-channel	8-channel	16-channel	32-channel
24 V DC, I _{max} = 2.0 A		EL2022 4-wire	EL2024 2-wire	EL2828		
		EL2032 with diagnostics	EL2034 with diagnostics	EL2838 with channel diagnostics		
			EL2044 with extended diagnostics			
24 V DC, I _{max} = 4.0 A/8.0 A		EL2042 2 x 4.0 A/1 x 8.0 A				
24 V DC, XFC: T _{ON} /T _{OFF} 1 µs		EL2202 push-pull output		EL2258 multi-timestamping		
		EL2202-0100 push-pull outputs, DC preset	EL2212 overexcitation, multi-timestamping		EL1259 8 inputs, 8 outputs, multi-timestamping, I _{max} = 0.5 A	
		EL2252 timestamp	EL2262 oversampling			
Ex i, 24 V DC		ELX2002 45 mA	ELX2792 I _{max} = 0.5 A AC/1 A DC, change-over contact	ELX2008 30 mA		
24 V DC, safe output	EL2911 TwinSAFE Logic, 4 safe inputs, 1 safe output	EL2912 TwinSAFE Logic, 2 safe outputs	EL2904 TwinSAFE, 4 safe outputs			
30 V AC/ 48 V DC solid- state relay, I _{max} = 2.0 A			EL2784	EL2788		
			EL2794 potential-free	EL2798 potential-free		
Relay (up to 250 V AC)		EL2602 I _{max} = 5.0 A, make contact, power contacts	EL2622 I _{max} = 5.0 A, make contact, no power contacts	EL2624 I _{max} = 2.0 A, make contact		
		EL2602-0010 I _{max} = 5.0 A, make contact, power contacts, contact- protecting switching	EL2622-0010 I _{max} = 5.0 A, make contact, no power contacts, contact- protecting switching	EL2634 I _{max} = 4.0 A, make contact, 250 V AC/30 V DC, no power contacts		
		EL2612 I _{max} = 2.0 A, change-over, no power contacts	EL2642 I _{max} = 1.0 A, change-over, no power contacts, reed relays			
		EL2652 I _{max} = 1.0 A, change-over, no power contacts				
Triac (12...230 V AC)		EL2712 I _{max} = 0.5 A, power contacts	EL2722 I _{max} = 1.0 A, mutually locked outputs			

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.

EL2xxx EtherCAT Terminals, digital output						
Signal	1-channel	2-channel	4-channel	8-channel	16-channel	32-channel
PWM		EL2502 push-pull output, separate frequency can be set for each channel	EL2502-0005 plastic optical fiber, separate frequency can be set for each channel			
		EL2502-0010 push-pull output, separate frequency can be set for each channel, timestamp				
		EL2535 24 V DC, I _{max} = ±50 mA, ±1 A, ±2 A	EL2535-0002 24 V DC, I _{max} = ±2 A			
		EL2535-0005 24 V DC, I _{max} = 0...5 A	EL2535-0050 24 V DC, I _{max} = ±50 mA			
Frequency output		EL2535-0100 24 V DC, I _{max} = ±100 mA	EL2535-0103 48 V DC, I _{max} = 3.5 A			
	EL2521 incr. enc. simulation, 1-channel AB, 0...500 kHz, RS422	EL2522 incr. enc. simulation, 2-channel AB, 1-channel ABC, 0...4 MHz				
	EL2521-0024 incr. enc. simulation, RS422, 24 V DC, externally powered					
	EL2521-0025 incr. enc. simulation, RS422, 24 V DC, externally powered, ground switching					
LED control		EL2521-0124 incr. enc. simulation, RS422/24 V DC, capture/compare in-/output				
	EL2595 48 V DC, 300...700 mA, current control		EL2564 5...48 V DC, 4 A, RGBW, common anode			
	EL2596 24 V DC, 3 A, pulse > 25 µs, current control		EL2564-0010 8...48 V DC, 3 A, RGBW, common cathode			
	EL2596-0010 48 V DC, 3 A, pulse > 25 µs, current control		EL2574 pixel LED, 2048 individually addressable LEDs			
Multiplexer		ELM2742-0000 2 x multiplexer, 1 x 4 solid-state relays	ELM2744-0000 4 x multiplexer, 1 x 4 solid-state relays			
		ELM2642-0000 2 x multiplexer, 1 x 4 reed relays	ELM2644-0000 4 x multiplexer, 1 x 4 reed relays			

EL3xxx EtherCAT Terminals, analog input							
Signal	1-channel		2-/3-channel		4-channel		5-/6-/8-channel
0...10 V, standard signal	EL3061 12 bit	EL3161 16 bit	EL3062 12 bit	EL3162 16 bit	EL3064 12 bit	EL3164 16 bit	EL3068 12 bit
±10 V	EL3001 single-ended, 12 bit		EL3002 single-ended, 12 bit		EL3004 single-ended, 12 bit		EL3008 single-ended, 12 bit
	EL3101 differential input, 16 bit		EL3102 differential input, 16 bit	EL3602 differential input, 24 bit	EL3104 differential input, 16 bit		
			EL3702 differential input, 16 bit, oversampling				
±75 mV			EL3602-0010 differential input, 24 bit				
±100 mV			EL3702-0015 differential input, 16 bit, oversampling				
±200 mV			EL3602-0002 differential input, 24 bit				
0...30 V			EL3062-0030 12 bit				
±30 V			ELM3002-0000 24 bit, 20 ksps, push-in		ELM3004-0000 24 bit, 10 ksps, push-in		
±60 V...±1200 V ±60 mV...±5 V			ELM3002-0205 24 bit, 50 ksps, galv. isolated, 4 mm, 2 x ±1200...60 mV	ELM3002-0305 24 bit, 50 ksps, galv. isolated, 4 mm, 2 x ±5 V...60 mV			
			ELM3002-0405 24 bit, 50 ksps, galv. isolated, 4 mm, 1 x ±1200 V...60 mV, 1 x 5 V...60 mV				
0...20 mA, standard signal	EL3041 single-ended, 12 bit	EL3141 single-ended, 16 bit	EL3042 single-ended, 12 bit	EL3142 single-ended, 16 bit	EL3044 single-ended, 12 bit	EL3144 single-ended, 16 bit	EL3048 single-ended, 12 bit
	EL3011 differential input, 12 bit	EL3111 differential input, 16 bit	EL3012 differential input, 12 bit	EL3142-0010 single-ended, ±10 mA, 16 bit	EL3014 differential input, 12 bit	EL3114 differential input, 16 bit	
			EL3112 differential input, 16 bit	EL3612 differential input, 24 bit			
			EL3742 differential input, 16 bit, oversampling	EL3182 single-ended, 16 bit, HART	EL3184 single-ended, 16 bit, HART		
4...20 mA, standard signal	EL3051 single-ended, 12 bit	EL3151 single-ended, 16 bit	EL3052 single-ended, 12 bit	EL3152 single-ended, 16 bit	EL3054 single-ended, 12 bit	EL3154 single-ended, 16 bit	EL3058 single-ended, 12 bit
	EL3021 differential input, 12 bit	EL3121 differential input, 16 bit	EL3022 differential input, 12 bit	EL3122 differential input, 16 bit	EL3024 differential input, 12 bit	EL3124 differential input, 16 bit	
		EL3621-0020 differential input, 24 bit				EL3124-0090 16 bit, TwinSAFE SC	

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.

EL3xxx EtherCAT Terminals, analog input							
Signal	1-channel		2-/3-channel		4-channel		5-/6-/8-channel
±20 mA			EL3112-0011 differential input, 16 bit	ELM3102-0000 24 bit, 20 ksps, NAMUR NE43, push-in	ELM3104-0000 24 bit, 10 ksps, NAMUR NE43, push-in		
±10 V/±20 mA			EL3072 12 bit, NAMUR NE43		EL3074 12 bit, NAMUR NE43		EL3078 16 bit, NAMUR NE43
			EL3172 16 bit, NAMUR NE43		EL3174 16 bit, NAMUR NE43	EL3174-0002 16 bit, electrically isolated, NAMUR NE43	
					EL3174-0090 16 bit, NAMUR NE43, TwinSAFE SC		ELM3146-0000 24 bit, 1 ksps, push-in
			ELM3142-0000 24 bit, 1 ksps, push-in		ELM3144-0000 24 bit, 1 ksps, push-in		ELM3148-0000 24 bit, 1 ksps, push-in
±3 V/±20 mA					EL3174-0032 16 bit, electrically isolated, NAMUR NE43, ±3 V		
±3 V/±5 V							EL3008-0003 ±3 V, 16 bit, cascaded channels
							EL3008-0005 ±5 V, 16 bit, cascaded channels
±60 V					EL3174-0042 16 bit, electrically isolated, NAMUR NE43		
±60 V/±20 mA				ELM3102-0100 24 bit, 20 ksps, push-in, galv. isolated			
Multi-function	EL3751 24 bit, 10 ksps	EL3751-0004 24 bit, 10 ksps	ELM3702-0000 24 bit, 10 ksps, push-in	ELM3702-0101 24 bit, 10 ksps, galvani- cally isolated, LEMO	ELM3704-0000 24 bit, 10 ksps, push-in	ELM3704-0001 24 bit, 10 ksps, LEMO	
Temperature measurement, resistance thermometer RTD	EL3201 16 bit	EL3201-0010 16 bit, high-precision	EL3202 16 bit	EL3202-0010 16 bit, high-precision	EL3204 2-wire, 16 bit		EL3208 16 bit
					EL3204-0162 2-wire, 16 bit, 2 x RTD, 2 x ±10 V	EL3204-0200 16 bit, universal input for RTD	EL3208-0010 Pt1000, Ni1000, NTC 1.8...100 k, potentiom. 1, 5, 10 kΩ
					EL3214 3-wire, 16 bit	EL3214-0090 16 bit, TwinSAFE SC	EL3218 3-wire, 16 bit
						ELM3244-0000 <u>i</u> 24 bit, high-precision, 1 ksps, push-in	ELM3246-0000 <u>i</u> 24 bit, high-precision, 1 ksps, push-in
Temperature measurement, thermocouple, mV	EL3311 16 bit		EL3312 16 bit		EL3314 16 bit	EL3314-0090 16 bit, TwinSAFE SC	EL3318 16 bit
					EL3314-0002 24 bit, electrically isolated	EL3314-0092 24 bit, galvanically isolated, TwinSAFE SC	
					EL3314-0010 24 bit	ELM3344-0000 24 bit, 1 ksps, push-in	ELM3348-0000 24 bit, 1 ksps, push-in
					ELM3704-1001 24 bit, 10 ksps, push-in, TC adjustment	ELM3344-0003 24 bit, 1 ksps, push-in, Mini-TC universal	ELM3348-0003 24 bit, 1 ksps, push-in, Mini-TC universal

EL3xxx EtherCAT Terminals, analog input					
Signal	1-channel		2-/3-channel	4-channel	5-/6-/8-channel
Measurement bridge, strain gauge	EL3351	EL3356	ELM3502-0000	ELM3504-0000	
	16 bit	self-calibration	24 bit, 20 ksps, push-in	24 bit, 10 ksps, push-in	
	EL3356-0010	EL3356-0090	ELM3542-0000 ⁱ	ELM3544-0000 ⁱ	
	24 bit, 10 ksps	TwinSAFE SC	24 bit, 1 ksps, push-in	24 bit, 1 ksps, push-in	
Measurement technology	EL3681		EL3692		EL3255
	digital multimeter		resistance measurement,		potentiometer
	terminal, voltage/		100 mΩ...10 MΩ		measurement,
	current, 18 bit				5-channel
Acceleration measurement, position, vibration, condition monitoring, IEPE			EL3632	ELM3602-0000	ELM3604-0000
			16 bit, 50 ksps	24 bit, 50 ksps, push-in	24 bit, 20 ksps, push-in
				ELM3602-0002	ELM3604-0002
				24 bit, 50 ksps, BNC	24 bit, 20 ksps, BNC
Pressure measuring	EM3701		EM3702	EM3712	
	differential pressure,		relative pressure,	relative pressure,	
	±100 hPa		7500 hPa	±1000 hPa	
Power measurement, ≤ 500 V			EL3403	EL3423	
			500 V AC, 1 A	480 V AC/DC, 1 A,	
				economy	
				EL3443	
				480 V AC/DC, 1 A,	
				extended functionalities	
			EL3443-0010	EL3443-0011	EL3444
			480 V AC/DC, 5 A,	480 V AC/DC, 100 mA,	distributed power mea-
			extended functionalities	extended functionalities	surement, galv. isolated
			EL3443-0013		EL3446-0011
			480 V AC/DC, 333 mV,		100 mA, distributed
			extended functionalities		power measurement
Power measurement, > 500 V			EL3453	EL3453-0100	
			690 V AC, 5 A,	130 V AC, 5 A,	
			extended functionalities	extended functionalities	
Mains monitor, ±480 V			EL3483	EL3483-0060	
			480 V AC/DC	480 V AC/DC, with	
				voltage measurement	
Power monitoring, ≤ 500 V			EL3773		
			500 V, 1 A AC/DC,		
			10 ksps		
Power monitoring, > 500 V			EL3783	EL3783-0100	
			690 V AC, 5 A AC,	130 V AC, 5 A AC,	
			20 ksps	20 ksps	
Ex i, 0/4...20 mA, standard signal	ELX3181		ELX3152	ELX3152-0090	ELX3184
	4...20 mA,		0/4...20 mA,	0/4...20 mA,	4...20 mA,
	single-ended,		single-ended,	single-ended,	single-ended,
	16 bit, HART		16 bit	16 bit, TwinSAFE SC	16 bit, HART

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.

EL3xxx EtherCAT Terminals, analog input						
Signal	1-channel		2-/3-channel	4-channel	5-/6-/8-channel	
Ex i, temperature measurement, resistance thermometer RTD			ELX3202	ELX3202-0090	ELX3204	ELX3204-0090
			RTD, 2-, 3- and 4-wire,	RTD, 2-, 3- and 4-wire,	RTD, 2-wire,	RTD, 2-wire,
			16 bit	16 bit, TwinSAFE SC	16 bit	16 bit, TwinSAFE SC
Ex i, temperature measurement, thermocouple, mV			ELX3312	ELX3312-0090	ELX3314	ELX3314-0090
			2-wire, 16 bit	2-wire, 16 bit,	2-wire, 16 bit	2-wire, 16 bit,
				TwinSAFE SC		TwinSAFE SC
Ex i, measurement technology	ELX3351	ELX3351-0090	ELX3252	ELX3632 ⁱ		
	strain gauge, 24 bit	strain gauge, 24 bit,	potentiometer	IEPE, 16 bit		
		TwinSAFE SC	measurement,			
			16 bit			

EL4xxx EtherCAT Terminals, analog output						
Signal	1-channel	2-channel		4-channel		8-channel
0...10 V	EL4001	EL4002	EL4102	EL4004	EL4104	EL4008
	12 bit	12 bit	16 bit	12 bit	16 bit	12 bit
±10 V	EL4031	EL4032	EL4132	EL4034	EL4134	EL4038
	12 bit		16 bit	12 bit	16 bit	12 bit
		EL4732				
		16 bit, oversampling				
0...20 mA	EL4011	EL4012	EL4112	EL4014	EL4114	EL4018
	12 bit	12 bit	16 bit	12 bit	16 bit	12 bit
		EL4712				
		16 bit, oversampling				
4...20 mA	EL4021	EL4022	EL4122	EL4024	EL4124	EL4028
	12 bit	12 bit	16 bit	12 bit	16 bit	12 bit
±10 V/±20 mA		EL4072		EL4074		EL4078
		16 bit		16 bit		16 bit
		EL4172		EL4374		
		16 bit, 10 ksps		16 bit, 1 ksps,		
				2 x input, 2 x output		
Ex i, 0/4...20 mA	ELX4181			ELX4154		
	single-ended, 16 bit, HART			single-ended, 16 bit		
±10 mA		EL4112-0010				
		16 bit				

EL5xxx EtherCAT Terminals, position measurement						
Signal	1-channel			2-channel		
Absolute position measurement	EL5001 SSI encoder interface	EL5001-0011 SSI monitor interface	EL5001-0090 SSI encoder interface, TwinSAFE SC	EL5002 SSI encoder interface	EL5032 EnDat® 2.2 interface	EL5032-0090 EnDat® 2.2 interface, TwinSAFE SC
		EL5031-0011 EnDat® 2.2 interface, oversampling		EL5042 BiSS® C interface	EL5072 inductive displacement sensor interface, LVDT	
Incremental position measurement	EL5021 SinCos encoder interface, 1 V _{PP}	EL5021-0090 SinCos encoder interface, 1 V _{PP} , TwinSAFE SC				
	EL5101 incremental encoder interface, RS422, TTL, 1 MHz	EL5101-0010 incremental encoder interface, RS422, 5 MHz	EL5101-0011 incremental encoder interface, RS422, 5 MHz, oversampling	EL5102 incremental encoder interface, RS422, TTL, open collector, 5 MHz	EL5112 incremental encoder interface, RS422, TTL, open collector, 5 MHz, 2 x AB/1 x ABC	
	EL5101-0090 incremental encoder interface, RS422, TTL, 1 MHz, TwinSAFE SC	EL5131 incremental encoder interface, RS422, TTL, 2 x 24 V DC push-pull outputs		EL5122 incremental encoder interface, TTL, open collector, 1 MHz, 2 x AB		
	EL5151 incremental encoder interface, 24 V HTL, 100 kHz	EL5151-0021 incremental encoder interface, 24 V HTL, 100 kHz, 1 x 24 V DC output	EL5151-0090 incremental encoder interface, 24 V HTL, 100 kHz, TwinSAFE SC	EL5152 incremental encoder interface, 24 V HTL, 100 kHz		
Ex i, incremental position measurement	ELX5151 incremental encoder interface, NAMUR	ELX5151-0090 incremental encoder interface, NAMUR, TwinSAFE SC				
Encoder simulation	EL5001-0012 SSI encoder simulation					

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.



EL6xxx EtherCAT Terminals, communication						
Signal	1-channel			2-channel		4-channel
System	EL6070 license key terminal	EL6071 license key terminal	EL6072 license key terminal, RTC			
	EL6080 memory terminal 128 kbyte	EL6090 display terminal				
Subsystem	EL6821 DALI-2 master and power supply terminal					
Serial	EL6001 RS232, 115.2 kbaud	EL6021 RS422/RS485, 115.2 kbaud		EL6002 RS232, 115.2 kbaud, D-sub	EL6022 RS422/RS485, 115.2 kbaud, D-sub	
EtherCAT/ Ethernet	EL6601 switch port	EL6688 IEEE 1588 master/slave	EL6689 synchronization via GNSS	EL6692 EtherCAT bridge	EL6695 EtherCAT bridge, high performance	EL6614 switch port
		EL6685 reference clock	EL6685-0010 reference clock, trimmable	EL6233 Ethernet-APL		
Master/slave, slave function -0010	EL6201 AS-Interface, master	EL6251 Modbus TCP, client/server	EL6631 PROFINET RT, controller	EL6632 PROFINET IRT, controller	EL6633 PROFINET RT, controller/i-device	EL6184 HART, secondary master
	EL6631-0010 PROFINET RT, device	EL6711-0010 CC-Link, slave	EL6720 Lightbus, master	EL6633-0010 PROFINET RT, device	EL6634 PROFINET IRT, controller	EL6254 Modbus TCP, client/server
	EL6731 PROFIBUS DP, master/slave	EL6731-0010 PROFIBUS, slave	EL6733 PROFIBUS, master/slave	EL6652 EtherNet/IP™, scanner	EL6652-0010 EtherNet/IP™, adapter	EL6224 IO-Link, master
	EL6733-0010 PROFIBUS, slave	EL6740-0010 Interbus, slave	EL6751 CANopen, master/slave	EL6653 EtherNet/IP™, scanner	EL6653-0010 EtherNet/IP™, adapter	EL6224-0090 IO-Link, TwinSAFE SC, master
	EL6751-0010 CANopen, slave	EL6753 CANopen, master/slave	EL6753-0010 CANopen, slave			
	EL6752 DeviceNet®, master	EL6752-0010 DeviceNet®, slave	EL6754 DeviceNet®, master			
	EL6754-0010 DeviceNet®, slave	EL6761 ISO 15118 powerline, charge controller	EL6851 DMX, master/slave			
	EL6861 BACnet MS/TP (RS485)					
	EL6900 TwinSAFE Logic	EL6910 TwinSAFE Logic, PROFIsafe master and slave support	EL6930 TwinSAFE Logic, PROFIsafe slave support			
Ex i				ELX6233 communication interface, Ethernet-APL		

EL/ELM7xxx EtherCAT Terminals, compact drive technology					
Motor type	< 3 A	3...5 A	> 5 A		16 A
Servomotor			ELM7211-0010 I _{rms} = 4.5 A, 48 V DC		
			ELM7211-9016 I _{rms} = 4.5 A, 48 V DC, TwinSAFE Logic	ELM7211-9018 I _{rms} = 4.5 A, 48 V DC, Safe Motion, TwinSAFE Logic	
			ELM7212-0010 I _{rms} = 2 x 4.5 A, 48 V DC		ELM7222-0010 I _{rms} = 2 x 8.0 A, 48 V DC
			ELM7212-9016 I _{rms} = 2 x 4.5 A, 48 V DC, TwinSAFE Logic	ELM7212-9018 I _{rms} = 2 x 4.5 A, 48 V DC, Safe Motion, TwinSAFE Logic	ELM7222-9016 I _{rms} = 2 x 8.0 A, 48 V DC, TwinSAFE Logic
					ELM7222-9018 I _{rms} = 2 x 8.0 A, 48 V DC, Safe Motion, TwinSAFE Logic
	EL7201-0010 I _{rms} = 2.8 A, 48 V DC, OCT	EL7211-0010 I _{rms} = 4.5 A, 48 V DC, OCT	ELM7221-0010 I _{rms} = 8 A, 48 V DC		ELM7231-0010 I _{rms} = 16 A, 48 V DC
EL7201 I _{rms} = 2.8 A, 48 V DC, resolver	EL7211 I _{rms} = 4.5 A, 48 V DC, resolver	ELM7221-9016 I _{rms} = 8 A, 48 V DC, TwinSAFE Logic	ELM7221-9018 I _{rms} = 8 A, 48 V DC, Safe Motion, TwinSAFE Logic	ELM7231-9016 I _{rms} = 16 A, 48 V DC, TwinSAFE Logic	
				ELM7231-9018 I _{rms} = 16 A, 48 V DC, Safe Motion, TwinSAFE Logic	
EL7201-9014 I _{rms} = 2.8 A, 48 V DC, OCT, STO	EL7211-9014 I _{rms} = 4.5 A, 48 V DC, OCT, STO	EL7221-9014 I _{rms} = 7...8 A with ZB8610, 48 V DC, OCT, STO			
Stepper motor	EL7031 I _{max} = 1.5 A, 24 V DC	EL7041 I _{max} = 5.0 A, 48 V DC, incr. enc.			
	EL7031-0030 I _{max} = 2.8 A, 24 V DC	EL7041-0052 I _{max} = 5.0 A, 48 V DC			
	EL7037 I _{max} = 1.5 A, 24 V DC, incr. enc., vector control	EL7047 I _{max} = 5.0 A, 48 V DC, incr. enc., vector control			
		EL7062 I _{max} = 3 A, 5 V DC, incr. enc.			
DC motor output stage	EL7332 I _{max} = 1.0 A, 24 V DC	EL7342 I _{max} = 3.5 A, 48 V DC, incr. enc.			
BLDC motor		EL7411 I _{rms} = 4.5 A, 48 V DC			
4-axis interface	EM7004 4 incr. enc., 32 digital I/Os 24 V DC, 4 analog outputs ±10 V				

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.

EL8xxx EtherCAT Terminals, multi-functional					
Multi-functional	EL8601-8411				
	8 x digital input, 1 x counter, 4 x digital output, 2 x PWM, 1 x analog input, 1 x analog output, 1 x encoder				
EL9xxx EtherCAT Terminals, system					
Signal	System				
Components for system bus	EL9011 bus end cover	EL9012 bus end cover for power and E-bus contacts	ELM9012 bus end cover for ELMxxxx, black	ELX9012 bus end cover for ELX, blue	EL9930 PROFIsafe, segment end terminal
	EL9195 shield terminal	EL9070 shield terminal	EL9080 isolation terminal		
Potential distribution	EL9180 2 clamping units per power contact	EL9181 2 x 8 terminal points	EL9182 8 x 2 terminal points	EL9183 1 x 16 terminal points	EL9184 8 x 24 V DC, 8 x 0 V DC
	EL9185 4 clamping units at 2 power contacts	EL9185-0010 4 clamping units at 2 power contacts, potential supply function	EL9186 8 x 24 V DC	EL9187 8 x 0 V DC	EL9188 16 x 24 V DC
	EL9189 16 x 0 V DC				
Potential supply, 24 V DC	EL9100 24 V DC	EL9110 diagnostics	EL9200 with fuse	EL9210 diagnostics, with fuse	EL9520 AS-Interface potential supply with filter
Potential supply, 120... 230 V AC	EL9150 with LED	EL9160 diagnostics	EL9190 any voltage up to 230 V		
Overcurrent protection, 24 V DC	EL9221-xxxx 1-channel	EL9222-xxxx 2-channel	EL9227-xxxx 2-channel, extended functionalities		
Power supply	EL9410 input 24 V DC, output 5 V DC/2 A	ELM9410 input 24 V DC, output 5 V DC/2 A	ELX9410 power supply terminal for E-bus refresh, 1 A	EL9501 input 24 V DC, output 0...20 V/0...2 A	EL9505 input 24 V DC, output 5 V DC/0.5 A
	EL9508 input 24 V DC, output 8 V DC/0.5 A	EL9510 input 24 V DC, output 10 V DC/0.5 A	EL9512 input 24 V DC, output 12 V DC/0.5 A	EL9515 input 24 V DC, output 15 V DC/0.5 A	EL9560 input 24 V DC, output 24 V DC/0.1 A with electrical isolation
	EL9561 input 24 V DC, output 0...20 V/0...2 A with electrical isolation	EL9562 input 24 V DC, output 2 x 24 V DC/0.2 A with electrical isolation	EL9562-0015 input 24 V DC, output 2 x 15 V DC/0.3 A with electrical isolation	ELX9560 power supply, 24 V DC, electrically isolated	
Filtering and smoothing	EL9540 surge filter terminal for field supply	EL9540-0010 surge filter terminal for field supply, onshore and offshore areas	EL9550 surge filter terminal for system/field supply	EL9550-0010 surge filter terminal for system/field supply, onshore and offshore areas	EL9550-0012 surge filter terminal for system/field supply with up to 10 A
	EL9570 buffer capacitor terminal, 500 µF, 48 V DC	EL9576 brake chopper terminal, up to 72 V DC, 155 µF			

EtherCAT Box

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EP1xxx EtherCAT Box, digital input				
Signal	8-channel		16-channel	
24 V DC, filter parameterizable 0...100 ms			EP1839-0022 8 x M12, with diagnostics	
			EP1839-0042 8 x M12, with diagnostics, EtherCAT M12	
24 V DC, filter 3 ms	EP1008-0001 ⁽¹⁾ 8 x M8	EP1008-0002 ^(1, 2) 4 x M12	EP1809-0021 ⁽¹⁾ 16 x M8	EP1809-0022 ^(1, 2) 8 x M12
		EP1008-0022 ⁽¹⁾ 8 x M12		EP1809-0042 8 x M12, EtherCAT M12
24 V DC, filter 10 µs	EP1018-0001 ⁽¹⁾ 8 x M8	EP1018-0002 ⁽¹⁾ 4 x M12	EP1819-0021 ⁽¹⁾ 16 x M8	EP1819-0022 ⁽¹⁾ 8 x M12
			EP1819-0005 16 x M8, 4-pin	
			EP1816-0003 connector with spring-loaded system	
			EP1816-0703 connector with spring-loaded system, ID switch	
			EP1816-0008 D-sub, 25-pin	
			EP1816-3008 D-sub, 25-pin, acceleration sensor	
			EP1816-1008 D-sub, 25-pin, changed pin assignment	
			EP1859-0042 8 x M12, 8 inputs + 8 outputs, I _{max} = 0.5 A, EtherCAT M12, 3 ms	
24 V DC, ground switching	EP1098-0001 ⁽¹⁾ 8 x M8			
24 V DC, timestamp	EP1258-0001 ⁽¹⁾ 8 x M8, 2-channel timestamp	EP1258-0002 ⁽¹⁾ 4 x M12, 2-channel timestamp		
		EP1258-0502 ⁽¹⁾ 4 x M12, 8-channel multi-timestamping		
24 V DC, counter		EP1518-0002 ⁽¹⁾ 4 x M12, multi-function input		
24 V DC, safe input	EP1908-0002 TwinSAFE, 8 safe inputs	EP1918-0002 TwinSAFE Logic, 8 safe inputs		
Ex i, NAMUR	EPX1058-0022 8 x M12			

EP2xxx EtherCAT Box, digital output						
Signal	4-channel	8-channel		16-channel		24-channel
24 V DC, I _{max} = 0.5 A		EP2008-0001 ⁽¹⁾ 8 x M8	EP2008-0002 ^(1, 2) 4 x M12		EP2839-0022 8 x M12, with diagnostics	
					EP2839-0042 8 x M12, with diagnostics, EtherCAT M12	
			EP2008-0022 ⁽¹⁾ 8 x M12	EP2809-0021 ⁽¹⁾ 16 x M8	EP2809-0022 ^(1, 2) 8 x M12	
				EP2816-0003 connector with spring-loaded system	EP2816-0004 M16, 19-pin	
				EP2816-0008 D-sub, 25-pin	EP2816-0010 2 x D-sub, 9-pin	EP2817-0008 D-sub, 25-pin
24 V DC, I _{max} = 0.5 A, Σ 16 A				EP2809-0042 8 x M12, EtherCAT M12		
24 V DC, I _{max} = 2.0 A		EP2028-0001 ⁽¹⁾ 8 x M8	EP2028-0002 ⁽¹⁾ 4 x M12			
		EP2038-0001 ⁽¹⁾ 8 x M8, with diagnostics	EP2038-0002 ⁽¹⁾ 4 x M12, with diagnostics			
24 V DC, I _{max} > 2.0 A, Σ 16 A			EP2038-0042 8 x M12, with diagnostics, EtherCAT M12			
			EP2028-0032 8 x M12			
			ER2028-1032 8 x M12			
24 V DC, safe output		EP2918-0032 TwinSAFE Logic, 8 safe outputs				
25 V AC/ 30 V DC	EP2624-0002 ⁽¹⁾ relay output, 4 x M12					
PWM	EP2534-0002 PWM output, 2 A, 4 x M12, current-controlled					
Ex i	EPX2004-0022 4 x M12, 50 mA					

EPxxxx: industrial housing in IP67, ⁽¹⁾also as ERxxxx: zinc die-cast housing in IP67, ⁽²⁾also as EQxxxx: stainless steel housing in IP69K

EP23xx EtherCAT Box, digital combi						
Signal	8-channel		12-channel	16-channel		
24 V DC, inputs + outputs	EP2308-0001 ⁽¹⁾ 8 x M8, 4 inputs + 4 outputs, I _{max} = 0.5 A, 3 ms	EP2308-0002 ⁽¹⁾ 4 x M12, 4 inputs + 4 outputs, I _{max} = 0.5 A, 3 ms		EP1859-0042 8 x M12, 8 inputs + 8 outputs, I _{max} = 0.5 A, EtherCAT M12, 3 ms		
	EP2318-0001 ⁽¹⁾ 8 x M8, 4 inputs + 4 outputs, I _{max} = 0.5 A, 10 µs	EP2318-0002 ⁽¹⁾ 4 x M12, 4 inputs + 4 outputs, I _{max} = 0.5 A, 10 µs		EP2316-0003 8 inputs + 8 outputs, I _{max} = 0.5 A, connector with spring-loaded system, 10 µs	EP2316-0008 8 inputs + 8 outputs, D-sub, 25-pin, 10 µs	
	EP2328-0001 ⁽¹⁾ 8 x M8, 4 inputs + 4 outputs, I _{max} = 2 A, 3 ms	EP2328-0002 ⁽¹⁾ 4 x M12, 4 inputs + 4 outputs, I _{max} = 2 A, 3 ms				
24 V DC, in-/outputs	EP2338-0001 ⁽¹⁾ 8 x M8, 8 in-/outputs, I _{max} = 0.5 A, 10 µs	EP2338-0002 ⁽¹⁾ 4 x M12, 8 in-/outputs, I _{max} = 0.5 A, 10 µs		EP2339-0021 ⁽¹⁾ 16 x M8, 16 in-/outputs, I _{max} = 0.5 A, 3 ms	EP2339-0022 ^(1, 2) 8 x M12, 16 in-/outputs, I _{max} = 0.5 A, 3 ms	EP2339-0121 16 x M8, 16 in-/outputs, I _{max} = 0.5 A, 3 ms, ground switching
	EP2338-1001 ⁽¹⁾ 8 x M8, 8 in-/outputs, I _{max} = 0.5 A, 3 ms	EP2338-1002 ⁽¹⁾ 4 x M12, 8 in-/outputs, I _{max} = 0.5 A, 3 ms		EP2339-0003 16 in-/outputs, I _{max} = 0.5 A, connector with spring-loaded system, 3 ms	EP2339-0042 8 x M12, 16 in-/outputs, I _{max} = 0.5 A, ∑ 16 A, EtherCAT M12, 3 ms	EP2339-0703 connector with spring-loaded system, ID switch
		EP2338-2002 4 x M12, 8 in-/outputs, I _{max} = 0.5 A, 10 µs		EP2349-0021 ⁽¹⁾ 16 x M8, 16 in-/outputs, I _{max} = 0.5 A, 10 µs	EP2349-0022 ⁽¹⁾ 8 x M12, 16 in-/outputs, I _{max} = 0.5 A, 10 µs	
Safety, safe in-/outputs			EP1957-0022 TwinSAFE Logic, 8 safe inputs, 4 safe outputs			

EPxxxx: industrial housing in IP67, ⁽¹⁾also as ERxxxx: zinc die-cast housing in IP67, ⁽²⁾also as EQxxxx: stainless steel housing in IP69K

EP3xxx EtherCAT Box, analog input					
Signal	1-channel	2-channel	4-channel		8-channel
±10 V, ±20 mA		EP3162-0002 parameterizable, electrically isolated, single-ended			EP3048-0002 16 bit, NAMUR NE43
±10 V, 0/4...20 mA			EP3174-0002 ^(1, 2) parameterizable, differential inputs	EP3174-0092 parameterizable, differential inputs, TwinSAFE SC	
		EP3182-1002 2 analog inputs, parameterizable, single-ended, 2 digital control outputs (sink/source type), 24 V DC, short-circuit proof	EP3184-0002 ⁽¹⁾ parameterizable, single-ended	EP3184-1002 ⁽¹⁾ parameterizable, single-ended, 2 channels per socket	
Resistance thermometer (RTD)			EP3204-0002 ^(1, 2) Pt100, Pt200, Pt500, Pt1000, Ni100, Ni120, Ni1000	EPX3204-0022 4 x M12, RTD	
Thermo-couple/mV			EP3314-0002 ^(1, 2) type J, K, L, B, E, N, R, S, T, U	EPX3314-0022 4 x M12, RTD	
Measurement bridge (SG)	EP3356-0022 24 bit, self-calibration				
Condition monitoring/ IEPE		EP3632-0001			
Acceler-ometers	EP3751-0160 1 x 3 axes	EP3752-0000 2 x 3 axes			
	EP3751-0260 1 x 3 axes, acceleration/gyroscope				
Pressure measuring			EP3744-0041 4 pressure inputs -1...1 bar (differential pressure to fifth connection)	EP3744-1041 4 pressure inputs 0...7 bar (differential pressure to fifth connection)	
			EP3744-2041 4 pressure inputs -1...1 bar (differential pressure to fifth connection), high-precision	<i>i</i> EP3744-3041 4 pressure inputs 0...12 bar (differential pressure to fifth connection)	<i>i</i>
Multi-function			EP3754-0002 ±10 V/±20 mA differential inputs, RTD, thermocouple	<i>i</i> EP3754-0702 ±10 V/±20 mA differential inputs, RTD, thermocouple, ID switch	<i>i</i>
Ex i, 4...20 mA			EPX3184-0022 4 x M12, single-ended, HART	EPX3184-0092 4 x M12, single-ended, HART, TwinSAFE SC	EPX3158-0022 8 x M12, single-ended

EP4xxx EtherCAT Box, analog output	
Signal	4-channel
±10 V, 0/4...20 mA	EP4174-0002 ⁽¹⁾ parameterizable

EP43xx EtherCAT Box, analog combi		
Signal	4-channel	8-channel
±10 V, 0/4...20 mA	EP4374-0002 ⁽¹⁾ 2 inputs + 2 outputs, parameterizable	EP4378-1022 4 inputs + 4 outputs, U/I parameterizable per channel, 8 digital I/Os, 24 V DC/3 ms
±10 V	EP4304-1002 2 inputs + 2 outputs, single-ended, 2 digital inputs, 24 V DC, 10 µs	
±20 mA	EP4314-1002 2 inputs + 2 outputs, single-ended, 2 digital inputs, 24 V DC, 10 µs	

EP5xxx EtherCAT Box, position measurement		
Function	M12	D-sub
SSI encoder interface	EP5001-0002 1 MHz, 32 bit	
Incremental encoder interface RS422	EP5101-0002 32/16 bit, 5 V DC sensor supply, 4 million increments/s	EP5101-0011 32/16 bit, 5 V DC sensor supply, 4 million increments/s
	EP5101-1002 32/16 bit, 24 V DC sensor supply	EP5101-2011 32/16 bit, 5 V DC sensor supply, 20 million increments/s
Incremental encoder interface 24 V DC	EP5151-0002 32/16 bit	

EP6xxx EtherCAT Box, communication					
Function	1-channel	2-channel	4-channel	8-channel	Other
System	EP6070-0060 license key module				
	EP6080-0000 memory box 128 kbyte				
Serial interface	EP6001-0002 ⁽¹⁾ RS232, RS422/RS485, 5 V DC/1 A	EP6002-0002 ⁽¹⁾ RS232, RS422/RS485			
EtherCAT/Ethernet	EP6601-0002 switch port				
IO-Link master		EP6222-0002 Class A	EP6224-0002 Class A	EP6228-0022 Class A	
			EP6224-2022 Class A	EP6228-0042 Class A, EtherCAT M12	
			EP6224-0042 Class A, EtherCAT M12	EP6228-0044 Class A, EtherCAT M12D, power 12L	i
			EP6224-0092 Class A, TwinSAFE SC	EP6228-3032 Class B	
			EP6224-3002 Class B	EP6228-3034 Class B, power 12L	
			EP6224-3022 Class B	EP6228-3132 4 x Class A, 4 x Class B	
				EP6228-3142 4 x Class A, 4 x Class B, EtherCAT M12	
	2 x 16 character display				EP6090-0000 display box

EPxxxx: industrial housing in IP67, ⁽¹⁾also as ERxxxx: zinc die-cast housing in IP67, ⁽²⁾also as EQxxxx: stainless steel housing in IP69K

EP7xxx EtherCAT Box, compact drive technology			
Motor type	< 3 A	> 3 A	
Servomotor		EP7211-0034 I _{rms} = 4.5 A, 48 V DC, OCT, STO suitable	EP7211-0035 I _{rms} = 4.5 A, 48 V DC, OCT, STO suitable, drive profile CiA DS402
Stepper motor		EP7047-1032 I _{max} = 5.0 A, 48 V DC	
	EP7041-1002 ⁽¹⁾ I _{max} = 1.5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output	EP7041-0002 ⁽¹⁾ I _{max} = 5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output	EP7041-2002 ⁽¹⁾ I _{max} = 5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output, motor connection via plug
		EP7041-3002 ⁽¹⁾ I _{max} = 5 A, 48 V DC, incremental encoder, for high-speed applications, encoder system (24 V DC encoder)	EP7041-3102 I _{max} = 5 A, 48 V DC, incremental encoder, for high-speed applications, encoder system (5 V DC encoder)
		EP7041-4032 I _{max} = 5.0 A, 48 V DC, BiSS® C encoder	
DC motor		EP7342-0002 ⁽¹⁾ I _{max} = 3.5 A, 48 V DC	
BLDC motor		EP7402-0057 for roller conveyor systems, 24 V DC, EtherCAT junction	EP7402-0067 for roller conveyor systems, 48 V DC, EtherCAT junction
			EP7402-0167 for roller conveyor systems, 48 V DC

EP8xxx EtherCAT Box, multi-functional		
Function	8-channel	12-channel
Multi-functional	EP8309-1022 8 digital inputs/outputs, 2 x tachometer input, 2 x 0/4...20 mA input, 1 x 0/4...20 mA output, 1 x 1.2 A PWMi output	EP8601-0022 8 x digital input, 1 x counter, 4 x digital output, 2 x PWM, 1 x analog input, 1 x analog output, 1 x encoder

EPxxxx EtherCAT Box, system				
Function				
Identification	EP1111-0000			
	3 decimal ID switches			
Junctions	EP1122-0001	EP1312-0001	EP9128-0021	
	EtherCAT, 2-channel	EtherCAT P, 2-channel	EtherCAT, 8 x M8	
Power distribution	EP9208-1035	EP9214-0023	EP9214-0024	
	8-channel, M12, L coded, 7/8"	4/4-channel, 7/8"	4/4-channel, M12, L-coded	
	EP9224-0023	EP9224-0024	EP9224-0037	EP9224-2037
	4/4-channel, current measurement and data logging, 7/8"	4/4-channel, current measurement and data logging, M12, L-coded	4-channel, ENP B17, ENP to EtherCAT P	4-channel junction, with power supply, ENP B17
PROFINET RT EtherCAT Box	EP9300-0022	EP9320-0022 ⁽¹⁾		
	EtherCAT Box interface with PROFINET RT	EtherCAT Box interface with PROFINET RT		
EtherCAT media converters fiber optic	EP9521-0020			
	1-channel, multi-mode			
Brake chopper box	EP9576-1032			
	up to 72 V DC			

EtherCAT P Box

► www.beckhoff.com/ethercat-p-box



EPP1xxx EtherCAT P Box, digital input					
Signal	4-channel	8-channel		16-channel	
24 V DC, filter 3 ms	EPP1004-0061 4 x M8	EPP1008-0001 8 x M8	EPP1008-0002 4 x M12	EPP1809-0021 16 x M8	EPP1809-0022 8 x M12
			EPP1008-0022 8 x M12	EPP1839-0022 8 x M12, with diagnostics	 EPP1859-0022 8 x M12
24 V DC, filter 10 µs		EPP1018-0001 8 x M8	EPP1018-0002 4 x M12	EPP1819-0021 16 x M8	EPP1819-0022 8 x M12
				EPP1819-0005 16 x M8, 4-pin	
				EPP1816-0008 D-sub, 25-pin	EPP1816-3008 D-sub, 25-pin, acceleration sensor
				EPP1816-0003 connector with spring- loaded system	EPP1816-0703 connector with spring- loaded system, ID switch
24 V DC, ground switching		EPP1098-0001 8 x M8			
24 V DC, timestamp		EPP1258-0001 8 x M8, 2-channel timestamp	EPP1258-0002 4 x M12, 2-channel timestamp		
24 V DC, counter			EPP1518-0002 4 x M12, multi-function input		

EPP2xxx EtherCAT P Box, digital output					
Signal	1-channel	4-channel	8-channel		16-channel
24 V DC, I _{max} = 0.5 A			EPP2008-0001 8 x M8	EPP2008-0002 4 x M12	
				EPP2008-0022 8 x M12	EPP2809-0021 16 x M8
					EPP2809-0022 8 x M12
					EPP2839-0022 8 x M12, with diagnostics
					 EPP2816-0008 D-sub, 25-pin
					EPP2817-0008 D-sub, 25-pin
					EPP2816-0010 2 x D-sub, 9-pin
					EPP2816-0003 connector with spring-loaded system
					EPP2816-0004 M16, 19-pin

EPP2xxx EtherCAT P Box, digital output					
Signal	1-channel	4-channel	8-channel		16-channel
24 V DC, I _{max} = 2.0 A			EPP2028-0001 8 x M8	EPP2028-0002 4 x M12	
			EPP2038-0001 8 x M8, with diagnostics	EPP2038-0002 4 x M12, with diagnostics	
25 V AC/ 30 V DC		EPP2624-0002 relay output, 4 x M12			
Current control, LED control	EPP2596-0002 24 V DC				

EPP23xx EtherCAT P Box, digital combi					
Signal	4-channel	8-channel		16-channel	
24 V DC, inputs + outputs		EPP2308-0001 8 x M8, 4 inputs + 4 outputs, I _{max} = 0.5 A, 3 ms	EPP2308-0002 4 x M12, 4 inputs + 4 outputs, I _{max} = 0.5 A, 3 ms	EPP2316-0003 8 inputs + 8 outputs, I _{max} = 0.5 A, connector with spring-loaded system, 10 µs	EPP2316-0008 8 inputs + 8 outputs, I _{max} = 0.5 A, D-sub, 25-pin, 10 µs
		EPP2318-0001 8 x M8, 4 inputs + 4 outputs, I _{max} = 0.5 A, 10 µs	EPP2318-0002 4 x M12, 4 inputs + 4 outputs, I _{max} = 0.5 A, 10 µs		
		EPP2328-0001 8 x M8, 4 inputs + 4 outputs, I _{max} = 2 A, 3 ms	EPP2328-0002 4 x M12, 4 inputs + 4 outputs, I _{max} = 2 A, 3 ms		
24 V DC, in-/outputs		EPP2338-0001 8 x M8, 8 in-/outputs, I _{max} = 0.5 A, 10 µs	EPP2338-0002 4 x M12, 8 in-/outputs, I _{max} = 0.5 A, 10 µs	EPP2339-0021 16 x M8, 16 in-/outputs, I _{max} = 0.5 A, 3 ms	EPP2339-0022 8 x M12, 16 inputs/outputs, I _{max} = 0.5 A, 3 ms
			EPP2338-2002 4 x M12, 8 in-/outputs, I _{max} = 0.5 A, 10 µs	EPP2349-0021 16 x M8, 16 in-/outputs, I _{max} = 0.5 A, 10 µs	EPP2349-0022 8 x M12, 16 inputs/outputs, I _{max} = 0.5 A, 10 µs
	EPP2334-0061 4 x M8, 4 inputs/outputs, I _{max} = 0.5 A, 10 µs	EPP2338-1001 8 x M8, 8 in-/outputs, I _{max} = 0.5 A, 3 ms	EPP2338-1002 4 x M12, 8 in-/outputs, I _{max} = 0.5 A, 3 ms	EPP2339-0003 16 inputs/outputs, I _{max} = 0.5 A, connector with spring-loaded system, 3 ms	EPP2339-0703 connector with spring- loaded system, ID switch

EPP3xxx EtherCAT P Box, analog input					
Signal	1-channel	2-channel	4-channel		8-channel
±10 V, 0/4...20 mA, standard signal			EPP3174-0002 parameterizable, differential inputs	EPP3184-0002 parameterizable, single-ended	EPP3048-0002 16 bit, NAMUR NE43 <i>i</i>
4...20 mA, standard signal			EPP3184-0802 single-ended, HART		
Temperature measurement, resistance ther- mometer RTD			EPP3204-0002 Pt100, Pt200, Pt500, Pt1000, Ni100, Ni120, Ni1000		
Temperature measurement, thermocouple, mV			EPP3314-0002 type J, K, L, B, E, N, R, S, T, U		
Measuring bridge, strain gauge	EPP3356-0022 24 bit, self-calibration		EPP3504-0023 24 bit, 10 ksps, push-in	ERP3504-0022 24 bit, 10 ksps, M12, zinc die-cast	
Acceleration measurement, position, vibra- tion, condition monitoring, IEPE		EPP3632-0001 16 bit, 50 ksps, 2 x M8			
		EPP3752-0000 2 x 3 axes			
Pressure measuring			EPP3744-0041 4 pressure inputs -1...1 bar (differential pressure to fifth connection)	EPP3744-1041 4 pressure inputs 0...7 bar (differential pressure to fifth connection)	
Multi-function			EPP3754-0002 <i>i</i> ±10 V/±20 mA differential inputs, RTD, thermocouple	EPP3754-0702 <i>i</i> ±10 V/±20 mA differential inputs, RTD, thermocouple, ID switch	

EPP4xxx EtherCAT P Box, analog output	
Signal	4-channel
±10 V, 0/4...20 mA	EPP4174-0002 parameterizable

EPP43xx EtherCAT P Box, analog combi	
Signal	4-channel
±10 V, 0/4...20 mA	EPP4374-0002 2 inputs + 2 outputs, parameterizable
±10 V	EPP4304-1002 2 inputs + 2 outputs, single-ended, 2 digital inputs, 24 V DC, 10 µs
±20 mA	EPP4314-1002 2 inputs + 2 outputs, single-ended, 2 digital inputs, 24 V DC, 10 µs

EPP5xxx EtherCAT P Box, position measurement		
Function	M12	D-sub
SSI encoder interface	EPP5001-0002 1 MHz, 32 bit	
Incremental encoder inter- face RS422	EPP5101-0002 32/16 bit, 5 V DC sensor supply, 4 million increments/s	EPP5101-1002 32/16 bit, 24 V DC sensor supply
Incremental encoder inter- face 24 V DC	EPP5151-0002 32/16 bit	EPP5101-0011 32/16 bit, 5 V DC sensor supply, 4 million increments/s

EPP6xxx EtherCAT P Box, communication					
Function	1-channel	2-channel	4-channel	8-channel	Other
Serial interface	EPP6001-0002 RS232, RS422/RS485, 5 V DC/1 A	EPP6002-0002 RS232, RS422/RS485			
IO-Link master			EPP6224-0002 <i>i</i> Class A	EPP6228-0022 Class A	
			EPP6224-0522 Class A, timestamp		
2 x 16 charac- ter display					EPP6090-0000 display box

EPP7xxx EtherCAT P Box, compact drive technology		
Motor type	< 3 A	> 3 A
Stepper motor	EPP7041-1002 I _{max} = 1.5 A, 48 V DC, incremental encoder	EPP7041-3002 I _{max} = 5.0 A, 48 V DC, incremental encoder
DC motor output stage		EPP7342-0002 I _{max} = 3.5 A, 48 V DC

EPPxxxx EtherCAT P Box, system			
Function			
Identification	EPP1111-0000 with ID switch		
EtherCAT P diagnostics	EPP9022-0060 4 x diagnostics (U _s , U _r , I _s , I _r)		
Converter EtherCAT P to EtherCAT	EPP9001-0060 EtherCAT P/EtherCAT connector with power transmission		
Junctions	EPP1322-0001 3 ports, with feed-in	EPP1332-0001 3 ports, with refresh	EPP1342-0001 3 ports
Supply module EtherCAT to EtherCAT P	EPP1321-0060		
Power distri- bution ENP to EtherCAT P	EP9224-0037 4-channel, ENP B17		
TwinSAFE SC	EPP9022-9060 4 x diagnostics (U _s , U _r , I _s , I _r), TwinSAFE SC		

EtherCAT plug-in modules

► www.beckhoff.com/ethercat-plug-in-modules



EJ11xx EtherCAT Couplers			
	EtherCAT		EtherCAT P
EtherCAT Couplers E-bus	EJ1100	EJ1101-0022	EJ1321
	2 x RJ45	external: connectors, power supply module and optional ID switches	1-port junction
Extension system and junctions	EK1110-0043	EK1110-0044	
	EtherCAT EJ coupler, CX and EL terminal connection	EtherCAT EJ coupler, CX and EL terminal connection, EtherCAT junction	
	EJ1122		
	2-port junction, external: connectors		

EJ1xxx EtherCAT plug-in modules, digital input			
Signal	4-channel	8-channel	16-channel
3.3 V DC/5 V DC		EJ1128 filter 0.05 µs	
24 V DC, filter 3 ms		EJ1008 type 3	EJ1809 type 3
			EJ1859 type 3, 8 inputs, 8 outputs, I _{max} = 0.5 A
			EJ1889 ground switching
24 V DC, filter 10 µs			EJ1819 type 3
24 V DC, filter 1 µs	EJ1254 type 3, timestamp		
24 V DC, safe input	EJ1914 TwinSAFE Logic, 4 safe inputs	EJ1918 TwinSAFE Logic, 8 safe inputs	
		EJ1957 TwinSAFE Logic, 8 safe inputs, 4 safe outputs	

EJ2xxx EtherCAT plug-in modules, digital output					
Signal	1-channel	2-channel	4-channel	8-channel	16-channel
3.3 V DC/5 V DC				EJ2128 I _{max} = ±20 mA	
24 V DC, I _{max} = 0.5 A		EJ2262 oversampling		EJ2008	EJ2809
					EJ2889 ground switching
					EJ1859 type 3, 8 inputs, 8 outputs, I _{max} = 0.5 A
24 V DC, safe output			EJ2914 TwinSAFE Logic, 4 safe outputs	EJ2918 TwinSAFE Logic, 8 safe outputs	
			EJ1957 TwinSAFE Logic, 8 safe inputs, 4 safe outputs		
PWM		EJ2502 24 V DC, 0.5 A	EJ2564 5...48 V DC, 4 A, RGBW, common anode		
Frequency output	EJ2521-0224 24 V DC, 1 A	EJ2522 24 V DC, 50 mA			

EJ3xxx EtherCAT plug-in modules, analog input				
Signal	2-channel	4-channel	5-channel	8-channel
±10 V, standard signal		EJ3004 single-ended, 12 bit		
		EJ3104 differential input, 16 bit		EJ3108 6 x differential inputs, 2 x single-ended, 16 bit
0...10 V, standard signal				EJ3068 single-ended, 12 bit
0...20 mA, standard signal				EJ3048 single-ended, 12 bit
4...20 mA, standard signal		EJ3124-0090 TwinSAFE SC, 16 bit		EJ3058 single-ended, 12 bit
0...±20 mA		EJ3114-0010 differential input, 16 bit, high-precision		
Temperature measurement, resistance ther- mometer (RTD)	EJ3202 16 bit	EJ3214 16 bit		
Temperature measurement, thermo- couple/mV		EJ3314-0090 TwinSAFE SC, 16 bit		EJ3318 type J, K, L...U, 16 bit
Measurement technology, potentiometer			EJ3255 16 bit	

EJ4xxx EtherCAT plug-in modules, analog output			
Signal	2-channel	4-channel	8-channel
0...10 V	EJ4002 12 bit	EJ4004 12 bit	EJ4008 12 bit
±10 V	EJ4132 16 bit	EJ4134 16 bit	
0...20 mA			EJ4018 12 bit
4...20 mA		EJ4024 12 bit	

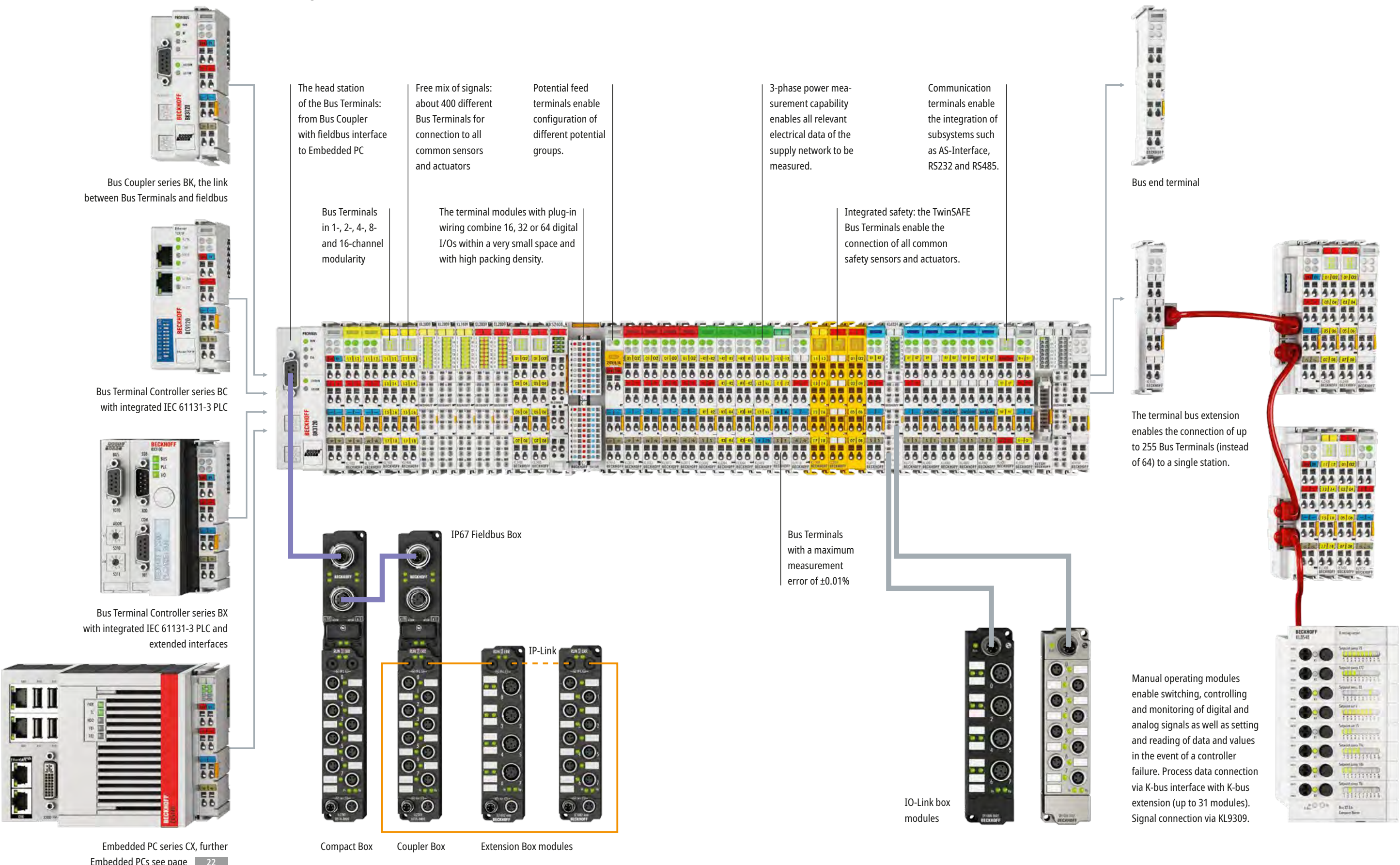
EJ5xxx EtherCAT plug-in modules, position measurement						
Signal	1-channel				2-channel	
Absolute position measurement					EJ5002 SSI encoder interface	EJ5042-0010 BiSS® C interface
Incremental position measurement	EJ5021 SinCos encoder interface, 1 V _{pp}	EJ5101 incremental encoder interface, RS422, TTL, 1 MHz	EJ5101-0090 incremental encoder interface, RS422, TTL, 1 MHz, TwinSAFE SC	EJ5151 incremental encoder interface, 24 V HTL, 100 kHz	EJ5152 incremental encoder interface, 24 V HTL, 100 kHz	EJ5112 incremental encoder interface, RS422, TTL, open collector, 5 MHz, 2 x AB/1 x ABC

EJ6xxx EtherCAT plug-in modules, communication				
Signal	1-channel	2-channel	4-channel	
System	EJ6070			
	license key module			
	EJ6080			
	memory module 128 kbyte			
Master		EJ6002 serial interface RS232, RS485 or RS422	EJ6224 IO-Link	EJ6224-0090 IO-Link, TwinSAFE SC
Safety	EJ6910 TwinSAFE Logic			

EJ7xxx EtherCAT plug-in modules, compact drive technology				
Motor type	< 3 A		3...5 A	
Servomotor			EJ7211-0010 I _{rms} = 4.5 A, 48 V DC, OCT	EJ7211-9414 I _{rms} = 4.5 A, 48 V DC, OCT, STO, TwinSAFE SC
Stepper motor	EJ7031 I _{max} = 1.5 A, 24 V DC	EJ7037 I _{max} = 1.5 A, 24 V DC, incremental encoder, vector control	EJ7041-0052 I _{max} = 5.0 A, 48 V DC	EJ7047 I _{max} = 5.0 A, 48 V DC, incremental encoder, vector control
DC motor output stage			EJ7334-0008 I _{max} = 3.0 A, 24 V DC, incremental encoder	EJ7342 I _{max} = 3.5 A, 48 V DC, incremental encoder
BLDC			EJ7411 I _{rms} = 4.5 A, 48 V DC	

EJ9xxx EtherCAT plug-in modules, system		
Signal	Power supply and accessories	System
Power supply	EJ9400 input 24 V DC, E-bus power supply, 2.5 A	EJ9404 input 24 V DC, E-bus power supply, 12 A
	EJ9505 input 24 V DC, output 5 V DC, 0.5 A	
Filtering and smoothing	EJ9576 brake chopper module, up to 72 V DC, 155 µF	
System		EJ9001 placeholder module

System overview fieldbus I/O



Bus Terminals

► www.beckhoff.com/busterminal



BKxxxx Bus Couplers			
Fieldbus	Standard	Economy plus	Compact
EtherCAT		BK1120	BK1150
			BK1250 E-bus to K-bus interface
Ethernet TCP/IP	BK9000		BK9050
	BK9100 2-channel switch		
EtherNet/IP	BK9105 2-channel switch		BK9055
CANopen		BK5120	BK5150
			BK5151
			BK5160
CC-Link			BK7150
DeviceNet	BK5200	BK5220	BK5250
INTERBUS	BK4000	BK4020	
LIGHTBUS	BK2000	BK2020	
Modbus			BK7350
PROFINET	BK3100 12 Mbaud	BK3120 12 Mbaud	BK3150 12 Mbaud
		BK3520 12 Mbaud, fiber optic	
PROFINET	BK9103 2-channel switch		BK9053
RS485	BK8000		
RS232	BK8100		
sercos the automation bus	BK7500	BK7520	

BCxxxx, BXxxxx Bus Terminal Controllers					
Fieldbus	Programm storage				
	32/96 kbytes	48 kbytes	64/96 kbytes	128 kbytes	256 kbytes
Ethernet TCP/IP		BC9050	BC9000	BC9020	BX9000
			BC9100 2-channel switch	BC9120 2-channel switch	
		BC9191 room controller		BC9191-0100 room controller, RS485 interface	
CANopen		BC5150			BX5100
DeviceNet		BC5250			BX5200
Modbus	BC7300				
PROFINET	BC3100 12 Mbaud	BC3150 12 Mbaud			BX3100 12 Mbaud
	RS485	BC8050			BX8000
RS232		BC8150			

KL1xxx Bus Terminals, digital input						
Signal	2-channel	4-channel	8-channel	16-channel	KM1xxx	
5 V DC		KL1124 filter 0.2 ms				
24 V DC, filter 3 ms	KL1002 type 3	KL1104 type 3	KL1804 type 3, 8 x 24 V, 4 x 0 V	KL1808 type 3, 8 x 24 V DC	KL1809 type 3	KM1002 16-channel, type 1
	KL1402 type 3	KL1302 type 2	KL1404 type 3, 4 x 2-wire connection	KL1304 type 2	KL1408 type 3	KM1004 32-channel, type 1
	KL1052 positive/ground switching	KL1154 positive/ground switching	KL1184 ground switching	KL1488 ground switching	KL1889 ground switching	KM1008 64-channel, type 1
	KL1212 type 1, short-circuit pro- tected sensor supply	KL1362 break-in alarm			KL1859 type 3, 8 inputs, 8 outputs, I _{max} = 0.5 A	
					KL1862 type 3, flat-ribbon cable	
24 V DC, filter 0.2 ms					KL1862-0010 type 3, flat-ribbon cable, ground switching	
	KL1012 type 3	KL1412 type 3	KL1114 type 3	KL1814 type 3, 8 x 24 V, 4 x 0 V	KL1418 type 3	KL1819 type 3
		KL1312 type 2		KL1314 type 2		KM1012 16-channel, type 1
			KL1414 type 3, 4 x 2-wire connection	KL1434 type 2, 4 x 2-wire connection		KM1014 32-channel, type 1
			KL1164 positive/ground switching	KL1194 ground switching	KL1498 ground switching	KM1018 64-channel, type 1
24 V DC					KL1872 type 3, flat-ribbon cable	
	KL1232 pulse expansion	KL1382 thermistor	KL1904 TwinSAFE, 4 safe inputs			KM1644 4-channel, manual operation
	KL1501 type 1, 100 kHz, 32 bit	KL1512 type 1, 1 kHz, 16 bit				
24 V DC, counter						
≥ 48 V DC	KL1032 48 V DC, filter 3 ms	KL1712-0060 60 V DC				
120 V AC/DC	KL1712					
230 V AC	KL1702	KL1722 no power contacts	KL1704			
NAMUR	KL1352					

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.

KL2xxx Bus Terminals, digital output						
Signal	1-channel	2-channel	4-channel	8-channel	16-channel	KM2xxx
5 V DC			KL2124 I _{max} = ±20 mA			
24 V DC, I _{max} = 0.5 A		KL2012 short-circuit proof	KL2114 short-circuit proof	KL2808 8 x 0 V	KL2809 reverse voltage protection	KM2002 16-channel
		KL2032 reverse voltage protection	KL2134 reverse voltage protection			KM2004 32-channel
			KL2404 4 x 2-wire	KL2408 reverse voltage protection		KM2008 64-channel
		KL2212 diagnostics, protected sensor supply			KL2819 with diagnostics	KM2042 16-channel, D-sub connection
			KL2184 ground switching	KL2488 ground switching	KL2889 ground switching	
					KL1859 type 3, 8 inputs, 8 outputs, I _{max} = 0.5 A	
					KL2872 flat-ribbon cable	
					KL2872-0010 flat-ribbon cable, ground switching	
24 V DC, I _{max} = 2.0 A		KL2022	KL2424 4 x 2-wire	KL2828 8 x 2-wire		
24 V DC, I _{max} = 4.0 A/8.0 A		KL2442 2 x 4 A/1 x 8 A				
24 V DC, safe output			KL2904 TwinSAFE, 4 safe outputs			
30 V AC/ 48 V DC solid-state relay, I _{max} = 2.0 A			KL2784			
			KL2794 potential-free	KL2798 potential-free		
230 V AC solid-state relay	KL2701 I _{max} = 3 A	KL2702 I _{max} = 0.3 A				
Relay (up to 400 V AC)	KL2641 make contact, manual operation, I _{max} = 16 A	KL2602 make contact, I _{max} = 5 A	KL2622 make contact, no power contacts, I _{max} = 5 A	KL2634 make contact, 250 V AC/30 V DC		KM2604 I _{max} = 16 A, 4-channel
		KL2602-0010 make contact, I _{max} = 5 A, contact- protecting switching	KL2622-0010 make contact, no power contacts, I _{max} = 5 A, contact- protecting switching			KM2614 I _{max} = 16 A, 4-channel, manual operation
		KL2652 change-over, I _{max} = 5 A				KM2642 I _{max} = 6 A, manual/ automatic operation, relay state readable
	KL2631 400 V AC, make contact	KL2612 125 V AC, change-over	KL2692 cycle monitoring (watchdog)			KM2652 I _{max} = 6 A, manual/ automatic operation, switch and relay state readable

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.

KL2xxx Bus Terminals, digital output						
Signal	1-channel	2-channel	4-channel	8-channel	16-channel	KM2xxx
Triac (12...230 V AC)		KL2712	KL2722 mutually locked outputs			
		KL2732 mutually locked outputs, no power contacts				
PWM		KL2502 24 V DC, I _{max} = 0.1 A	KL2512 24 V DC, I _{max} = 1.5 A, ground switching			
		KL2535 I _{max} = ±1 A, 24 V DC, current-controlled	KL2545 I _{max} = ±3.5 A, 50 V DC, current-controlled			
Frequency output	KL2521 1-channel AB, 0...500 kHz, RS422					
Current con- trol, dimmer control	KL2751 universal dimmer, 300 W					
	KL2761 universal dimmer, 600 W					

KL2xxx Bus Terminals, compact drive technology		
Motor type	< 3 A	3...5 A
Stepper motor	KL2531 I _{max} = 1.5 A, 24 V DC	KL2541 I _{max} = 5.0 A, 48 V DC, incremental encoder
DC motor output stage	KL2532 I _{max} = 1.0 A, 24 V DC	KL2284 reverse switching, I _{max} = 2.0 A, 0...24 V DC
AC motor speed controller	KL2791 230 V AC, 200 VA, 1-phase AC motor	KL2552 I _{max} = 5.0 A, 48 V DC, incremental encoder

KL3xxx Bus Terminals, analog input					
Signal	1-channel	2-/3-channel	4-channel	8-channel	
0...2 V, 0...500 mV		KL3172 0...2 V, 16 bit, 0.05%	KL3172-0500 0...500 mV, 16 bit, 0.05%		
			KL3182 16 bit, 0.05%		
±2 V					
0...10 V	KL3061 single-ended, 12 bit	KL3062 single-ended, 12 bit	KL3162 16 bit, 0.05%	KL3064 single-ended, 12 bit	
				KL3464 with sensor supply, single-ended, 12 bit	KL3468 single-ended, 12 bit
±10 V	KL3001 differential input, 12 bit	KL3002 differential input, 12 bit	KL3102 differential input, 16 bit	KL3404 single-ended, 12 bit	KL3408 single-ended, 12 bit
			KL3132 16 bit, 0.05%		
0...20 mA	KL3011 differential input, 12 bit	KL3012 differential input, 12 bit	KL3112 differential input, 16 bit	KL3044 single-ended, 12 bit	KL3448 single-ended, 12 bit
	KL3041 with sensor supply, 12 bit	KL3042 with sensor supply, 12 bit	KL3142 16 bit, 0.05%	KL3444 with sensor supply, single-ended, 12 bit	
4...20 mA	KL3021 differential input, 12 bit	KL3022 differential input, 12 bit	KL3122 differential input, 16 bit	KL3054 single-ended, 12 bit	KL3458 single-ended, 12 bit
	KL3051 with sensor supply, 12 bit	KL3052 with sensor supply, 12 bit	KL3152 16 bit, 0.05%	KL3454 with sensor supply, single-ended, 12 bit	
Resistance thermometer (RTD)	KL3201 Pt100...1000, Ni100, 16 bit	KL3202 Pt100...1000, Ni100, 16 bit	KL3222 Pt100, 4-wire connection, high-precision	KL3204 Pt100...1000, Ni100...1000, 2-wire connection	KL3208-0010 Pt1000, Ni1000, NTC 1.8...100 k, potentiom. 1, 5, 10 kΩ
				KL3204-0030 NTC (10 kΩ)	
				KL3214 Pt100...1000, Ni100...1000, KTY, 3-wire connection	KL3228 Pt1000, Ni1000
Thermo- couple/mV	KL3311 type J, K, L...U, 16 bit	KL3312 type J, K, L...U, 16 bit	KL3314 type J, K, L...U, 16 bit		
Measurement bridge (SG)	KL3351 16 bit				
	KL3356 16 bit, self-calibration				
Oscilloscope	KL3361 ±16 mV	KL3362 ±10 V			
Measurement technology	KL3681 digital multimeter, 18 bit				
Pressure measuring	KM3701 differential pressure, -100...+100 hPa	KM3702 relative pressure, 7500 hPa	KM3712 relative pressure, -1000...+1000 hPa		
	KM3701-0340 differential pressure, up to 340 hPa				
Power measurement		KL3403 power measurement, 3-phase, 1 A	KL3403-0010 power measurement, 3-phase, 5 A		
		KL3453 690 V AC, 5 A, extended functionalities			

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.

KL4xxx Bus Terminals, analog output					
Signal	1-channel	2-channel	4-channel	8-channel	KM4xxx
0...10 V	KL4001 12 bit, potential-free output	KL4002 12 bit	KL4004 12 bit, no power contacts		KM4602 12-bit manual/automatic operation
			KL4404 12 bit	KL4408 12 bit	
±10 V	KL4031 12 bit, potential-free output	KL4032 12 bit	KL4034 12 bit, no power contacts		
		KL4132 16 bit	KL4434 12 bit	KL4438 12 bit	
			KL4494 12 bit, 2 x input, 2 x output		
0...20 mA	KL4011 12 bit	KL4012 12 bit	KL4414 12 bit	KL4418 12 bit	
		KL4112 16 bit			
4...20 mA	KL4021 12 bit	KL4022 12 bit	KL4424 12 bit	KL4428 12 bit	

KL5xxx Bus Terminals, position measurement		
Signal	1-channel	2-channel
Absolute position measurement	KL5001 SSI encoder interface	
	KL5051 SSI encoder interface, bidirectional	
Incremental position measurement	KL5101 incremental encoder interface, RS422, TTL, 1 MHz	
	KL5111 incremental encoder interface, 24 V HTL, 250 kHz, 16 bit counter	
	KL5151 incremental encoder interface, 24 V HTL, 100 kHz, 32 bit counter	KL5152 incremental encoder interface, 24 V HTL, 100 kHz, 32 bit counter
	KL5121 incremental encoder interface, 24 V HTL, path control, 250 kHz	

KL6xxx Bus Terminals, communication			
Signal			
Serial interfaces	KL6001	KL6031	KL6011
	RS232, 19.2 kbaud	RS232, 115.2 kbaud	TTY, 20 mA current loop
	KL6051	KL6021	KL6041
	data exchange terminal, 32 bit	RS422/RS485, 19.2 kbaud	RS422/RS485, 115.2 kbaud
Subsystems	KL6201	KL6211	KL6224
	AS-Interface master terminal	AS-Interface master terminal with power contacts	IO-Link master
	KL6301		
	KNX/EIB Bus Terminal		
	KL6581	KL6583	
	EnOcean master	EnOcean transmitter/receiver	
	KL6771	KL6781	
	MP-Bus master terminal	M-Bus master terminal	
	KL6811	KL6821	
	DALI/DSI master and power supply terminal	DALI-2 multi-master and power supply terminal	
	KL6831	KL6841	
	SMI terminal, LoVo	SMI terminal, 230 V AC	
Safety	KL6904		
	TwinSAFE Logic, 4 safe outputs		

KL85xx Bus Terminals, manual operation modules				
Technology	4-channel	8-channel	16-channel	Other
Manual operation modules	KL8524	KL8528	KL8519	KL8500
	4 x 2-channel digital output, 24 V DC, 0.5 A	digital output, 24 V DC, 0.5 A	digital input signal module	placeholder module
		KL8548		
		analog output, 0...10 V		
System				KL9309
				adapter terminal for manual operating modules

KL9xxx Bus Terminals, system			
Signal	System		Potential supply
System			Power supply and accessories
	KL9010	KL9070	
	bus end terminal	shield terminal	
	KL9020	KL9050	
	terminal bus extension end terminal	terminal bus extension coupler terminal	
	KL9309	KL9080	
	adapter terminal for manual operating modules	isolation terminal	
	KL9195		
	shield terminal		

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.

KL9xxx Bus Terminals, system			
Signal	System		Potential supply
Potential distribution terminals			Power supply and accessories
	KL9180	KL9181	
	2 terminal points per power contact	2 x 8 terminal points	
	KL9182	KL9183	
	8 x 2 terminal points	1 x 16 terminal points	
	KL9184	KL9185	
	8 x 24 V DC, 8 x 0 V DC	only 2 power contacts	
	KL9186	KL9187	
	8 x 24 V DC	8 x 0 V DC	
	KL9188	KL9189	
	16 x 24 V DC	16 x 0 V DC	
	KL9380		
Filter	KL9540		
	surge filter terminal for field supply		
	KL9540-0010	KL9550	
	surge filter field supply for analog terminals	surge filter terminal for system/field supply	
Diode arrays	KL9300		
	4 diodes, potential-free		
	KL9301	KL9302	
	7 diodes, common cathode	7 diodes, common anode	
24 V DC		KL9100	KL9400
			K-bus power supply, 2 A
		KL9110	KL9505
		diagnostics	output 5 V DC, 0.5 A
		KL9200	KL9508
		with fuse	output 8 V DC, 0.5 A
		KL9210	KL9510
		diagnostics, with fuse	output 10 V DC, 0.5 A
			KL9512
			output 12 V DC, 0.5 A
			KL9515
			output 15 V DC, 0.5 A
		KL9520	KL9528
		AS-Interface potential supply	AS-Interface power supply terminal
			KL9560
			output 24 V DC, 0.1 A
50 V DC			KL9570
			buffer capacitor terminal, 500 µF
120... 230 V AC		KL9150	
		KL9160	
		diagnostics	
		KL9250	
		with fuse	
		KL9260	
		diagnostics, with fuse	
		KL9190	
		any voltage up to 230 V AC	
		KL9290	
		with fuse	

Fieldbus Box and IO-Link box

► www.beckhoff.com/fieldbusbox



Fieldbus Box	Compact Box		Coupler Box	
Fieldbus	Fieldbus Box without IP-Link interface		Fieldbus Box with IP-Link interface	
EtherCAT			IL230x-B110	
PROFINET	IPxxxx-B310	IPxxxx-B318 with integrated tee-connector	IL230x-B310	IL230x-B318 with integrated tee-connector
CANopen	IPxxxx-B510	IPxxxx-B518 with integrated tee-connector	IL230x-B510	IL230x-B518 with integrated tee-connector
DeviceNet	IPxxxx-B520	IPxxxx-B528 with integrated tee-connector	IL230x-B520	IL230x-B528 with integrated tee-connector
Ethernet TCP/IP			IL230x-B900	IL230x-B901
PROFINET			IL230x-B903	
EtherNet/IP			IL230x-B905	

IP1xxx-Bxxx Fieldbus Box, digital input			
Signal	2-channel	8-channel	
24 V DC, filter 3 ms		IP1001-Bxxx ⁽¹⁾ 8 x M8	IP1002-Bxxx ⁽¹⁾ 4 x M12
24 V DC, filter 0.2 ms		IP1011-Bxxx ⁽¹⁾ 8 x M8	IP1012-Bxxx ⁽¹⁾ 4 x M12
Counter	IP1502-Bxxx ⁽¹⁾ up/down counter 24 V DC, 100 kHz		

IP2xxx-Bxxx Fieldbus Box, digital output			
Signal	2-channel	8-channel	16-channel
24 V DC, I _{max} = 0.5 A		IP2001-Bxxx ⁽¹⁾ 8 x M8	IP2002-Bxxx ⁽¹⁾ 4 x M12
24 V DC, I _{max} = 0.5 A, Σ 4 A			IE2808 D-sub
24 V DC, I _{max} = 2 A, Σ 4 A		IP2021-Bxxx ⁽¹⁾ 8 x M8	IP2022-Bxxx ⁽¹⁾ 4 x M12
24 V DC, I _{max} = 2 A, Σ 12 A		IP2041-Bxxx ⁽¹⁾ 8 x M8	IP2042-Bxxx ⁽¹⁾ 4 x M12
PWM, I _{max} = 2.5 A	IP2512-Bxxx ⁽¹⁾ 4 x M12		

⁽¹⁾also as IExxxx: Extension Box, ⁽²⁾also as ILxxxx-Bxxx: Coupler Box

IP23/24xx-Bxxx Fieldbus Box, digital combi				
Signal	8-channel		16-channel	
24 V DC, filter 3 ms, I _{max} = 0.5 A	IP2301-Bxxx ^(1, 2) 8 x M8, 4 inputs + 4 outputs	IP2302-Bxxx ^(1, 2) 4 x M12, 4 inputs + 4 outputs	IP2401-Bxxx ⁽¹⁾ 8 x M8, 8 inputs/outputs	IE2403 IP20 plug
24 V DC, filter 0.2 ms, I _{max} = 0.5 A	IP2311-Bxxx ⁽¹⁾ 8 x M8, 4 inputs + 4 outputs	IP2312-Bxxx ⁽¹⁾ 4 x M12, 4 inputs + 4 outputs		
24 V DC, filter 3 ms, I _{max} = 2 A, Σ 4 A	IP2321-Bxxx ⁽¹⁾ 8 x M8, 4 inputs + 4 outputs	IP2322-Bxxx ⁽¹⁾ 4 x M12, 4 inputs + 4 outputs		
24 V DC, filter 0.2 ms, I _{max} = 2 A, Σ 4 A	IP2331-Bxxx ⁽¹⁾ 8 x M8, 4 inputs + 4 outputs	IP2332-Bxxx ⁽¹⁾ 4 x M12, 4 inputs + 4 outputs		

IP3xxx-Bxxx Fieldbus Box, analog input	
Signal	4-channel
±10 V	IP3102-Bxxx ⁽¹⁾ differential inputs, 16 bit
0/4...20 mA	IP3112-Bxxx ⁽¹⁾ differential inputs, 16 bit
Resistance thermometer	IP3202-Bxxx ⁽¹⁾ Pt100, Pt200, Pt500, Pt1000, Ni100, 16 bit
Thermo-couple/mV	IP3312-Bxxx ⁽¹⁾ type J, K, L, B, E, N, R, S, T, U, 16 bit

IP4xxx-Bxxx Fieldbus Box, analog output	
Signal	4-channel
0/4...20 mA	IP4112-Bxxx ⁽¹⁾ 16 bit
±10 V	IP4132-Bxxx ⁽¹⁾ 16 bit

IP5xxx-Bxxx Fieldbus Box, position measurement	
Function	M12
SSI encoder interface	IP5009-Bxxx ⁽¹⁾
Incremental encoder interface RS422	IP5109-Bxxx ⁽¹⁾ 1 MHz
SinCos encoder interface	IP5209-Bxxx 12-pin
	IP5209-Bxxx-1000 9-pin

IP6xxx-Bxxx Fieldbus Box, communication			
Function			
Serial interfaces	IP6002-Bxxx ⁽¹⁾ RS232	IP6012-Bxxx ⁽¹⁾ 0...20 mA (TTY)	IP6022-Bxxx ⁽¹⁾ RS422/RS485

Infrastructure components

► www.beckhoff.com/infrastructure-components



EPI1xxx | Fieldbus Box, IO-Link box, digital input

Signal	8-channel		16-channel	
24 V DC, filter 3 ms	EPI1008-0001 ⁽¹⁾ 8 x M8	EPI1008-0002 ⁽¹⁾ 4 x M12	EPI1809-0021 ⁽¹⁾ 16 x M8	EPI1809-0022 ⁽¹⁾ 8 x M12

EPI2xxx | Fieldbus Box, IO-Link box, digital output

Signal	8-channel		16-channel	
24 V DC, I _{max} = 0.5 A	EPI2008-0001 ⁽¹⁾ 8 x M8	EPI2008-0002 ⁽¹⁾ 4 x M12		
24 V DC, I _{max} = 0.5 A, Σ 4 A			EPI2809-0021 ⁽¹⁾ 16 x M8	EPI2809-0022 ⁽¹⁾ 8 x M12

EPI23xx | Fieldbus Box, IO-Link box, digital combi

Signal	8-channel		16-channel	
24 V DC, filter 3 ms, I _{max} = 0.5 A	EPI2338-0001 ⁽¹⁾ 8 x M8	EPI2338-0002 ⁽¹⁾ 4 x M12		
24 V DC, filter 3 ms, I _{max} = 0.5 A, Σ 4 A			EPI2339-0021 ⁽¹⁾ 16 x M8	EPI2339-0022 ⁽¹⁾ 8 x M12

EPI3xxx | Fieldbus Box, IO-Link box, analog input

Signal	4-channel	8-channel
±10 V, 0/4...20 mA	EPI3174-0002 ⁽¹⁾ parameterizable, differential input, 16 bit	EPI3188-0022 parameterizable, single-ended, 16 bit

EPI4xxx | Fieldbus Box, IO-Link box, analog output

Signal	4-channel
±10 V, 0/4...20 mA	EPI4374-0002 ⁽¹⁾ 2 inputs + 2 outputs, parameterizable, 16 bit

EPIxxxx: industrial housing in IP67, ⁽¹⁾also as ERIxxxx: zinc die-cast housing in IP67

CUxxxx, EPxxxx | EtherCAT components

	100 Mbit/s, IP20		100 Mbit/s, IP67	1 Gbit/s, IP20	
Junctions	CU1123 junction, 3 x RJ45	CU1123-0010 junction, 3 x RJ45, Extended Distance		CU1423 junction, 3 x RJ45	
	CU1124 junction, 4 x RJ45	CU1128 junction, 8 x RJ45	EP9128-0021 EtherCAT, 8 x M8	CU1411 branch controller, 1 port	CU1418 branch controller, 8 ports
Media converters	CU1521 1-channel, multi-mode/ single-mode	CU1521-0020 1-channel, SFP slot	EP9521-0020 1-channel, multi-mode		
	CU1561 1-channel, POF				

CUxxxx, EPxxxx | Ethernet switches/components

	100 Mbit/s, IP20		100 Mbit/s, IP67	1 Gbit/s, IP20	
Switches	CU2005 5-port, RJ45	CU2008 8-port, RJ45	CU2016 16-port, RJ45	CU2608 8-port, M12 (D-coded)	CU2208 8-port, RJ45
Media converters	CU1521 1-channel, multi-mode/ single-mode	CU1561 1-channel, POF		EP9521-0020 1-channel, multi-mode	

CUxxxx | Ethernet port multiplier

	1 Gbit/s
Multiplier	CU2508 1 x RJ45 (+ 8 x RJ45: 100 Mbit/s)
	CU2508-0022 1 x M12 (+ 8 x M12: 100 Mbit/s)

Measuring transformers

► www.beckhoff.com/sct



SCT1111



SCT21xx

SCT1xxx Mini ring-type current transformers	
Primary current	Max. diameter round conductor 7.6 mm
0...32 to 0...64 A AC	SCT1111 accuracy class 1

SCT2xxx Ring-type current transformers					
Primary current	Max. diameter round conductor				
	25.7 mm	31.8 mm	43.7 mm	54.7 mm	70 mm
0...60 to 0...500 A AC	SCT2111 accuracy class 1				
0...125 to 0...600 A AC	SCT2121 accuracy class 0.5				
0...600/ 0...750 A AC		SCT2211 accuracy class 1			
		SCT2221 accuracy class 0.5			
0...800/ 0...1000 A AC			SCT2311 accuracy class 1	SCT2321 accuracy class 0.5	
0...1250/ 0...1500 A AC			SCT2411 accuracy class 1	SCT2421 accuracy class 0.5	
0...2000 A AC				SCT2515 accuracy class 1	
				SCT2525 accuracy class 0.5	
0...2500 A AC					SCT2615 accuracy class 1
					SCT2625 accuracy class 0.5



SCT32xx



SCT4xxx



SCT5564

SCT3xxx 3-phase ring-type current transformers			
Primary current	Max. diameter round conductor		
	13.5 mm	18 mm	22 mm
0...50 to 0...150 A AC	SCT3111 accuracy class 1		
0...125/ 0...150 A AC	SCT3121 accuracy class 0.5		
0...100 to 0...250 A AC		SCT3215 accuracy class 1	
0...250 to 0...600 A AC			SCT3315 accuracy class 1

SCT4xxx Differential current transformers, type A						
Primary current	Max. diameter round conductor					
	20 mm	35 mm	50 mm	60 mm	80 mm	120 mm
0...18 A AC	SCT4616-0018 split-core current transformer		SCT4716-0018 split-core current transformer		SCT4816-0018 split-core current transformer	
0...25 A AC	SCT4116-0025 ring-type current transformer	SCT4216-0025 ring-type current transformer		SCT4316-0025 ring-type current transformer		SCT4416-0025 ring-type current transformer

SCT5xxx Differential current transformers	
Primary current	Diameter transformer opening 70 mm
0...100 and 0...300 A	SCT5564 residual current measuring range 0.4 A or 2 A



SCT6xxx | Split-core current transformers

Primary current	Max. diameter round conductor				
	18.5 mm	27.9 mm	42.4 mm	2 x 42.4 mm	
0...60 to 0...150 A AC	SCT6101 accuracy class 3				
0...200/ 0...250 A AC	SCT6311 accuracy class 1	SCT6321 accuracy class 0.5			
0...300 to 0...500 A AC		SCT6411 accuracy class 1			
0...400/ 0...500 A AC		SCT6421 accuracy class 0.5			
0...600/ 0...750 A AC			SCT6615 accuracy class 1	SCT6625 accuracy class 0.5	
0...800/ 0...1000 A AC				SCT6715 accuracy class 1	SCT6725 accuracy class 0.5

SCT7xxx | Busbar split-core current transformers

Primary current	Max. diameter round conductor			
	20 mm		50 mm	80 mm
0...100/ 0...200 A AC	SCT7105 accuracy class 3			
0...250/ 0...400 A AC	SCT7115 accuracy class 1			
0...400 A AC	SCT7125 accuracy class 2			
0...500/ 0...600 A AC		SCT7215 accuracy class 1	SCT7225 accuracy class 2	
0...750 to 0...1500 A AC			SCT7315 accuracy class 1	SCT7325 accuracy class 2
0...1500/ 0...5000 A AC			SCT7415 accuracy class 1	SCT7425 accuracy class 2

SCT0xxx | Coil current transformers

Primary current	Primary conductor for connection	
0...1 to 0...30 A AC	SCT0111 accuracy class 1	SCT0121 accuracy class 0.5



SCL6xxx | Low power split-core transformer

Current range	Transformer opening			
	9.7 mm	6 mm	12 mm	24 mm
10 A			SCL6223-0010 10 A AC	i
15 A	SCL6023-0015 15 A AC	i		
20 A		SCL6123-0020 20 A AC	i	
30 A	SCL6023-0030 30 A AC	i		
40 A		SCL6123-0040 40 A AC	i	
60 A	SCL6023-0060 60 A AC	i	SCL6123-0060 60 A AC	i
75 A	SCL6023-0075 75 A AC	i		
80 A			SCL6223-0080 80 A AC	i
100 A			SCL6223-0100 100 A AC	i SCL6323-0100 100 A AC
200 A				SCL6323-0200 200 A AC
400 A				SCL6323-0400 400 A AC

SVL1xxx | Low power voltage transformer

Measuring voltage	
110 V AC	SVL1123 66 V U _N , 110 V U _L
400 V AC	SVL1323 277 V U _N , 480 V U _L
690 V AC	SVL1423 400 V U _N , 690 V U _L

Power supplies

► www.beckhoff.com/ps



PS1000 Power supplies				
Output current	Output voltage			
	24 V DC (1-phase)	48 V DC (1-phase)	24 V DC (3-phase)	48 V DC (3-phase)
2.5 A	PS1111-2402-0002 24 V DC, 2.5 A DC, 1-phase			
3.8 A	PS1111-2403-0000 24 V DC, 3.8 A DC, 1-phase, NEC			
	PS1111-2403-0002 24 V DC, 3.8 A DC, 1-phase			
5 A	PS1061-2405-0000 24 V DC, 5 A DC, 1-phase, AC 200...240 V			
	PS1021-2405-0000 24 V DC, 5 A DC, 1-phase			
10 A	PS1061-2410-0000 24 V DC, 10 A DC, 1-phase, AC 200...240 V			
	PS1011-2410-0000 24 V DC, 10 A DC, 1-phase			
20 A	PS1061-2420-0000 24 V DC, 20 A DC, 1-phase, AC 200...240 V			
	PS1011-2420-0000 24 V DC, 20 A DC, 1-phase			

PS2000 Power supplies				
Output current	Output voltage			
	24 V DC (1-phase)	48 V DC (1-phase)	24 V DC (3-phase)	48 V DC (3-phase)
5 A	PS2001-2405-0000 24 V DC, 5 A DC, 1-phase			
10 A	PS2001-2410-0000 24 V DC, 10 A DC, 1-phase	PS2001-4810-0000 48 V DC, 10 A DC, 1-phase	PS2031-2410-0000 24 V DC, 10 A DC, 3-phase	
20 A	PS2001-2420-0000 24 V DC, 20 A DC, 1-phase			

PS2000 Power supplies with EtherCAT				
Output current	Output voltage			
	24 V DC (1-phase)	48 V DC (1-phase)	24 V DC (3-phase)	48 V DC (3-phase)
10 A	PS2001-2410-1001 24 V DC, 10 A DC, 1-phase, EtherCAT	PS2001-4810-1001 48 V DC, 10 A DC, 1-phase, EtherCAT		
20 A	PS2001-2420-1001 24 V DC, 20 A DC, 1-phase, EtherCAT			

PS3000 Power supplies				
Output current	Output voltage			
	24 V DC (1-phase)	48 V DC (1-phase)	24 V DC (3-phase)	48 V DC (3-phase)
10 A	PS3001-2410-0001 24 V DC, 10 A DC, 1-phase			PS3031-4810-0001 48 V DC, 10 A DC, 3-phase
20 A	PS3001-2420-0001 24 V DC, 20 A DC, 1-phase	PS3011-4820-0000 48 V DC, 20 A DC, 1-phase	PS3031-2420-0001 24 V DC, 20 A DC, 3-phase	PS3031-4820-0000 48 V DC, 20 A DC, 3-phase
40 A	PS3011-2440-0000 24 V DC, 40 A DC, 1-phase		PS3031-2440-0000 24 V DC, 40 A DC, 3-phase	

PS9000 Buffer modules		
Output current	Input voltage	
	24 V DC	48 V DC
20 A	PS9011-2420-0001 24 V DC, 20 A, 200 ms	PS9031-4820-0001 48 V DC, 20 A, 100 ms
40 A	PS9011-2440-0000 24 V DC, 40 A, 160 ms	

PS9400 Redundancy modules		
Output current	Input voltage	
	12...28 V DC	24...56 V DC
20 A	PS9401-2420-0000 In: 2 x 10 A	
40 A	PS9401-2440-0000 In: 2 x 20 A	PS9421-4840-0000 In: 2 x 20 A

PS9700 DC/DC converter			
Output current	Input voltage		
	18...36 V DC	36...60 V DC	475...750 V DC
10 A	PS9711-2410-0000 24 V DC, 10 A	PS9731-2410-0000 24 V DC, 10 A	
40 A			PS9771-2440-0000 24 V DC, 40 A

The Motion Company

In combination with the motion control solutions offered by the company's TwinCAT automation software, Beckhoff Drive Technology provides an advanced, all-inclusive drive system. PC-based control technology from Beckhoff is ideally suited for single- and multi-axis positioning tasks with high dynamic requirements.

The servo drive series with high-performance EtherCAT communication offer the best-possible performance and dynamics. Servomotors with One Cable Technology (OCT), combining power and feedback systems into one standard motor cable, reduce material and commissioning costs.

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Intelligent linear product transport 98

- linear motor on an endless path
- replaces traditional mechanics with advanced mechatronic solutions
- software-based functional changes
- individual product transport with continuous material flow

► www.beckhoff.com/xts



XTS®

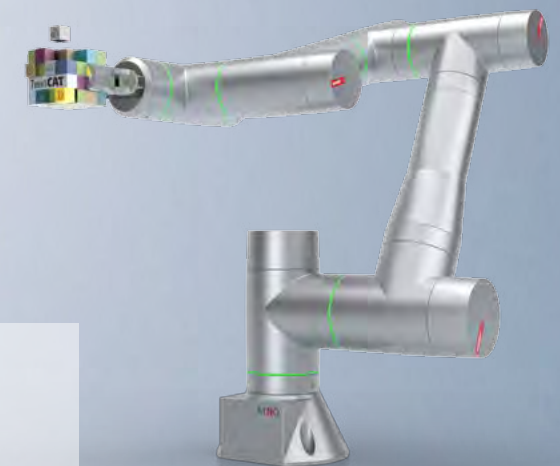


XPlanar®

Planar motor system 97

- free-floating movers for non-contact movement
- 6 degrees of freedom
- integrated position feedback
- individual machine layout
- ideal for all application areas

► www.beckhoff.com/xplanar



ATRO®

ATRO: Automation Technology for Robotics

- modular industrial robot system
- limitless combinations due to easily pluggable motor and link modules
- endlessly rotating axes due to internal media feed
- complete integration into the control platform
- standardized interfaces

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Economy drive system 82

- optimized price/performance ratio
 - takes up minimal space in the control cabinet and machine due to compact designs
 - available as a single-axis or highly cost-effective dual-axis version
 - convenient design, commissioning, and diagnostics with TwinCAT
- www.beckhoff.com/economy-drive-system

Servo drives 83

- available as multi-axis system, stand-alone or economy version (1-/2-channel)
- high-speed EtherCAT communication
- nominal current types, up to 170 A
- flexible motor type selection
- optimized for multi-axis applications
- 17 drive-integrated safety functions

► www.beckhoff.com/servo-drives

Distributed drive systems 84

- servo drives directly integrated into the motor
- STO/SS1 safety function or Safe Motion available
- minimal derating
- no changes in machine design required

► www.beckhoff.com/distributed-drive-systems

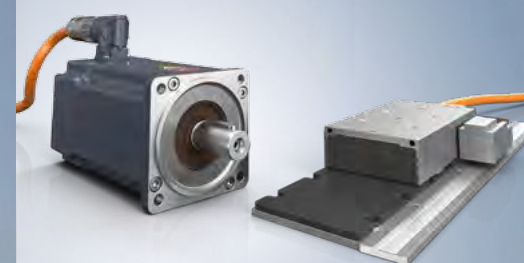
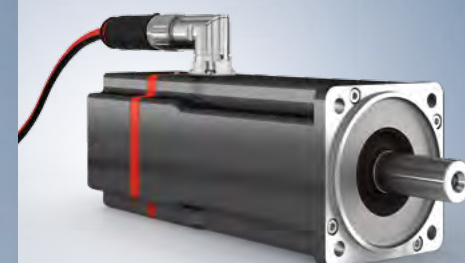
Servomotors 86

- for demanding positioning tasks
- highly dynamic behavior
- maximum speed
- optimum force density

► www.beckhoff.com/rotary-servomotors
 ► www.beckhoff.com/translatory-servomotors

Compact drive technology 92

- high performance in small design
 - motors and output stages for the < 48 V DC low voltage range
 - servo, BLDC, stepper and DC motor output stages in IP20 or IP67
 - servo and stepper motor drive with integrated output stage
- www.beckhoff.com/compact-drive-technology



- scalable product range of servo drive technology
- integrated safety technology in compliance with safety performance level PL e, integrated into compact drive technology up to safety performance level PL d
- As the pioneer of One Cable Technology and the eXtended Transport System, Beckhoff specializes in manufacturing efficient, space-saving motion solutions.

Economy drive system

► www.beckhoff.com/economy-drive-system



AF1000



AX1000



AM1000

AF1000 | Economy variable frequency drives

Rated supply voltage	1-channel			2-channel		
1 x 110...240 V AC	AF1103-1xxx  single-axis module, 1 x 110...240 V AC, 0.37 kW	AF1107-1xxx  single-axis module, 1 x 110...240 V AC, 0.75 kW	AF1115-1xxx  single-axis module, 1 x 110...240 V AC, 1.5 kW	AF1203-1xxx  dual-axis module, 1 x 110...240 V AC, 0.37 kW	AF1207-1xxx  dual-axis module, 1 x 110...240 V AC, 0.75 kW	
3 x 208...480 V AC		AF1107-3xxx  single-axis module, 3 x 208...480 V AC, 0.75 kW	AF1115-3xxx  single-axis module, 3 x 208...480 V AC, 1.5 kW		AF1207-3xxx  dual-axis module, 3 x 208...480 V AC, 0.75 kW	AF1215-3xxx  dual-axis module, 3 x 208...480 V AC, 1.5 kW
		AF1130-3xxx  single-axis module, 3 x 208...480 V AC, 3 kW	AF1155-3xxx  single-axis module, 3 x 208...480 V AC, 5.5 kW		AF1222-3xxx  dual-axis module, 3 x 208...480 V AC, 2.2 kW	

AX1000 | Economy servo drives

Rated supply voltage	1-channel			2-channel		
1 x 110...240 V AC	AX1101-1xxx  single-axis module, 1 x 110...240 V AC, 1.65 A	AX1103-1xxx  single-axis module, 1 x 110...240 V AC, 3.4 A	AX1106-1xxx  single-axis module, 1 x 110...240 V AC, 6.9 A	AX1201-1xxx  dual-axis module, 1 x 110...240 V AC, 2 x 1.65 A	AX1203-1xxx  dual-axis module, 1 x 110...240 V AC, 2 x 3.4 A	
3 x 208...480 V AC		AX1103-3xxx  single-axis module, 3 x 208...480 V AC, 3.4 A	AX1106-3xxx  single-axis module, 3 x 208...480 V AC, 6.9 A	AX1112-3xxx  single-axis module, 3 x 208...480 V AC, 12 A	AX1203-3xxx  dual-axis module, 3 x 208...480 V AC, 2 x 3 A	AX1206-3xxx  dual-axis module, 3 x 208...480 V AC, 2 x 6 A

AM1000 | Economy servomotors

Flange code	Motor length 1	Motor length 2	Motor length 3
I1 (40 mm)	AM1011  M ₀ = 0.17 Nm, 0.05 kW, nn = 3000 min ⁻¹	AM1012  M ₀ = 0.33 Nm, 0.10 kW, nn = 3000 min ⁻¹	
I2 (60 mm)	AM1021  M ₀ = 0.64 Nm, 0.20 kW, nn = 3000 min ⁻¹	AM1022  M ₀ = 1.34 Nm, 0.40 kW, nn = 3000 min ⁻¹	
I3 (80 mm)	AM1031  M ₀ = 1.83 Nm, 0.55 kW, nn = 3000 min ⁻¹	AM1032  M ₀ = 2.46 Nm, 0.75 kW, nn = 3000 min ⁻¹	AM1033  M ₀ = 3.18 Nm, 1.00 kW, nn = 3000 min ⁻¹

Servo drives

► www.beckhoff.com/servo-drives



AX8000



AX5000



AX8000 | Multi-axis servo system

Function				
Power supply modules	AX8620 20 A DC	AX8640 40 A DC		
Power supply module DC	AX8600 50 A DC, for supply voltage 24...680 V DC			
Axis modules	AX8108 single-axis module 8 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AX8118 single-axis module 18 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AX8128 single-axis module 28 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AX8206 dual-axis module 2 x 6 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion
Combined power supply and axis modules	AX8525 combined power supply and axis module 25 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AX8540 combined power supply and axis module 40 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion		
Option modules	AX8810 capacitor module	AX8820 universal regenerative unit	AX8831 coupling module, 1-channel	AX8832 coupling module with two outputs

AX5000 | Digital compact servo drives

Function	1-channel						2-channel		
Servo drives	AX5101 100...480 V AC, 1.5 A	AX5103 100...480 V AC, 3 A	AX5106 100...480 V AC, 6 A	AX5112 100...480 V AC, 12 A		AX5201 100...480 V AC, 2 x 1.5 A		AX5203 100...480 V AC, 2 x 3 A	AX5206 100...480 V AC, 2 x 6 A
	AX5118 100...480 V AC, 18 A	AX5125 100...480 V AC, 25 A	AX5140 100...480 V AC, 40 A						
	AX5160 3 x 400...480 V AC, 60 A	AX5172 3 x 400...480 V AC, 72 A	AX5190 3 x 400...480 V AC, 90 A	AX5191 3 x 400...480 V AC, 110 A	AX5192 3 x 400...480 V AC, 143 A	AX5193 3 x 400...480 V AC, 170 A			
Encoder option cards	AX5701 EnDat® 2.1, Hiperface, BiSS® B, SinCos 1 V _{pp}	AX5721 1 x EnDat® 2.2, BiSS® C					AX5702 EnDat® 2.1, Hiperface, BiSS® B, SinCos 1 V _{pp}	AX5722 2 x EnDat® 2.2, BiSS® C	
TwinSAFE safe drive technology	AX5801 drive-integrated safety functions: STO, SS1	AX5805 drive-integrated safety functions: Safe Motion, for AX5x01 to AX5140	AX5806 drive-integrated safety functions: Safe Motion, for AX5160 to AX5193						
Option module	AX8820 universal regenerative unit								

Distributed drive systems

► www.beckhoff.com/distributed-drive-systems



AMP8000 Distributed servo drives (400 V AC)				
Flange code	Motor length 1	Motor length 2	Motor length 3	Motor length 4
F3 (72 mm)	AMP8031 M ₀ = 1.36...1.38 Nm, nn = 3000...9000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8032 M ₀ = 2.35...2.37 Nm, nn = 3000...9000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8033 M ₀ = 3.10...3.15 Nm, nn = 3000...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	
F4 (87 mm)	AMP8041 M ₀ = 2.35...2.40 Nm, nn = 3000...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8042 M ₀ = 3.84...4.10 Nm, nn = 2500...7000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8043 M ₀ = 4.70...5.40 Nm, nn = 2500...7000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	
F5 (104 mm)	AMP8051 M ₀ = 4.40...4.60 Nm, nn = 2500...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8052 M ₀ = 5.60...7.60 Nm, nn = 2000...7300 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8053 M ₀ = 9.60...10.20 Nm, nn = 2000...4000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8054 M ₀ = 11.8 Nm, nn = 2000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion

AMP8500 Distributed servo drives with increased rotor moment of inertia (400 V AC)			
Flange code	Motor length 1	Motor length 2	Motor length 3
F3 (72 mm)	AMP8531 M ₀ = 1.36...1.38 Nm, nn = 3000...9000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8532 M ₀ = 2.35...2.37 Nm, nn = 3000...9000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8533 M ₀ = 3.10...3.15 Nm, nn = 3000...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion
F4 (87 mm)	AMP8541 M ₀ = 2.35...2.40 Nm, nn = 3000...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8542 M ₀ = 3.84...4.10 Nm, nn = 2500...7000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8543 M ₀ = 4.70...5.40 Nm, nn = 2500...7000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion
F5 (104 mm)	AMP8551 M ₀ = 4.40...4.60 Nm, nn = 2500...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8552 M ₀ = 5.60...7.60 Nm, nn = 2000...7300 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	AMP8553 M ₀ = 9.60...10.20 Nm, nn = 2000...4000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion



AMI8100,
rear view



ASI8100,
rear view

AMP8600 Distributed power supply modules			
Function			
Supply modules	AMP8620-2005-0000 20 A DC for 400...480 V AC supply voltage, 5-channel, 24 V DC power supply	AMP8620-2005-0100 20 A DC for 400...480 V AC supply voltage, 5-channel, 24 V DC power supply, with regen resistor	AMP8620-2005-0200 20 A DC for 400...480 V AC supply voltage, 5-channel, 24 V DC power supply, with connector for regen resistor
	AMP8620-2005-0010 20 A DC for 1 x 120...240 V AC, 3 x 200...480 V AC supply voltage, 5-channel, 24 V DC power supply	AMP8620-2005-0110 20 A DC for 1 x 120...240 V AC, 3 x 200...480 V AC supply voltage, 5-channel, 24 V DC power supply, with regen resistor	AMP8620-2005-0210 20 A DC for 1 x 120...240 V AC, 3 x 200...480 V AC supply voltage, 5-channel, 24 V DC power supply, with connector for regen resistor
AMP8800 Decentralized distribution modules			
Function			
Distribution modules	AMP8805-1000-0000 5-channel, 24 V DC power supply, 430...848 V DC	AMP8805-1010-0000 5-channel, 24 V DC power supply, 155...848 V DC	

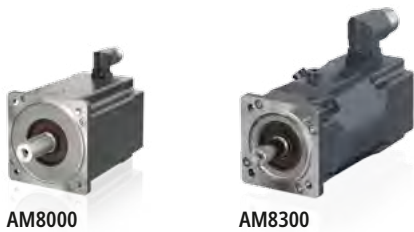
AX8800 Coupling modules		
Function	1-channel	2-channel
Coupling modules	AX8831	AX8832

AMI8100 Compact integrated servo drives (48 V DC)			
Flange code	Motor length 1	Motor length 2	Motor length 3
F2 (58 mm)	AMI8121 M ₀ = 0.48 Nm, nn = 3000 min ⁻¹	AMI8122 M ₀ = 0.78 Nm, nn = 2000...4500 min ⁻¹	AMI8123 M ₀ = 1.00 Nm, nn = 3000 min ⁻¹
F3 (72 mm)	AMI8131 M ₀ = 1.20 Nm, nn = 1800 min ⁻¹	AMI8132 M ₀ = 2.18 Nm, nn = 1000 min ⁻¹	AMI8133 M ₀ = 2.85 Nm, nn = 800 min ⁻¹

ASI8100 Compact integrated stepper motor drives (48 V DC)				
Flange code	Motor length 1	Motor length 2	Motor length 3	Motor length 4
N1 (42 mm)	ASI8111 M _H = 0.29 Nm	ASI8114 M _H = 0.80 Nm		
N2 (56 mm)	ASI8121 M _H = 0.75 Nm	ASI8122 M _H = 1.40 Nm	ASI8123 M _H = 2.35 Nm	ASI8124 M _H = 2.50 Nm

Rotary servomotors

► www.beckhoff.com/rotary-servomotors



AM8000 Servomotors				
Flange code	Motor length 1	Motor length 2	Motor length 3	Motor length 4
F1 (40 mm)	AM8011 M ₀ = 0.20 Nm, nn = 8000 min ⁻¹	AM8012 M ₀ = 0.38 Nm, nn = 8000 min ⁻¹	AM8013 M ₀ = 0.52 Nm, nn = 8000 min ⁻¹	
F2 (58 mm)	AM8021 M ₀ = 0.50 Nm, nn = 8000...9000 min ⁻¹	AM8022 M ₀ = 0.80 Nm, nn = 8000...9000 min ⁻¹	AM8023 M ₀ = 1.20 Nm, nn = 8000...9000 min ⁻¹	
F3 (72 mm)	AM8031 M ₀ = 1.37...1.40 Nm, nn = 3000...9000 min ⁻¹	AM8032 M ₀ = 2.37...2.38 Nm, nn = 3000...9000 min ⁻¹	AM8033 M ₀ = 3.20...3.22 Nm, nn = 3000...9000 min ⁻¹	
F4 (87 mm)	AM8041 M ₀ = 2.37...2.45 Nm, nn = 3000...8000 min ⁻¹	AM8042 M ₀ = 4.10 Nm, nn = 2500...8000 min ⁻¹	AM8043 M ₀ = 5.60...5.65 Nm, nn = 2500...8000 min ⁻¹	AM8044 M ₀ = 7.10 Nm, nn = 2500...5000 min ⁻¹
F5 (104 mm)	AM8051 M ₀ = 4.80...6.30 Nm, nn = 2500...8000 min ⁻¹	AM8052 M ₀ = 8.20...10.7 Nm, nn = 2000...7300 min ⁻¹	AM8053 M ₀ = 11.4...15.4 Nm, nn = 2000...7000 min ⁻¹	AM8054 M ₀ = 13.8...17.2 Nm, nn = 2000...4000 min ⁻¹
F6 (142 mm)	AM8061 M ₀ = 12.8...17.1 Nm, nn = 1400...5000 min ⁻¹	AM8062 M ₀ = 21.1...29.9 Nm, nn = 1400...5000 min ⁻¹	AM8063 M ₀ = 29.0...41.4 Nm, nn = 1400...4000 min ⁻¹	AM8064 M ₀ = 35.0...49.0 Nm, nn = 1500...4000 min ⁻¹
F7 (197 mm)	AM8071 M ₀ = 31.8...42.8 Nm, nn = 1500...4000 min ⁻¹	AM8072 M ₀ = 54.6...80.7 Nm, nn = 1000...3000 min ⁻¹	AM8073 M ₀ = 70.0...104 Nm, nn = 1000...3000 min ⁻¹	AM8074 M ₀ = 92.0...129 Nm, nn = 1000...3000 min ⁻¹

AM8300 Servomotors with water cooling			
Flange code	Motor length 2	Motor length 3	Motor length 4
F3 (72 mm)	AM8332 M ₀ = 5.02...5.60 Nm, nn = 2200...8500 min ⁻¹	AM8333 M ₀ = 7.53...8.40 Nm, nn = 2300...8000 min ⁻¹	
F4 (87 mm)	AM8342 M ₀ = 10.9 Nm, nn = 1700...6000 min ⁻¹	AM8343 M ₀ = 14.8...16.3 Nm, nn = 1700...7000 min ⁻¹	AM8344 M ₀ = 22.3 Nm, nn = 1900...3700 min ⁻¹
F5 (104 mm)	AM8352 M ₀ = 19.2 Nm, nn = 1600...6300 min ⁻¹	AM8353 M ₀ = 28.8 Nm, nn = 1700...6300 min ⁻¹	AM8354 M ₀ = 33.1...38.4 Nm, nn = 1800...6500 min ⁻¹
F6 (142 mm)	AM8362 M ₀ = 43.9...49.8 Nm, nn = 1200...4000 min ⁻¹	AM8363 M ₀ = 60.6...74.7 Nm, nn = 1200...4900 min ⁻¹	AM8364 M ₀ = 98.1...99.6 Nm, nn = 1200...2500 min ⁻¹
F7 (197 mm)	AM8372 M ₀ = 129...130 Nm, nn = 850...3000 min ⁻¹	AM8373 M ₀ = 194...195 Nm, nn = 850...3000 min ⁻¹	AM8374 M ₀ = 219...259 Nm, nn = 750...2500 min ⁻¹



AM8500 Servomotors with increased rotor moment of inertia			
Flange code	Motor length 1	Motor length 2	Motor length 3
F3 (72 mm)	AM8531 M ₀ = 1.37...1.40 Nm, nn = 3000...9000 min ⁻¹	AM8532 M ₀ = 2.37...2.38 Nm, nn = 3000...9000 min ⁻¹	AM8533 M ₀ = 3.20...3.22 Nm, nn = 3000...9000 min ⁻¹
F4 (87 mm)	AM8541 M ₀ = 2.37...2.45 Nm, nn = 3000...8000 min ⁻¹	AM8542 M ₀ = 4.10 Nm, nn = 2500...8000 min ⁻¹	AM8543 M ₀ = 5.60...5.65 Nm, nn = 2500...8000 min ⁻¹
F5 (104 mm)	AM8551 M ₀ = 4.80...6.30 Nm, nn = 2500...8000 min ⁻¹	AM8552 M ₀ = 8.20...10.7 Nm, nn = 2000...7300 min ⁻¹	AM8553 M ₀ = 11.4...15.4 Nm, nn = 2000...7000 min ⁻¹
F6 (142 mm)	AM8561 M ₀ = 12.8...17.1 Nm, nn = 1400...5000 min ⁻¹	AM8562 M ₀ = 21.1...29.9 Nm, nn = 1400...5000 min ⁻¹	AM8563 M ₀ = 29.0...41.1 Nm, nn = 1400...4000 min ⁻¹

AM8700 Servomotors with anodized housing			
Flange code	Motor length 1	Motor length 2	Motor length 3
R2 (77 mm)	AM8721 M ₀ = 0.5 Nm, nn = 8000 min ⁻¹	AM8722 M ₀ = 0.8 Nm, nn = 8000 min ⁻¹	AM8723 M ₀ = 1.2 Nm, nn = 8000 min ⁻¹
R3 (89 mm)	AM8731 M ₀ = 1.38 Nm, nn = 6000 min ⁻¹	AM8732 M ₀ = 2.37 Nm, nn = 6000 min ⁻¹	AM8733 M ₀ = 3.22 Nm, nn = 6000 min ⁻¹
R4 (114 mm)	AM8741 M ₀ = 2.45 Nm, nn = 6000 min ⁻¹	AM8742 M ₀ = 4.10 Nm, nn = 5000 min ⁻¹	AM8743 M ₀ = 5.65 Nm, nn = 5000 min ⁻¹
R5 (134 mm)	AM8751 M ₀ = 4.90 Nm, nn = 5000 min ⁻¹	AM8752 M ₀ = 8.20 Nm, nn = 4000 min ⁻¹	AM8753 M ₀ = 11.4 Nm, nn = 4000 min ⁻¹
R6 (189 mm)	AM8761 M ₀ = 12.8 Nm, nn = 3000 min ⁻¹	AM8762 M ₀ = 21.1 Nm, nn = 3000 min ⁻¹	AM8763 M ₀ = 29.0 Nm, nn = 3000 min ⁻¹

AM8800 Stainless steel servomotors in hygienic design			
Flange code	Motor length 1	Motor length 2	Motor length 3
R3 (89 mm)	AM8831 M ₀ = 0.85 Nm, nn = 3000 min ⁻¹	AM8832 M ₀ = 1.40 Nm, nn = 3000 min ⁻¹	AM8833 M ₀ = 1.85 Nm, nn = 3000 min ⁻¹
R4 (114 mm)	AM8841 M ₀ = 1.60 Nm, nn = 3000 min ⁻¹	AM8842 M ₀ = 2.60 Nm, nn = 2500 min ⁻¹	AM8843 M ₀ = 3.50 Nm, nn = 2500 min ⁻¹
R5 (134 mm)	AM8851 M ₀ = 3.10 Nm, nn = 2500 min ⁻¹	AM8852 M ₀ = 4.80 Nm, nn = 2000 min ⁻¹	AM8853 M ₀ = 6.40 Nm, nn = 2000 min ⁻¹
R6 (189 mm)	AM8861 M ₀ = 7.75 Nm, nn = 1500 min ⁻¹	AM8862 M ₀ = 13.1 Nm, nn = 1500 min ⁻¹	AM8863 M ₀ = 16.7 Nm, nn = 1500 min ⁻¹

Planetary gear units

► www.beckhoff.com/planetary-gears



AG2300



AG2400



AG2800



AG3210



AG3300



AG3400

AG2300 High-end planetary gear units with output shaft	
Sizes	Straight design
SP060	AG2300-+SP060S nominal output torque 21...40 Nm
SP075	AG2300-+SP075S nominal output torque 41...106 Nm
SP100	AG2300-+SP100S nominal output torque 76...277 Nm
SP140	AG2300-+SP140S nominal output torque 127...581 Nm
SP180	AG2300-+SP180S nominal output torque 289...1162 Nm
SP210	AG2300-+SP210S nominal output torque 728...2200 Nm
SP240	AG2300-+SP240S nominal output torque 1344...3784 Nm

AG2400 High-end planetary gear units with output flange	
Sizes	Straight design
TP004	AG2400-+TP004S nominal output torque 26...48 Nm
TP010	AG2400-+TP010S nominal output torque 77...126 Nm
TP025	AG2400-+TP025S nominal output torque 169...304 Nm
TP050	AG2400-+TP050S nominal output torque 316...607 Nm
TP110	AG2400-+TP110S nominal output torque 861...1408 Nm
TP300	AG2400-+TP300S nominal output torque 1354...2353 Nm
TP500	AG2400-+TP500S nominal output torque 2800...4400 Nm

AG2800 Planetary gear units in hygienic design	
Sizes	Straight design
HDV015	AG2800-+HDV015S nominal output torque 15...16 Nm
HDV025	AG2800-+HDV025S nominal output torque 35...40 Nm
HDV035	AG2800-+HDV035S nominal output torque 90...100 Nm

AG3210 Economy planetary gear units	
Sizes	Straight design
NP005	AG3210-+NP005S nominal output torque 5.1...6.5 Nm
NP015	AG3210-+NP015S nominal output torque 17...21 Nm
NP025	AG3210-+NP025S nominal output torque 40...50 Nm
NP035	AG3210-+NP035S nominal output torque 100...130 Nm
NP045	AG3210-+NP045S nominal output torque 200...350 Nm

AG3300 Economy planetary gear units	
Sizes	Straight design
NPS015	AG3300-+NPS015S nominal output torque 17...21 Nm
NPS025	AG3300-+NPS025S nominal output torque 40...50 Nm
NPS035	AG3300-+NPS035S nominal output torque 100...130 Nm
NPS045	AG3300-+NPS045S nominal output torque 200...350 Nm

AG3400 Economy planetary gear units with output flange	
Sizes	Straight design
NPT005	AG3400-+NPT005S nominal output torque 5.1...6.5 Nm
NPT015	AG3400-+NPT015S nominal output torque 17...21 Nm
NPT025	AG3400-+NPT025S nominal output torque 40...50 Nm
NPT035	AG3400-+NPT035S nominal output torque 100...130 Nm
NPT045	AG3400-+NPT045S nominal output torque 200...350 Nm

Translatory servomotors

► www.beckhoff.com/translatory-servomotors



AL8000

AL8000 Highly dynamic linear servomotors			
Peak force	Overall width W2 (50 mm)	Overall width W4 (80 mm)	Overall width W6 (130 mm)
≤ 500 N	AL8021 F _{max} = 120 N, I _{max} = 7.3 A, V _{max} = 12 m/s	AL8041 F _{max} = 230 N, I _{max} = 7.2 A, V _{max} = 7 m/s	
	AL8022 F _{max} = 240 N, I _{max} = 7.3 A, V _{max} = 12 m/s	AL8042 F _{max} = 460 N, I _{max} = 7.2 A, V _{max} = 7 m/s	
	AL8024 F _{max} = 480 N, I _{max} = 12 A, V _{max} = 12 m/s		
> 500... 1500 N	AL8026 F _{max} = 720 N, I _{max} = 12 A, V _{max} = 10 m/s	AL8043 F _{max} = 690 N, I _{max} = 7.2/12 A, V _{max} = 3.5/7 m/s	
		AL8044 F _{max} = 920 N, I _{max} = 7.2/15 A, V _{max} = 3.5/7 m/s	
		AL8045 F _{max} = 1150 N, I _{max} = 12/24 A, V _{max} = 3.5/7 m/s	
		AL8046 F _{max} = 1380 N, I _{max} = 12/24 A, V _{max} = 3.5/7 m/s	
> 1500 N		AL8048 F _{max} = 1840 N, I _{max} = 15/29 A, V _{max} = 3.5/7 m/s	AL8064 F _{max} = 1800 N, I _{max} = 12/24 A, V _{max} = 3/6 m/s
			AL8065 F _{max} = 2250 N, I _{max} = 15/24 A, V _{max} = 3/6 m/s
			AL8066 F _{max} = 2700 N, I _{max} = 18/42 A, V _{max} = 3/6 m/s
			AL806A F _{max} = 4500 N, I _{max} = 24/72 A, V _{max} = 3/6 m/s
			AL806B F _{max} = 4950 N, I _{max} = 29 A, V _{max} = 3 m/s
			AL806F F _{max} = 6750 N, I _{max} = 42/100 A, V _{max} = 3/6 m/s

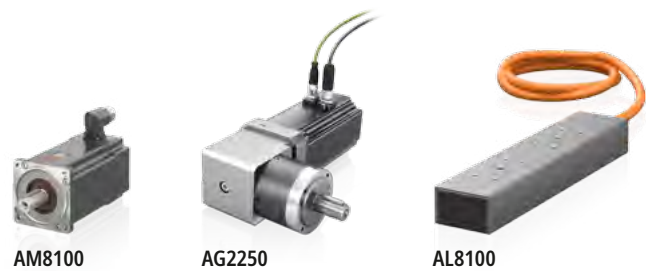


AA3000

AA3000 Electric cylinders (400 V AC)			
Peak force	Flange code 58 mm	Flange code 75 mm	Flange code 110 mm
3125... 6250 N	AA3023 F _C = 700/1400 N		
6250... 12,500 N		AA3033 F _C = 1850/3700 N	
12,500... 25,000 N			AA3053 F _C = 3200/6400 N

Compact drive technology

► www.beckhoff.com/compact-drive-technology



AM8100 Servomotors for compact drive technology			
Flange code	Motor length 1	Motor length 2	Motor length 3
F1 (40 mm)	AM8111 M₀ = 0.20 Nm, nn = 4000 min⁻¹	AM8112 M₀ = 0.38 Nm nn = 4500 min⁻¹	AM8113 M₀ = 0.52 Nm, nn = 3000 min⁻¹
F2 (58 mm)	AM8121 M₀ = 0.50 Nm, nn = 3000...6000 min⁻¹	AM8122 M₀ = 0.80 Nm, nn = 2000...8000 min⁻¹	AM8123 M₀ = 1.20 Nm, nn = 5000 min⁻¹
F3 (72 mm)	AM8131 M₀ = 1.30...1.35 Nm, nn = 1000...4000 min⁻¹	AM8132 M₀ = 2.37...2.40 Nm, nn = 1000...2500 min⁻¹	AM8133 M₀ = 3.20 Nm, nn = 2000 min⁻¹
F4 (87 mm)	AM8141 M₀ = 2.40 Nm, nn = 1000...2500 min⁻¹	AM8142 M₀ = 3.90 Nm, nn = 1500 min⁻¹	

AG2250 Planetary gear units for servo and stepper motors		
Sizes	Straight design	Angled design
PLE40	AG2250-+PLE40 nominal output torque 5...20 Nm	
PLE60	AG2250-+PLE60 nominal output torque 15...64 Nm	
PLE80	AG2250-+PLE80 nominal output torque 38...120 Nm	
WPLE40		AG2250-+WPLE40 nominal output torque 4.5...20 Nm
WPLE60		AG2250-+WPLE60 nominal output torque 14...64 Nm
WPLE80		AG2250-+WPLE80 nominal output torque 38...120 Nm

AL8100 Highly dynamic linear servomotors for compact drive technology			
Peak force	Overall width W2 (50 mm)		
≤ 500 N	AL8121 F_{max} = 100 N, I_{max} = 5.6...9.0 A, V_{max} = 2.5...4.5 m/s	AL8122 F_{max} = 170...220 N, I_{max} = 5.6...32 A, V_{max} = 1.3...6 m/s	AL8124 F_{max} = 440 N, I_{max} = 16...32 A, V_{max} = 1.7...3.5 m/s
> 500... 1500 N	AL8126 F_{max} = 650 N, I_{max} = 32 A, V_{max} = 2.3 m/s		



ASxxxx Stepper motors							
Flange code	Rated current (per phase)						
	1.00 A	1.50 A	2.00 A	5.00 A	5.60 A	6.50 A	5.60 A 6.40 A
N1 (NEMA17/ 42 mm)	AS1010 0.40 Nm						
	AS1020 0.5 Nm						
N2 (NEMA23/ 56 mm)		AS1030 0.6 Nm	AS2021 0.8 Nm		AS2022 1.50 Nm		AS2023 1.8 Nm 2.3 Nm
N3 (NEMA34/ 86 mm)				AS1050 1.2 Nm	AS2041 3.3 Nm	AS2043 8.0 Nm	
				AS1060 5.0 Nm	AS2042 6.4 Nm		

AG1000 Planetary gear units for AS1000 stepper motors	
Sizes	Straight design
PM52	AG1000-+PM52.i nominal output torque 4 Nm
PM81	AG1000-+PM81.i nominal output torque 20 Nm

AA3100 Electric cylinders (48 V DC)		
Peak force	Flange code 58 mm	Flange code 75 mm
2650... 5300 N	AA3123 F_c = 650/1300 N	
6000... 12,000 N		AA3133 F_c = 1400/2800 N



EtherCAT Terminals

ED7xxx EtherCAT Terminals, compact drive technology		
Motor type	3...5 A	
Servomotor	ED7211-0010 48 V DC, 4.5 A, OCT, push-in	
Stepper motor	ED7062 48 V DC, 3 A, push-in	

EL/ELM7xxx EtherCAT Terminals, compact drive technology					
Motor type	< 3 A	3...5 A	> 5 A		16 A
Servomotor			ELM7211-0010 <i>I_{rms}</i> = 4.5 A, 48 V DC		
			ELM7211-9016 <i>I_{rms}</i> = 4.5 A, 48 V DC, TwinSAFE Logic	ELM7211-9018 <i>I_{rms}</i> = 4.5 A, 48 V DC, Safe Motion, TwinSAFE Logic	
			ELM7212-0010 <i>I_{rms}</i> = 2 x 4.5 A, 48 V DC		ELM7222-0010 <i>I_{rms}</i> = 2 x 8.0 A, 48 V DC
			ELM7212-9016 <i>I_{rms}</i> = 2 x 4.5 A, 48 V DC, TwinSAFE Logic	ELM7212-9018 <i>I_{rms}</i> = 2 x 4.5 A, 48 V DC, Safe Motion, TwinSAFE Logic	ELM7222-9016 <i>I_{rms}</i> = 2 x 8.0 A, 48 V DC, TwinSAFE Logic
					ELM7222-9018 <i>I_{rms}</i> = 2 x 8.0 A, 48 V DC, Safe Motion, TwinSAFE Logic
	EL7201-0010 <i>I_{rms}</i> = 2.8 A, 48 V DC, OCT	EL7211-0010 <i>I_{rms}</i> = 4.5 A, 48 V DC, OCT	ELM7221-0010 <i>I_{rms}</i> = 8 A, 48 V DC		ELM7231-0010 <i>I_{rms}</i> = 16 A, 48 V DC
	EL7201 <i>I_{rms}</i> = 2.8 A, 48 V DC, resolver	EL7211 <i>I_{rms}</i> = 4.5 A, 48 V DC, resolver	ELM7221-9016 <i>I_{rms}</i> = 8 A, 48 V DC, TwinSAFE Logic	ELM7221-9018 <i>I_{rms}</i> = 8 A, 48 V DC, Safe Motion, TwinSAFE Logic	ELM7231-9016 <i>I_{rms}</i> = 16 A, 48 V DC, TwinSAFE Logic
					ELM7231-9018 <i>I_{rms}</i> = 16 A, 48 V DC, Safe Motion, TwinSAFE Logic
	EL7201-9014 <i>I_{rms}</i> = 2.8 A, 48 V DC, OCT, STO	EL7211-9014 <i>I_{rms}</i> = 4.5 A, 48 V DC, OCT, STO	EL7221-9014 <i>I_{rms}</i> = 7...8 A with ZB8610, 48 V DC, OCT, STO		
Stepper motor	EL7031 <i>I_{max}</i> = 1.5 A, 24 V DC	EL7041 <i>I_{max}</i> = 5.0 A, 48 V DC, incr. enc.			
	EL7031-0030 <i>I_{max}</i> = 2.8 A, 24 V DC	EL7041-0052 <i>I_{max}</i> = 5.0 A, 48 V DC			
	EL7037 <i>I_{max}</i> = 1.5 A, 24 V DC, incr. enc., vector control	EL7047 <i>I_{max}</i> = 5.0 A, 48 V DC, incr. enc., vector control			
		EL7062 <i>I_{max}</i> = 3 A, 5 V DC, incr. enc.			

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.



EtherCAT Box modules

EL/ELM7xxx EtherCAT Terminals, compact drive technology				
Motor type	< 3 A	3...5 A	> 5 A	16 A
DC motor output stage	EL7332 <i>I_{max}</i> = 1.0 A, 24 V DC	EL7342 <i>I_{max}</i> = 3.5 A, 48 V DC, incr. enc.		
BLDC motor		EL7411 <i>I_{rms}</i> = 4.5 A, 48 V DC		
4-axis interface	EM7004 4 incr. enc., 32 digital I/Os 24 V DC, 4 analog outputs ±10 V			

EP7xxx EtherCAT Box, compact drive technology			
Motor type	< 3 A	> 3 A	
Servomotor		EP7211-0034 <i>I_{rms}</i> = 4.5 A, 48 V DC, OCT, STO suitable	EP7211-0035 <i>I_{rms}</i> = 4.5 A, 48 V DC, OCT, STO suitable, drive profile CiA DS402
Stepper motor		EP7047-1032 <i>I_{max}</i> = 5.0 A, 48 V DC	
	EP7041-1002 ⁽¹⁾ <i>I_{max}</i> = 1.5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output	EP7041-0002 ⁽¹⁾ <i>I_{max}</i> = 5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output	EP7041-2002 ⁽¹⁾ <i>I_{max}</i> = 5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output, motor connection via plug
		EP7041-3002 ⁽¹⁾ <i>I_{max}</i> = 5 A, 48 V DC, incremental encoder, for high-speed applications, encoder system (24 V DC encoder)	EP7041-3102 <i>I_{max}</i> = 5 A, 48 V DC, incremental encoder, for high-speed applications, encoder system (5 V DC encoder)
		EP7041-4032 <i>I_{max}</i> = 5.0 A, 48 V DC, BiSS® C encoder	
DC motor		EP7342-0002 ⁽¹⁾ <i>I_{max}</i> = 3.5 A, 48 V DC	
BLDC motor		EP7402-0057 for roller conveyor systems, 24 V DC, EtherCAT junction	EP7402-0067 for roller conveyor systems, 48 V DC, EtherCAT junction
			EP7402-0167 for roller conveyor systems, 48 V DC

EPxxxx: industrial housing in IP67, ⁽¹⁾also as ERxxxx: zinc die-cast housing in IP67, ⁽²⁾also as EQxxxx: stainless steel housing in IP69K

XPlanar | Planar motor system

► www.beckhoff.com/xplanar



EtherCAT P Box modules



EtherCAT plug-in modules



Bus Terminals

EPP7xxx | EtherCAT P Box, compact drive technology

Motor type	< 3 A	> 3 A
Stepper motor	EPP7041-1002 I_{max} = 1.5 A, 48 V DC, incremental encoder	EPP7041-3002 I_{max} = 5.0 A, 48 V DC, incremental encoder
DC motor output stage		EPP7342-0002 I_{max} = 3.5 A, 48 V DC

EJ7xxx | EtherCAT plug-in modules, compact drive technology

Motor type	< 3 A	3...5 A	
Servomotor		EJ7211-0010 I_{rms} = 4.5 A, 48 V DC, OCT	EJ7211-9414 I_{rms} = 4.5 A, 48 V DC, OCT, STO, TwinSAFE SC
Stepper motor	EJ7031 I_{max} = 1.5 A, 24 V DC	EJ7037 I_{max} = 1.5 A, 24 V DC, incremental encoder, vector control	EJ7041-0052 I_{max} = 5.0 A, 48 V DC EJ7047 I_{max} = 5.0 A, 48 V DC, incremental encoder, vector control
DC motor output stage		EJ7334-0008 I_{max} = 3.0 A, 24 V DC, incremental encoder	EJ7342 I_{max} = 3.5 A, 48 V DC, incremental encoder
BLDC		EJ7411 I_{rms} = 4.5 A, 48 V DC	

KL2xxx | Bus Terminals, compact drive technology

Motor type	< 3 A	3...5 A
Stepper motor	KL2531 I_{max} = 1.5 A, 24 V DC	KL2541 I_{max} = 5.0 A, 48 V DC, incremental encoder
DC motor output stage	KL2532 I_{max} = 1.0 A, 24 V DC	KL2284 reverse switching, I_{max} = 2.0 A, 0...24 V DC KL2552 I_{max} = 5.0 A, 48 V DC, incremental encoder
AC motor speed controller	KL2791 230 V AC, 200 VA, 1-phase AC motor	

Details for a pluggable wiring level (where present) can be seen in the housing data and ordering information on the product page.



Movers



Tile

Starter kits

XPlanar | Planar motor system

Movers	APM4220-0000-0000 0.6 kg payload, 113 mm x 113 mm x 12 mm	APM4230-0000-0000 0.8 kg payload, 115 mm x 155 mm x 12 mm	<i>i</i> APM4221-0000-0000 1.0 kg payload, 127 mm x 127 mm x 12 mm	APM4330-0001-0000 1.2 kg payload, 150 mm x 150 mm x 12 mm, stainless steel
	APM4330-0000-0000 1.8 kg payload, 155 mm x 155 mm x 12 mm	APM4350-0000-0000 3.0 kg payload, 155 mm x 235 mm x 12 mm	<i>i</i> APM4550-0000-0000 4.5 kg payload, 235 mm x 235 mm x 12 mm	
Tile	APS4322-0000-0000 240 mm x 240 mm	APS4244-1x00-0000 320 mm x 320 mm	APS4224-1x00-0000 160 mm x 320 mm, alignment to the y axis	APS4242-1x00-0000 320 mm x 160 mm, alignment to the x axis
Accessories	APM9001-0000-4xxx XPlanar ID bumper, 90-degree mover rotation			
Starter kits	APS9000 6 (2 x 3) APS4322 planar motor tiles, 2 APM4330 movers, Industrial PC, software, pre-installed, ready for operation	APS9001 12 (4 x 3) APS4322 planar motor tiles, 4 APM4330 movers, Industrial PC, software, pre-installed, ready for operation	APS9002-0000-0001 2 APS4322 planar motor tiles, 2 APM4220 movers, Industrial PC, software, pre-installed, ready for operation, with plexiglass cover and transport case	

XTS | Linear product transport

► www.beckhoff.com/xts



XTS Motor modules		
Design form	XTS Standard	XTS Hygienic
Straight	AT2000 straight, without infeed	ATH2000 straight, without infeed
	AT2200 EcoLine, straight, without infeed	
	AT2001 straight, with connection cables for infeed	ATH2001 straight, with infeed
	AT2002 straight, with plug connector for infeed	ATH2002 straight, with angled infeed
	AT2202 EcoLine, straight, with plug connector for infeed	
	AT2100 straight, without infeed, with integrated NCT functionality	
	AT2102 straight, with plug connector for infeed, with integrated NCT functionality	
22.5° curved segment (Ø 1273 mm)	AT2020 22.5° curved segment, without infeed	ATH2020 22.5° curved segment, without infeed
	AT2021 22.5° curved segment, with connection cables for infeed	
-22.5° curved segment (Ø 1273 mm)	AT2025 -22.5° curved segment, without infeed	
	AT2026 -22.5° curved segment, with connection cables for infeed	
45° curved segment (Ø 637 mm)	AT2040 45° curved segment, without infeed	ATH2040 45° curved segment, without infeed
	AT2041 45° curved segment, with connection cables for infeed	ATH2041 45° curved segment, with straight infeed
		ATH2042 45° curved segment, with angled infeed
180° curved segment (clothoid)	AT2050 180° curved segment, without infeed	ATH2050 180° curved segment, without infeed
		ATH2051 180° curved segment, with straight infeed



XTS Guide rails		
Design form	XTS Standard	XTS Hygienic
Straight	AT9000 straight, without lock	ATH9000 straight, without lock
	AT9100 straight, with lock	ATH9100 straight, with lock
		ATH9200 straight, connector
45° curved segment (Ø 637 mm)	AT9040 45° curved segment, without lock	
180° curved segment (clothoid)	AT9050 180° curved segment, without lock	ATH9050 180° curved segment

XTS Movers		
Material	XTS Standard	XTS Hygienic
Aluminum	AT9011 mover, length 70 mm	AT9014 mover, length 55 mm or 70 mm, spring-loaded
	AT9001 magnetic plate sets	ATH9013 mover, length 75 mm
Stainless steel		ATH9011 mover, length 75 mm
		ATH9001 magnetic plate sets

XTS NCT electronics				
	Version			
Basic electronics	AT8200-1000-0100 NCT electronics, with housing, without mover	AT8200-2000-0100 NCT electronics, with housing, without mover, suitable for third-party movers	AT8300-1100-0100 NCT electronics, with housing, mounted on AT9014-1070-0550 mover	AT8300-1200-0100 NCT electronics, with housing, mounted on AT9014-1070-1550 mover (mover 1)

XTS Starter kits			
	Mover 55 mm length	Mover 70 mm length	With NCT functionality
Small	AT2000-0500-0055	AT2000-0500-0170	AT2100-0011-0001
Medium	AT2000-1000-0055	AT2000-1000-0170	AT2100-0012-0001
Large	AT2000-1500-0055	AT2000-1500-0170	AT2100-0032-0001

The Automation Company

Beckhoff offers comprehensive system solutions in numerous performance classes for all areas of automation. The control technology is exceptionally scalable – from high-performance Industrial PCs to mini-PLCs – and can be adapted precisely to application-specific requirements. TwinCAT automation software integrates real-time control with PLC, NC and CNC functions in a single feature-filled package.

► www.beckhoff.com/automation



Efficient engineering

- integration into Microsoft Visual Studio
- wide selection of programming languages: IEC 61131-3, C/C++, MATLAB® and Simulink®, Safety C/FBD
- modular software development
- code generation interface
- link to source control systems
- TwinCAT CoAgent and Machine Learning Creator for AI-assisted automation

High performance

- cycle times from 50 µs
- multi-core support
- support of 32-bit and 64-bit operating systems
- pre-emptive multitasking
- TwinCAT PLC++: new PLC technology

Connectivity

- useable with all fieldbus systems
- open and expandable for IT trends – today and tomorrow
- adheres to industry-specific and standard protocols
- ideal for IoT and cloud computing applications

► www.beckhoff.com/twincat

TwinCAT 3 102

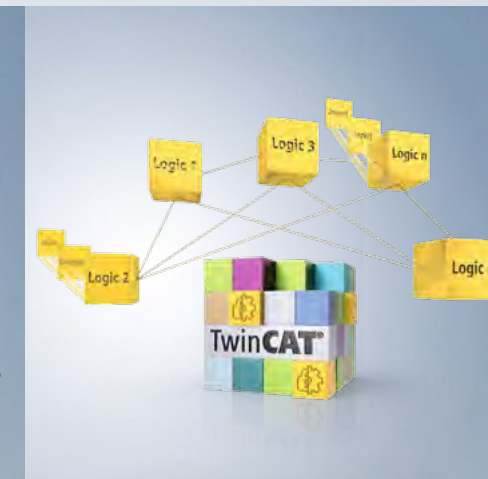
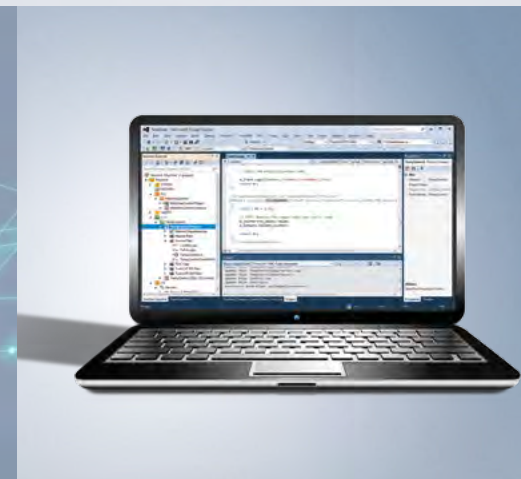
- one software platform for engineering and runtime
- integrated real-time support
- software modules for PLC, NC, CNC, robotics, HMI, measurement technology, analytics, safety, machine vision, machine learning

TwinCAT 2 112

TwinSAFE 116

- integrated safety system from I/Os to drives
- compact safety PLC
- certified for solutions up to IEC 61508 SIL 3 and DIN EN ISO 13849-1:2008 PL e
- safety engineering integrated into TwinCAT 3

► www.beckhoff.com/twinsafe



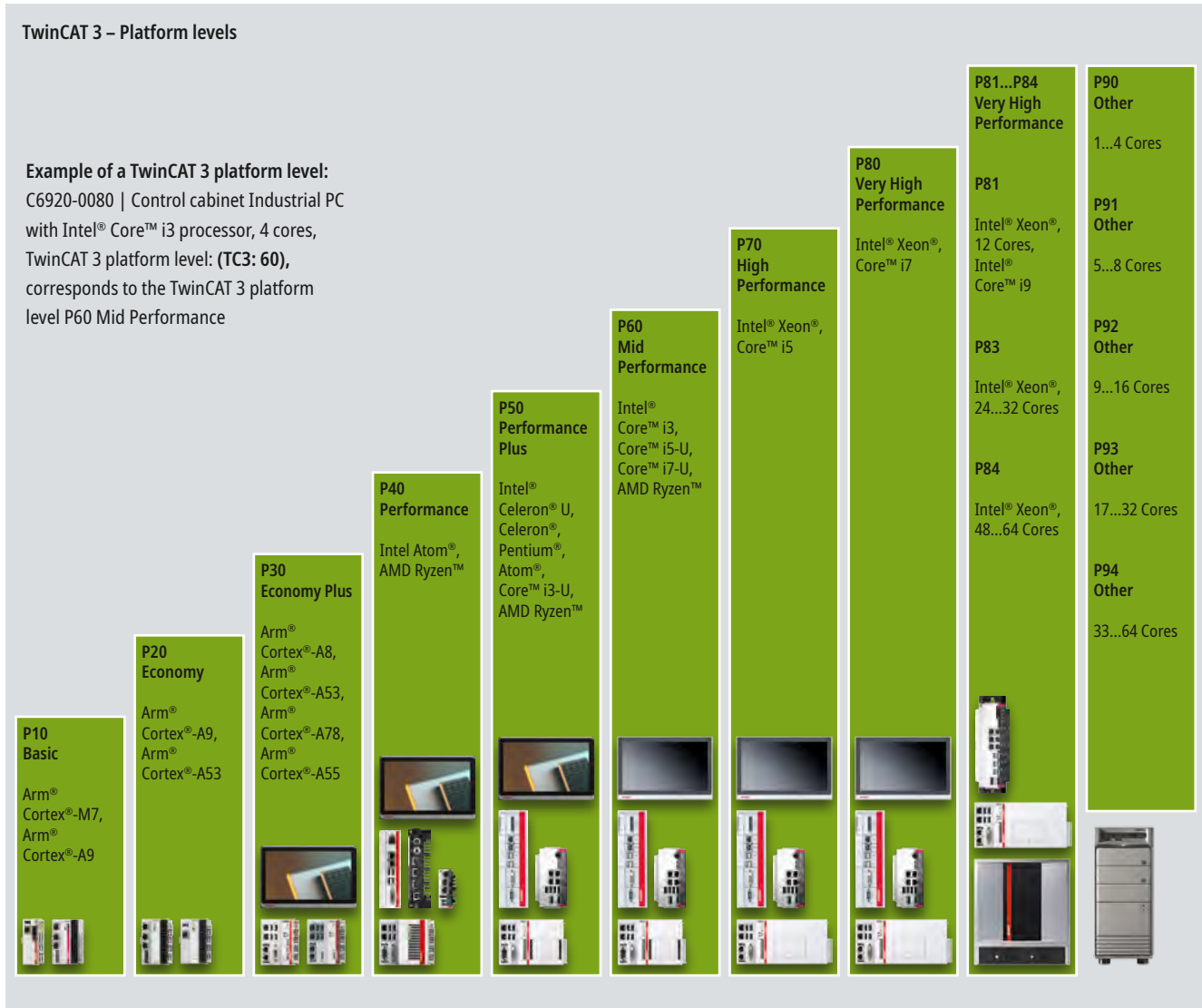
- efficient, universal engineering
- programming in different languages
- Open, hardware-independent control system gives freedom of choice in terms of automation and control components.
- scalable control platform from single- to multi-core CPUs
- all control functions on a single, centralized platform: PLC, motion control, robotics, measurement technology, a.o.

TwinCAT 3

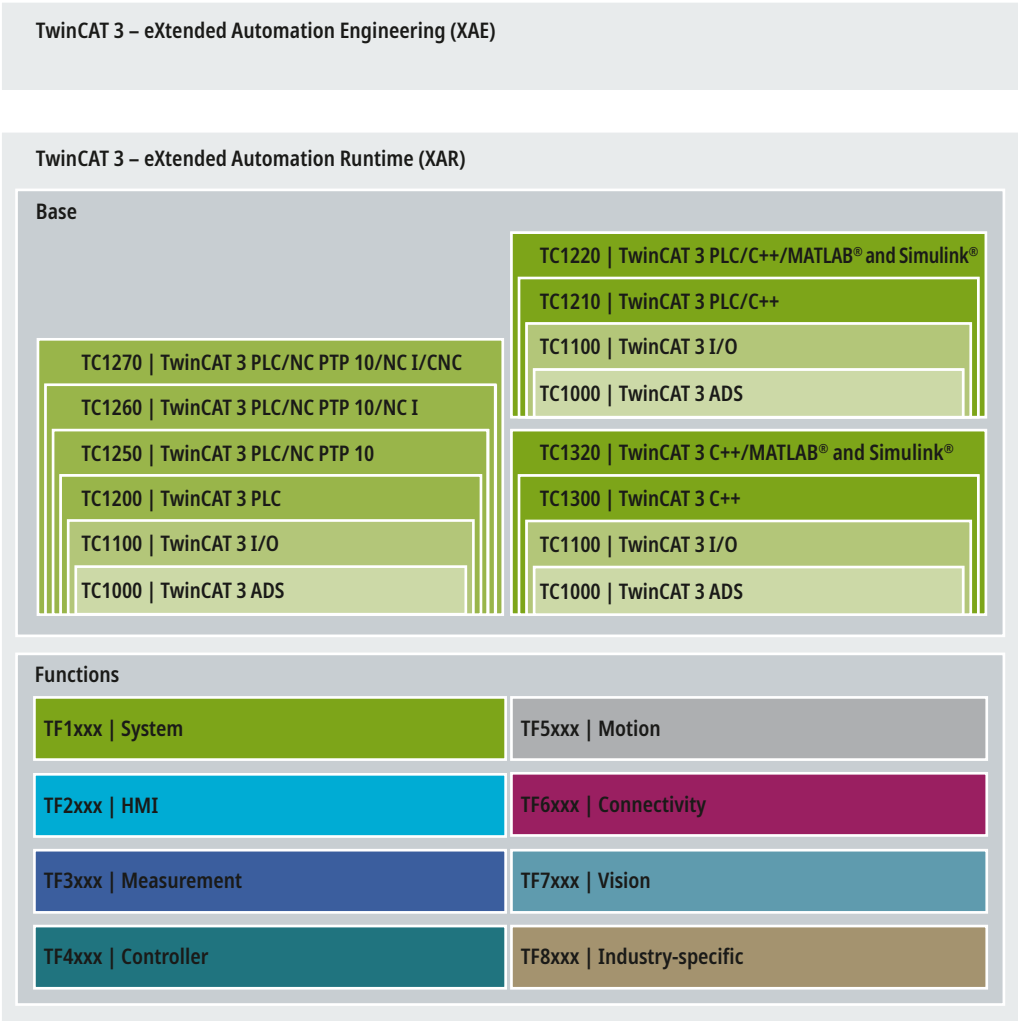
► www.beckhoff.com/twincat

The TwinCAT 3 runtime components are available for different platform levels.
The platform levels correspond to the various TwinCAT 3 platform levels of the Beckhoff PCs. The TwinCAT 3 platform level of a Beckhoff PC depends on the configuration and the technical data of the PC (including the processor).

The overview shows the various TwinCAT 3 platform levels. The controllers integrated in the platform levels represent sample configurations. The TwinCAT 3 platform level required for a TwinCAT 3 Runtime component can be found in the product description of the respective Beckhoff PC.



The controllers integrated in the platform classifications are only example configurations.



TwinCAT 3 is divided into components. The TwinCAT 3 engineering components enable the configuration, programming and debugging of applications. The TwinCAT 3 runtime consists of further components – basic components and functions. The basic components can be extended by functions.

TExxxx TwinCAT 3, Engineering		
TwinCAT 3 Engineering	TE1000	TwinCAT 3 engineering environment
TwinCAT 3 Realtime Monitor	TE1010	tool for precise diagnostics and optimization of the runtime behavior of tasks in the TwinCAT 3 runtime
TwinCAT 3 Documentation Generation	TE1030	tool for simplified creation of documentation from the current PLC code of the machine via specific markups
TwinCAT 3 EtherCAT Simulation	TE1111	easy configurations of simulation environments with several EtherCAT slaves
TwinCAT 3 XCAD Interface	TE1120	interface between ECAD tools and TwinCAT 3
TwinCAT 3 Interface for Inventor®	TE1130	link between TwinCAT and the Inventor® 3D CAD software for SiL simulation i
TwinCAT 3 Interface Maintenance for Inventor®	TE1131	optional annual expansion of functions for TwinCAT 3 Interface for Inventor® i
TwinCAT 3 Interface for SOLIDWORKS®	TE1132	link between TwinCAT and the SOLIDWORKS® 3D CAD software for SiL simulation i
TwinCAT 3 Interface Maintenance for SOLIDWORKS®	TE1133	optional annual expansion of functions for TwinCAT 3 Interface for SOLIDWORKS® i
TwinCAT 3 Interface for NX™ Mechatronics Concept Designer™	TE1134	link between TwinCAT and the NX™ 3D CAD software for SiL simulation i
TwinCAT 3 Interface Maintenance for NX™ Mechatronics Concept Designer™	TE1135	optional annual expansion of functions for TwinCAT 3 Interface for NX™ Mechatronics Concept Designer™ i
TwinCAT 3 PLC Static Analysis	TE1200	analysis tool that tests PLC software on the basis of coding rules
TwinCAT 3 PLC Profiler	TE1210	analyzes the runtime characteristics of a PLC project and identifies time-intensive call-ups and program sections
TwinCAT 3 Scope View Professional	TE1300	software oscilloscope for the graphical display of data captured from several target systems
TwinCAT 3 Filter Designer	TE1310	graphical engineering tool for determining coefficients of digital filters
TwinCAT 3 Target for Simulink®	TE1400	TwinCAT target for Simulink® for generating TwinCAT 3 modules
TwinCAT 3 Target for MATLAB®	TE1401	TwinCAT target for MATLAB® for generating TwinCAT 3 modules
TwinCAT 3 Target for Embedded Coder®	TE1402	TwinCAT Target for generating TwinCAT 3 modules with Embedded Coder®
TwinCAT 3 Interface for MATLAB® and Simulink®	TE1410	communication interface between MATLAB® and Simulink® and the TwinCAT 3 runtime
TwinCAT 3 Target for FMI	TE1420	interface for simulation tools that support the Functional Mockup Interface (FMI)
TwinCAT 3 Simulation Runtime for FMI	TE1421	Co-Simulation interface for tools that support the Functional Mockup Interface (FMI)
TwinCAT 3 Valve Diagram Editor	TE1500	graphical tool for designing the characteristic curve of a hydraulic valve
TwinCAT 3 Cam Design Tool	TE1510	graphic design tool for electronic cam plates
TwinCAT 3 EAP Configurator	TE1610	tool for visualizing and configuring communication networks, in which data exchange based on the EtherCAT Automation Protocol (EAP) takes place
TwinCAT 3 CoAgent for Engineering	TE1700	smart AI assistant for advanced engineering with digital agents that accelerates development and improves system diagnostics i
TwinCAT 3 HMI Engineering	TE2000	tool for developing platform-independent user interfaces
TwinCAT 3 Analytics Workbench	TE3500	engineering tool for creating continuous data analysis of machines and plants with automatic code and dashboard generation
TwinCAT 3 Analytics Workbench Maintenance	TE3501	optional annual expansion of functions for TwinCAT 3 Analytics Workbench
TwinCAT 3 Analytics Vision	TE3510	graphic engineering tool for easy creation of applications for the machine vision sector, including automatic code and dashboard generation i
TwinCAT 3 Analytics Energy	TE3511	graphic engineering tool for easy creation of applications for the electrical energy system sector, including automatic code and dashboard generation i
TwinCAT 3 Analytics Condition Monitoring	TE3512	graphic engineering tool for easy creation of applications for the condition monitoring sector, including automatic code and dashboard generation i

TExxxx TwinCAT 3, Engineering		
TwinCAT 3 Analytics Service Tool	TE3520	tool for process data analysis, ideal for commissioning and service technicians
TwinCAT 3 Analytics Service Tool Maintenance	TE3521	optional annual expansion of functions for TwinCAT 3 Analytics Service Tool
TwinCAT 3 Machine Learning Creator	TE3850	automated AI model generation for industrial applications i
TwinCAT 3 Machine Learning Creator Computer Vision	TE3851	automated AI model generation and training for machine vision tasks i
TwinCAT 3 Machine Learning Creator Signals and Time Series	TE3852	automated AI model generation and training for signals and time series i
TwinCAT 3 Machine Learning Creator Resource Pack	TE3860	optional extension package for extra computing capacity for Machine Learning Creator applications i
TwinCAT 3 Motion Designer	TE5910	TwinCAT 3 Motion Designer for drive dimensioning
TwinCAT 3 Drive Manager 2	TE5950	TwinCAT 3 Drive Manager 2 for commissioning the AX8000 multi-axis servo system, AX5000 digital compact servo drive, AMP8000 distributed servo drive system, AMI8100 integrated servo drives or the I/O components EL72xx, EL74xx, EL70x7, ELM72xx, EP72xx and EJ72xx
TwinCAT 3 Autotuning	TE5960	TwinCAT 3 Autotuning to simplify the commissioning of servo axes by automatically identifying the mechanics and determining the load inertia, controller parameters and filter settings
TwinCAT 3 OPC UA Nodeset Editor	TE6100	Engineering tool for creating and editing OPC UA nodeset files, which are used in particular for companion specifications. With the help of the editor, existing companion specifications or also own information models can be mapped on a Beckhoff controller and linked with data points from the PLC.
TwinCAT 3 OPC UA Nodeset Editor L2	TE6101	extension of the TE6100 Nodeset Editor basic license to include additional functions, e.g. PLC code generation i
TwinCAT 3 MTP Engineering	TE8400	engineering environment for specifying properties and services of a software-based plant module and for defining the dependencies

TCxxxx TwinCAT 3, Base		
TwinCAT 3 ADS	TC1000	The Automation Device Specification (ADS) is the communication protocol of TwinCAT. It enables the data exchange and the control of TwinCAT systems. ADS is media-independent and can communicate via serial or network connections.
TwinCAT 3 I/O	TC1100	Using TwinCAT I/O, cyclic data can be collected by different fieldbuses in process images. Cyclic tasks drive the corresponding fieldbuses. Various fieldbuses can be operated with different cycle times on one CPU. Applications can directly access the process image. The fieldbuses and the process images are configured in TwinCAT Engineering.
TwinCAT 3 PLC	TC1200	TwinCAT PLC realizes one or more PLCs on an Industrial PC. The international standard IEC 61131-3 3 rd is used to program the PLC; all programming languages described in this standard are supported. Various convenient debugging options facilitate troubleshooting and commissioning. Program modifications can be carried out at any times and in any size online, i.e. when the PLC is running.
TwinCAT 3 PLC/C++	TC1210	Based on the TwinCAT PLC TC1200, TC1210 offers the additional option of using C++ modules in the runtime parallel to the PLC through TC1300 TwinCAT 3 C++.
TwinCAT 3 PLC/C++/ MATLAB® and Simulink®	TC1220	MATLAB® and Simulink® are established development environments in science and industry. Using the TE140x products from Beckhoff and the MATLAB Coder™ or the Simulink Coder™ from MathWorks®, TwinCAT 3 runtime modules (TcCOM objects and PLC function blocks) can be created from MATLAB® and Simulink®. TC1220 is an extension of TC1210 with the possibility to execute these modules.
TwinCAT 3 PLC/NC PTP 10	TC1250	Extension of the TwinCAT PLC TC1200 by the possibility to realize point-to-point movements in software (TwinCAT Motion Control PTP 10). The axes are represented by axis objects and provide a cyclic interface, e.g. for the PLC. This axis object is then linked to a corresponding physical axis.

TCxxxx TwinCAT 3, Base		
TwinCAT 3 PLC/NC PTP 10/ NC I	TC1260	Extension of the TwinCAT PLC/NC PTP 10 by the possibility to interpolate movements with up to three path axes and up to five auxiliary axes. Various axis types with various fieldbus interfaces are supported. The movement is usually programmed in DIN 66025, but it can also alternatively be carried out via PLC function blocks.
TwinCAT 3 PLC/NC PTP 10/ NC I/CNC	TC1270	Extension of the TwinCAT PLC/NC PTP 10/NC I by the possibility to realize an interpolation with up to 32 simultaneously interpolating axes. The number of axes and/or the number of channels can be adapted to the requirements of the application via the option packages. Various transformations can be supplemented via option packages.
TwinCAT 3 PLC/NC PTP 10/ NC I/CNC E	TC1275	TwinCAT CNC export version (E version) is an extension of the TwinCAT PLC/NC PTP 10 by the possibility to realize an interpolation with up to 4 simultaneously interpolating axes. The number of axes and/or the number of channels can be adapted to the requirements of the application via the option packages. Various transformations can be supplemented via option packages.
TwinCAT 3 C++	TC1300	TwinCAT C++ implements a real-time execution of C++ code on an Industrial PC. For programming, the widely used programming language C++ is supported, which is connected to the real-time via the TwinCAT SDK and CRT. Extensive debugging interfaces are supported by Visual Studio and also supplemented by representations typical of real-time.
TwinCAT 3 C++/ MATLAB® and Simulink®	TC1320	MATLAB® and Simulink® are established development environments in science and industry. Using the TE140x products from Beckhoff and the MATLAB Coder™ or the Simulink Coder™ from MathWorks®, TwinCAT 3 runtime modules (TcCOM objects and PLC function blocks) can be created from MATLAB® and Simulink®. TC1320 is an extension of TC1300 with the possibility to execute these modules.
TwinCAT 3 Usermode Runtime	TC1700	The TwinCAT 3 Usermode Runtime provides a way to run the applications programmed in TwinCAT without real-time properties in the user mode of the operating system. The TwinCAT 3 Usermode Runtime can be used free of license costs purely for engineering purposes and only requires (trial) licenses of the TwinCAT products used.
TwinCAT 3 Usermode Runtime: External Control	TC1701	The TwinCAT Usermode runtime provides a way to run the applications programmed in TwinCAT without real-time properties in the user mode of the operating system. The “External Control” option provides an interface that runs the application, clocked by an external application. Synchronization with other programs can be achieved with this option.
TwinCAT 3 Usermode Runtime: Fast As Possible	TC1702	The TwinCAT Usermode runtime provides a way to run the applications programmed in TwinCAT without real-time properties in the user mode of the operating system. The “Fast As Possible” option provides an interface that runs the application as fast as the hardware allows. A simulation of calculated results of an application can be realized with this option.
TwinCAT 3 Restricted Runtime	TC399x	Runtime license that can be used temporarily and repeatedly for developmental purposes and within the scope of continuous integration, continuous deployment, and simulation processes

TF1xxx TwinCAT 3, Functions, System		
TwinCAT 3 Controller Redundancy	TF1100	provides an extension to enable redundant processing of TwinCAT 3 PLC programs in two run-time environments and increases the availability of the entire system in the process
TwinCAT 3 UI Client	TF1200	cross-platform desktop application for displaying web applications
TwinCAT 3 Runtime for MATLAB® and Simulink®	TF1400	execution of runtime modules in TwinCAT 3 generated from MATLAB® and Simulink®
TwinCAT 3 Runtime for FMI	TF1420	enables the execution of TwinCAT 3 runtime modules generated via the TE1420 simulation tools interface
TwinCAT 3 CoAgent for Operations	TF1700	smart AI assistant for efficient machine operation, proactive maintenance, and precise system diagnostics
TwinCAT 3 PLC HMI	TF1800	stand-alone tool for displaying visualizations from the PLC development environment
TwinCAT 3 PLC HMI Web	TF1810	display of visualizations from the PLC development environment in a web browser
TwinCAT 3 UML	TF1910	UML (Unified Modeling Language) for modeling of PLC software

TF2xxx TwinCAT 3, Functions, HMI		
TwinCAT 3 HMI Server	TF2000	modular web server, includes a client connection and a target connection
TwinCAT 3 HMI Clients Packs	TF20x0	optional extension of the TwinCAT 3 HMI Server to increase the number of client connections
TwinCAT 3 HMI Targets Packs	TF20xx	optional extension of the TwinCAT 3 HMI Server to increase the number of connections to target systems
TwinCAT 3 HMI OPC UA	TF2110	server extension for access to TwinCAT target systems or other controllers via OPC UA
TwinCAT 3 HMI Database	TF2120	server extension for communicating with database systems
TwinCAT 3 HMI Extension SDK	TF2200	software development kit (.NET) for programming application-specific solutions
TwinCAT 3 HMI Scope	TF2300	software oscilloscope for graphic display of time sequences
TwinCAT 3 HMI Audit Trail	TF2400	server extension for logging operator changes and events that have occurred in the HMI server
TwinCAT 3 HMI Audit Trail Symbols Pack	TF24x0	optional extension of TwinCAT 3 HMI Audit Trail to increase the number of Audit Trail symbols

TF3xxx TwinCAT 3, Functions, Measurement		
TwinCAT 3 Scope Server	TF3300	data recording and preparation for visual display in TwinCAT 3 Scope View
TwinCAT 3 Analytics Logger	TF3500	analytics logger for cycle-synchronous data recording, storage and sending via MQTT to a message broker
TwinCAT 3 Analytics Library	TF3510	PLC library with analysis algorithms from simple edge counters and extreme value calculations to more complex correlation methods and unsupervised clustering algorithms
TwinCAT 3 Analytics Storage Provider	TF3520	IoT client as part of the Analytics workflow: Raw and analytic data can be received and stored in a storage; access for all Analytics tools.
TwinCAT 3 Analytics Runtime	TF3550	container running the Analytics application configured and developed in Analytics Workbench; including HMI server and client pack for Analytics dashboards
TwinCAT 3 Analytics Runtime Base	TF3551	container running the Analytics application configured and developed in Analytics Workbench; without HMI; ideal for headless applications or existing visualizations
TwinCAT 3 Condition Monitoring	TF3600	PLC library for the realization of a condition monitoring for a machine with algorithms like magnitude spectrum, envelope, kurtosis, order analysis or zoom FFT
TwinCAT 3 Power Monitoring	TF3650	PLC library for realization of power monitoring applications; algorithms for calculation of RMS values of current, voltage and power as well as THD fit to EL3773 and EL3783
TwinCAT 3 Filter	TF3680	PLC library for implementing digital filters
TwinCAT 3 Weighing Library	TF3685	PLC library for mapping a weighing scale in TwinCAT controllers based on Beckhoff load cell I/Os. The main focus is on dynamically weighing industrial goods.
TwinCAT 3 Interface for LabVIEW™	TF3710	enables the exchange of data between LabVIEW™ and the TwinCAT runtime
TwinCAT 3 Machine Learning Inference Engine	TF3800	execution module of trained classical machine learning algorithms
TwinCAT 3 Neural Network Inference Engine	TF3810	execution module of trained neural networks
TwinCAT 3 Machine Learning Server	TF3820	inference engine for trained machine learning and deep learning models with support for hardware accelerators
TwinCAT 3 Machine Learning Server Client	TF3830	client license for remote connections to a TF3820 TwinCAT 3 Machine Learning Server
TwinCAT 3 Solar Position Algorithm	TF3900	precise calculation of the sun's position

TF4xxx TwinCAT 3, Functions, Controller		
TwinCAT 3 Controller Toolbox	TF4100	basic controllers (P, I, D), complex controllers (PI, PID), pulse width modulation, ramps, signal generators and filters
TwinCAT 3 Temperature Controller	TF4110	temperature control for monitoring and controlling different temperature ranges
TwinCAT 3 Speech	TF4500	TwinCAT 3 Speech enables multilingual input and output of queries and information implemented in an industrially compatible way

TF5xxx TwinCAT 3, Functions, Motion		
TwinCAT 3 NC PTP 10 Axes	TF5000	TwinCAT 3 NC PTP enables point-to-point movements to be implemented in software; the axes are represented by axis objects and provide a cyclic interface for e.g. the PLC, the axis object is then linked to a corresponding physical axis
TwinCAT 3 NC PTP Axes Pack 25	TF5010	extension of TwinCAT 3 NC PTP to a maximum of 25 axes
TwinCAT 3 NC PTP Axes Pack unlimited	TF5020	extension of TwinCAT 3 NC PTP to 255 axes
TwinCAT 3 NC Camming	TF5050	TwinCAT 3 NC Camming (cam plates) enables the modeling of a non-linear relationship between master and slave axes
TwinCAT 3 NC Flying Saw	TF5055	TwinCAT 3 NC Flying Saw enables the coupling of a slave axis to a master axis in a specific synchronous position (flying saw)
TwinCAT 3 NC FIFO Axes	TF5060	TwinCAT 3 NC FIFO Axes enables the output of externally generated position setpoints to an axis group
TwinCAT 3 Motion Control XFC	TF5065	TwinCAT 3 Motion Control XFC enables time-accurate acquisition and switching of digital signals related to axis positions in conjunction with EtherCAT XFC terminals
TwinCAT 3 NC I	TF5100	TwinCAT 3 NC I enables interpolating path movements with three path axes and up to five auxiliary axes, whereby master/slave couplings can also be formed
TwinCAT 3 Kinematic Transformation L1	TF5110	TwinCAT 3 Kinematic Transformation L1 enables the control of various robot kinematics at level 1
TwinCAT 3 Kinematic Transformation L2	TF5111	TwinCAT 3 Kinematic Transformation L2 enables the control of various robot kinematics at level 2
TwinCAT 3 Kinematic Transformation L3	TF5112	TwinCAT 3 Kinematic Transformation L3 enables the control of various robot kinematics at level 3
TwinCAT 3 Kinematic Transformation L4	TF5113	TwinCAT 3 Kinematic Transformation L4 enables the control of various robot kinematics at level 4
TwinCAT 3 Robotics mxAutomation	TF5120	TwinCAT 3 Robotics mxAutomation allows direct communication between the PLC and a KUKA robot control via a common interface
TwinCAT 3 Robotics uniVAL PLC	TF5130	TwinCAT 3 Robotics uniVAL PLC allows direct communication between the PLC and a Stäubli robot control via a common interface
TwinCAT 3 CNC	TF5200	CNC path control software
TwinCAT 3 CNC E	TF5210	CNC path control software export version
TwinCAT 3 CNC Axes Pack 64	TF5220	extension to up to a total of 64 axes/controlled spindles, of which a maximum of 32 can be path axes and a maximum of 12 can be controlled spindles
TwinCAT 3 CNC Axes Pack unlimited	TF5221	extension to up to a total of 128 axes/controlled spindles, of which a maximum of 32 can be path axes and a maximum of 12 can be controlled spindles
TwinCAT 3 CNC Measurement	TF5225	optional package of CNC cycles that supports the measurement of tools or workpieces directly on the machine
TwinCAT 3 CNC Channel Pack	TF5230	further CNC channel, extension to a maximum of 32 channels, channel synchronization, axis transfer between channels

TF5xxx TwinCAT 3, Functions, Motion		
TwinCAT 3 CNC Transformation	TF5240	transformation functionality (5-axis functionality)
TwinCAT 3 CNC Kinematic Optimization	TF5245	optional CNC package that optimizes the determination of kinematic parameters for rotary axes in 5-axis kinematics
TwinCAT 3 CNC HSC Pack	TF5250	extending the CNC with HSC technology (high-speed cutting)
TwinCAT 3 CNC Spline Interpolation	TF5260	path programming via splines with programmable spline type, Akima-spline, B-spline
TwinCAT 3 CNC Realtime Cycles	TF5261	allows concurrent execution of G code in the interpolation cycle of the TwinCAT CNC
TwinCAT 3 CNC Online Adaption	TF5262	TcCom interfaces for integrating customer-specific interpolation functions
TwinCAT 3 CNC Extended Interpolation	TF5263	two-path programming and two-path compensation
TwinCAT 3 CNC Conveyor Tracking	TF5264	can synchronize a machine with moving workpieces
TwinCAT 3 CNC Virtual NCK Basis	TF5270	virtual TwinCAT CNC for simulation in a Windows environment
TwinCAT 3 CNC Virtual NCK Options	TF5271	virtual TwinCAT CNC for simulation in a Windows environment
TwinCAT 3 CNC Volumetric Compensation	TF5280	allows compensation of geometric machine errors according to DIN ISO 230 or ISO/TR 16907
TwinCAT 3 CNC Cutting Plus	TF5290	technology package for extending the CNC functionality for cutting operations
TwinCAT 3 CNC AM Plus	TF5291	function package for predictive process control
TwinCAT 3 CNC EDM Plus	TF5292	function package for wire-erosion machines and die-sinking machines
TwinCAT 3 CNC Milling Base	TF5293	CNC cycle package for triple-axis milling and drilling
TwinCAT 3 CNC HMI Base	TF5310	TwinCAT HMI components (control elements and server extension) for CNC-specific user interfaces i
TwinCAT 3 CNC HMI Simulation Server	TF5320	server application for provision of a processing simulation for TwinCAT 3 CNC HMI Base i
TwinCAT 3 Motion Collision Avoidance	TF5410	TwinCAT 3 Motion Collision Avoidance enables collision avoidance when operating multiple axes with TwinCAT 3 NC PTP in linear and/or translational dependency
TwinCAT 3 Motion Pick-and-Place	TF5420	TwinCAT 3 Motion Pick-and-Place enables the implementation of handling tasks by gantry robots or other kinematics
TwinCAT 3 Planar Motion	TF5430	TwinCAT 3 Planar Motion enables efficient and intelligent implementation of individual XPlanar applications and is a component of TF5890 TwinCAT 3 XPlanar
TwinCAT 3 MC3 Base	TF5500	next motion control generation combined with tried-and-tested motion control functionalities and new options i
TwinCAT 3 MC3 Axes Packs	TF551x	extension of TwinCAT 3 MC3 Base to include additional axis licenses i
TwinCAT 3 MC3 Multi Vendor Packs	TF553x	extension for MC3 axis licenses to include optional use of third-party drive technology i
TwinCAT 3 MC3 Camming	TF5550	extension for TwinCAT 3 MC3 Base to include non-linear couplings (cam plates) between axes i
TwinCAT 3 MC3 Fluid Power	TF5560	extension for TwinCAT 3 MC3 Base to include complete hydraulics integration in TwinCAT i
TwinCAT 3 Hydraulic Positioning	TF5810	manufacturer-independent control of hydraulic axes and replacement of external controllers; support of a wide variety of applications and different axis control concepts; number of axes depends only on the performance of the PC
TwinCAT 3 XTS	TF5850	TwinCAT 3 XTS enables the individual movement of XTS movers along a specific path; basic software package for the use and integration of XTS into the TwinCAT 3 environment; further use of the extensive possibilities of TwinCAT and XTS
TwinCAT 3 XPlanar	TF5890	TwinCAT 3 XPlanar enables free movement of XPlanar movers on freely arranged XPlanar tiles; basic software package for integration of the XPlanar system into the TwinCAT 3 environment; access to further extensive TwinCAT functions

TF6xxx TwinCAT 3, Functions, Connectivity		
TwinCAT 3 ADS Monitor	TF6010	recording and diagnostics functions for the communication of TwinCAT systems
TwinCAT 3 JSON Data Interface	TF6020	interface for the exchange of data in JSON format between the TwinCAT system and custom applications
TwinCAT 3 OPC UA	TF6100	access to TwinCAT in accordance with OPC UA with UA server (DA/HA/AC) and UA client (DA)
TwinCAT 3 OPC UA Pub/Sub	TF6105	protocol implementation for OPC UA Pub/Sub (UDP and MQTT)
TwinCAT 3 EtherCAT Redundancy 250	TF6220	extension of the TwinCAT EtherCAT master with cable redundancy capability for up to 250 slaves
TwinCAT 3 EtherCAT Redundancy 250+	TF6221	extension of the TwinCAT EtherCAT master with cable redundancy capability for more than 250 slaves
TwinCAT 3 EtherCAT External Sync	TF6225	extension of the TwinCAT EtherCAT master with an option to synchronize the Beckhoff real-time communication with external signals
TwinCAT 3 Parallel Redundancy Protocol (PRP)	TF6230	TwinCAT Parallel Redundancy Protocol (PRP) provides a redundant network communication according to IEC 62439-3. It offers a transparent Ethernet connection via two separate networks. The diagnostics information is provided in TwinCAT.
TwinCAT 3 Modbus TCP	TF6250	communication with Modbus TCP devices (server and client functionality)
TwinCAT 3 Modbus RTU	TF6255	serial communication with Modbus end devices
TwinCAT 3 PROFINET RT Device	TF6270	communication via PROFINET (PROFINET slave)
TwinCAT 3 PROFINET RT Controller	TF6271	communication via PROFINET (PROFINET master)
TwinCAT 3 EtherNet/IP™ Adapter	TF6280	communication via EtherNet/IP™ (EtherNet/IP™ adapter)
TwinCAT 3 EtherNet/IP™ Scanner	TF6281	communication via EtherNet/IP™ (EtherNet/IP™ scanner)
TwinCAT 3 FTP Client	TF6300	easy access from TwinCAT PLC to FTP server
TwinCAT 3 TCP/IP	TF6310	communication via generic TCP/IP server
TwinCAT 3 TCP/UDP Realtime	TF6311	TwinCAT 3 TCP/UDP Realtime enables fast and convenient access from real-time to an Ethernet network
TwinCAT 3 Serial Communication	TF6340	communication via serial Bus Terminals or PC COM ports with the 3964R and RK512 protocol
TwinCAT 3 SMS/SMTP	TF6350	sending SMS and e-mails from the PLC
TwinCAT 3 Virtual Serial COM	TF6360	virtual serial COM driver for Windows platforms
TwinCAT 3 Database Server	TF6420	interface for communication with various database systems from Microsoft SQL to MySQL and SQLite to MongoDB or InfluxDB
TwinCAT 3 XML Server	TF6421	read and write access to XML files from the PLC
TwinCAT 3 IEC 60870-5-10x	TF6500	communication according to IEC 60870-101 (master and slave), -102 (master), -103 (master), -104 (master and slave)
TwinCAT 3 IEC 61850/ IEC 61400-25	TF6510	communication according to IEC 61850 and IEC 61400-25 in the versions client and server, as well as via GOOSE as publisher and subscriber
TwinCAT 3 RFID Reader Communication	TF6600	connection of RFID readers to the TwinCAT PLC
TwinCAT 3 S7 Communication	TF6620	enables TCP/IP based communication with variables of a Siemens S7 controller
TwinCAT 3 DBC File Import for CAN	TF6650	reading of DBC file formats
TwinCAT 3 FDT ComDTM	TF6680	With the TwinCAT 3 FDT ComDTM, the FDT/DTM technology can be used with Beckhoff components in third-party systems. For this purpose, the ComDTM establishes the connection between the FDT frame application and the target system, e.g. a TwinCAT-based controller. This allows the configuration of the connected field devices via their device-specific DTMs. provides basic publisher/subscriber-based data connectivity via MQTT
TwinCAT 3 IoT Communication (MQTT)	TF6701	
TwinCAT 3 IoT Functions	TF6710	provides connectivity for cloud-based communication services
TwinCAT 3 IoT Data Agent	TF6720	gateway application for data connectivity between TwinCAT runtime and IoT services
TwinCAT 3 IoT Communicator	TF6730	sends process data and notifications from TwinCAT to smartphones and tablets through a messaging service

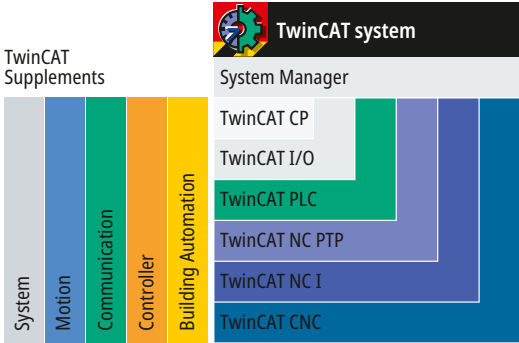
TF6xxx TwinCAT 3, Functions, Connectivity		
TwinCAT 3 IoT Communicator App	TF6735	smartphone and tablet app to receive and visualize live data and push notifications sent from TwinCAT
TwinCAT 3 IoT HTTPS/REST	TF6760	basic functions for HTTP/HTTPS communication in the form of a PLC library providing the ability to address REST APIs as a client
TwinCAT 3 IoT WebSockets	TF6770	basic functions for WebSockets communication as server and client
TwinCAT 3 IoT OCPP	TF6771	basic functions for communication with charging stations for electric vehicles and higher-level management systems

TF7xxx TwinCAT 3, Functions, Vision		
TwinCAT 3 GigE Vision Connector	TF700x	interface for the configuration and integration of GigE Vision cameras directly into TwinCAT
TwinCAT 3 Vision Beckhoff Camera Connector	TF7020	interface for configuring and using Beckhoff cameras directly in TwinCAT
TwinCAT 3 Vision Base	TF7100	extensive PLC library with a large number of different functions and algorithms for solving image processing tasks in TwinCAT real-time
TwinCAT 3 Vision Matching 2D	TF7200	extension of the basic package with the possibility to find and compare objects based on taught-in references, contours, feature points or other properties
TwinCAT 3 Vision Code Reading	TF7250	extension of the basic package with functions for reading various 1D and 2D codes
TwinCAT 3 Vision Code Quality	TF7255	extension of the basic package with functions for quality assessment of various 1D and 2D codes
TwinCAT 3 Vision OCR	TF7260	extension of the basic package with an option for optical character recognition
TwinCAT 3 Vision Metrology 2D	TF7300	extension of the basic package with a variety of functions: calibration, subpixel-accurate detection of edges, holes and circular arcs, determination of lengths, distances, diameters, angles and coordinates
TwinCAT 3 Vision Machine Learning	TF7800	extension of the basic package with the possibility to use classic machine learning algorithms for data analysis
TwinCAT 3 Vision Neural Network	TF7810	extension of the basic package to include an option for using neural networks for data analysis

TF8xxx TwinCAT 3, Functions, Industry-specific		
TwinCAT 3 BACnet	TF8020	communication with data networks of building automation and building control systems
TwinCAT 3 Building Automation	TF8040	PLC library for the automation of heating, ventilation and air conditioning technology, as well as the automation of rooms with the functions of sun protection and lighting
TwinCAT 3 Lighting Solution	TF8050	TwinCAT 3 Lighting Solution: software package for easy commissioning of DALI-2 lighting controllers
TwinCAT 3 Wind Framework	TF8310	framework for the development of operational management software for wind turbines
TwinCAT 3 Power Collector	TF8330	software modules for programming applications for power measurement
TwinCAT 3 Power Technologies	TF8350	software modules for programming deep diagnostics for electrical power measurement
TwinCAT 3 Power Control	TF8360	software modules for making a power plant controller
TwinCAT 3 MTP Runtime	TF8400	implementation of directive-compliant MTP interfaces in plant modules
TwinCAT 3 Plastic Processing Framework	TF8540	software library with temperature controller especially for plastics machines
TwinCAT 3 Plastic HMI Framework	TF8550	assembly of HMI elements for plastics machinery in NuGet packages
TwinCAT 3 Plastic Technology Functions	TF8560	technology package including abstracting motion control level for plastics machinery based on PLCopen standard
TwinCAT 3 AES70 (OCA)	TF8810	communication library for operating a system as an OCA (Open Control Architecture) controller in an OCA network

TwinCAT 2

► www.beckhoff.com/twincat



TX1000 TwinCAT 2, TwinCAT CP	
PC hardware	standard PC/IPC hardware, no extras
Operating systems	Windows 10, Windows Embedded WES2009*
Real-time	Beckhoff real-time kernel

Windows driver for Beckhoff Control Panels

TX1100 TwinCAT 2, TwinCAT I/O	
PC hardware	standard PC/IPC hardware, no extras
Operating systems	Windows 10, Windows CE*
Real-time	Beckhoff real-time kernel

Multi-purpose I/O interface for all common fieldbus systems, PC Fieldbus Cards and interfaces with integrated real-time driver

TX1200 TwinCAT 2, TwinCAT PLC	
PC hardware	standard PC/IPC hardware, no extras
Operating systems	Windows 10, Windows CE*
Real-time	Beckhoff real-time kernel
I/O system	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus, CANopen, DeviceNet®, SERCOS, Ethernet
Runtime system	4 multi-tasking PLCs each with 4 tasks in each PLC runtime system, development and runtime systems on one PC or separately (CE: only runtime)
Memory	process image size, flags area, program size, POU size, number of variables only limited by the size of the user memory (max. 2 GB with NT/2000/XP/Vista)
Cycle time	adjustable from 50 µs
Link time	1 µs (Intel® Core™ 2 Duo)
Programming	IEC 61131-3: IL, FBD, LD, SFC, ST, CFC, powerful library management

TX1250 TwinCAT 2, TwinCAT NC PTP	
TwinCAT PLC	inclusive
PC hardware	standard PC/IPC hardware, no extras
Operating systems	Windows 10, Windows CE*
Real-time	Beckhoff real-time kernel
I/O system	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus, CANopen, DeviceNet®, SERCOS, Ethernet
Programming	performed using function blocks for TwinCAT PLC according to IEC 61131-3 (standardized PLCopen motion control libraries), convenient axis commissioning menus in the System Manager
Runtime system	NC point-to-point including TwinCAT PLC
Number of axes	up to 255
Axis types	electrical and hydraulic servo drives, frequency converter drives, stepper motor drives, switched drives (fast/crawl axes)
Cycle time	50 µs upwards, typically 1 ms (selectable)
Axis functions	standard axis functions: start/stop/reset/reference, velocity override, special functions: master/slave cascading, cam plates, electronic gearings, online distance compensation of segments, flying saw

*Version-dependent/older operating system versions are available on request from our service department.

TX1260 TwinCAT 2, TwinCAT NC I	
TwinCAT PLC	inclusive
TwinCAT NC PTP	inclusive
PC hardware	standard PC/IPC hardware, no extras
Operating systems	Windows 10, Windows CE*
Real-time	Beckhoff real-time kernel
I/O system	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus, CANopen, DeviceNet®, SERCOS, Ethernet
Programming	DIN 66025 programs for NC interpolation, access via function blocks from TwinCAT PLC according to IEC 61131-3
Runtime system	NC interpolation, including TwinCAT NC PTP and PLC
Number of axes	max. 3 axes and up to 5 auxiliary axes per group, 1 group per channel, max. 31 channels
Axis types	electrical servo axes, stepper motor drives
Interpreter functions	subroutines and jumps, programmable loops, zeroshifts, tool compensations, M and H functions
Geometries	straight lines and circular paths in 3D space, circular paths in all main planes, helixes with base circles in all main planes linear, circular, helical interpolation in the main lanes and freely definable planes, Bezier splines, look-ahead function
Axis functions	online reconfiguration of axes in groups, path override, slave coupling to path axes, auxiliary axes, axis error and sag compensation, measuring functions
Operation	automatic operation, manual operation (jog/inching), single block operation, referencing, handwheel operation (motion/superposition)
Options	TS511x TwinCAT Kinematic Transformation

TX1270 TwinCAT 2, TwinCAT CNC				
TwinCAT PLC	inclusive			
TwinCAT NC PTP	inclusive			
TwinCAT NC I	inclusive			
PC hardware	standard PC/IPC hardware, no extras			
Operating systems	Windows 10*			
Real-time	Beckhoff real-time kernel			
I/O system	EtherCAT, Lightbus, PROFIBUS DP/MC, CANopen, DeviceNet®, SERCOS, Ethernet			
Programming	DIN 66025 programming language with high-level language extensions, access via function blocks from TwinCAT PLC according to IEC 61131-3			
Runtime system	CNC, including TwinCAT NC I, NC PTP, PLC			
Axes/spindles	8 path axes/controlled spindles, max. of 64 axes/controlled spindles (optional), max. 12 channels (optional)			
Axis types	electrical servo-axes, analog/encoder interface via fieldbus, digital interface via fieldbus			
Interpreter functions	subroutines and jumps, programmable loops, zero shifts, tool compensations, M and H functions, mathematical functions, programming of parameters/variables, user macros, spindle and help functions, tool functions			
Geometries	linear, circular, helical interpolation in the main planes and freely definable planes, max. 32 interpolating path axes per channel, look-ahead function			
Axis functions	coupling and gantry axis function, override, axis error and sag compensation, measuring functions			
Operation	automatic operation, manual operation (jog/inching), single block operation, referencing, block search, handwheel operation (motion/superposition)			
Options	TS5220	TwinCAT CNC Axes Pack	TS5250	TwinCAT CNC HSC Pack
	TS5230	TwinCAT CNC Channel Pack	TS5260	TwinCAT CNC Spline Interpolation
	TS5240	TwinCAT CNC Transformation		

TSxxxx TwinCAT 2, Supplements, System		
TwinCAT PLC HMI	TS1800	displaying visualizations created in PLC Control
TwinCAT PLC HMI Web	TS1810	displaying visualizations created in PLC Control in a web browser
TwinCAT Scope 2	TS3300	graphical analysis tool for displaying time-continuous signals
TwinCAT Solar Position Algorithm	TS3900	precise calculation of the sun's position
TwinCAT EtherCAT Redundancy	TS622x	extension of the TwinCAT EtherCAT master with cable redundancy capability
TwinCAT Database Server	TS6420	accessing databases from the PLC
TwinCAT XML Data Server	TS6421	reading and writing of XML-based data by the PLC

TS4xxx TwinCAT 2, Supplements, Controller		
TwinCAT PLC Controller Toolbox	TS4100	modules for basic controllers (P, I, D), complex controllers (PI, PID), pulse width modulation, ramps, signal generators and filters
TwinCAT PLC Temperature Controller	TS4110	instanced temperature control function block for monitoring and controlling different temperature ranges

TSxxxx TwinCAT 2, Supplements, Motion		
TwinCAT Valve Diagram Editor	TS1500	graphical tool for designing the characteristic curve of a hydraulic valve
TwinCAT Cam Design Tool	TS1510	graphic design tool for electronic cam plates
TwinCAT NC Camming	TS5050	providing the cam plate functionality (table coupling) of TwinCAT NC
TwinCAT NC Flying Saw	TS5055	providing flying saw functionality
TwinCAT NC FIFO Axes	TS5060	providing a FIFO interface for setpoint generation of an NC axis group
TwinCAT PLC Motion Control XFC	TS5065	high-precision logging and switching of digital signals in relation to axis positions
TwinCAT Kinematic Transformation	TS511x	implementation of different kinematic transformations for TwinCAT PTP or TwinCAT NC I
TwinCAT Digital Cam Server	TS5800	software implementation of fast cam controller
TwinCAT PLC Hydraulic Positioning	TS5810	control and adjustment of hydraulic axes

TS6xxx TwinCAT 2, Supplements, Communication		
TwinCAT OPC UA Server	TS6100	access to TwinCAT in accordance with OPC UA with UA server (DA/HA/AC) and UA client (DA)
TwinCAT Modbus TCP Server	TS6250	communication with Modbus TCP devices (server and client functionality)
TwinCAT PLC Modbus RTU	TS6255	serial communication with Modbus end devices
TwinCAT PROFINET RT Device	TS6270	license for using the TwinCAT PROFINET RT Device
TwinCAT PROFINET RT Controller	TS6271	license for using the TwinCAT PROFINET RT Controller
TwinCAT EtherNet/IP™ Adapter (Slave)	TS6280	license that turns any PC-based controller with an Intel® chipset and the real-time Ethernet driver developed by Beckhoff into an EtherNet/IP™ slave
TwinCAT FTP Client	TS6300	basic access from TwinCAT PLC to FTP server
TwinCAT TCP/IP Server	TS6310	communication via generic TCP servers
TwinCAT PLC Serial Communication	TS6340	communication via serial Bus Terminals or PC COM ports
TwinCAT PLC Serial Communication 3964R/RK512	TS6341	communication via serial Bus Terminals or PC COM ports with the 3964R and RK512 protocol
TwinCAT SMS/SMTP Server	TS6350	sending SMS and e-mails from the PLC
TwinCAT Virtual Serial COM Driver	TS6360	virtual serial COM driver for Windows and Windows CE platforms
TwinCAT PLC IEC 60870-5-101, -102, -103, -104 Master	TS650x	license for using a PLC library for the implementation of IEC 60870-5-10x masters
TwinCAT PLC IEC 60870-5-101, -104 Slave	TS650x	license for using a PLC library for the implementation of IEC 60870-5-10x slaves
TwinCAT PLC IEC 61400-25 Server	TS6509	IEC 61400-25 communication
TwinCAT PLC IEC 61850 Server	TS6511	IEC 61850 communication
TwinCAT PLC RFID Reader Communication	TS6600	connection of RFID readers to the TwinCAT PLC

TS8xxx TwinCAT 2, Supplements, Building Automation		
TwinCAT PLC HVAC	TS8000	automation of HVAC and sanitary installations
TwinCAT PLC Building Automation Basic	TS8010	executing basic room automation functions
TwinCAT BACnet/IP	TS8020	communication with the data networks of the building automation and building control systems
TwinCAT FIAS Server	TS8035	communication between TwinCAT PLC and a system using the FIAS standard
TwinCAT Crestron Server	TS8036	communication between a TwinCAT PLC and a Crestron controller
TwinCAT Building Automation	TS8040	software package covering all technical building automation services
TwinCAT Building Automation Framework	TS8100	configuration and commissioning of building automation projects

TwinSAFE

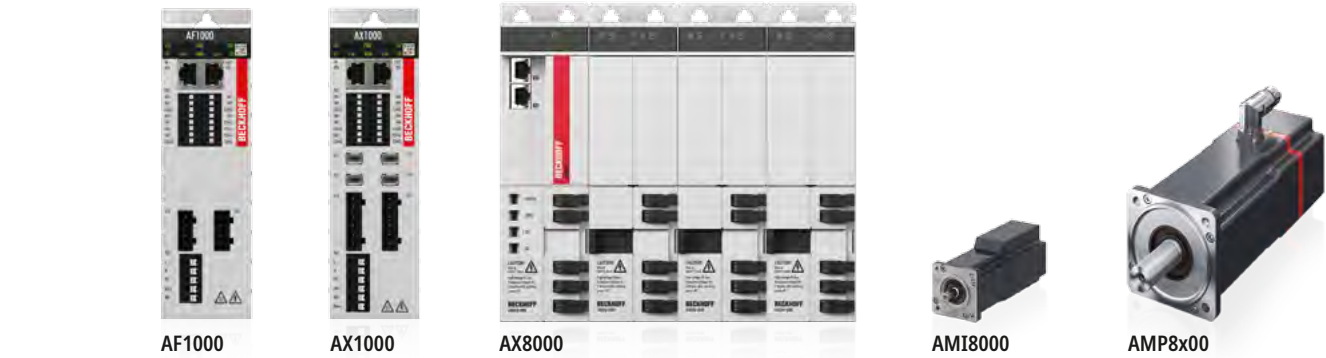
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TwinSAFE software		
TwinCAT 3 Safety Editor	TE9000	implementing of safety applications in graphical environment
TwinSAFE Loader/User	TE9200	TwinSAFE command line tools: Loader for downloading/customizing safety projects at runtime; User for handling user management of TwinSAFE logic components
TwinSAFE Logic Simulator	TE9100	virtual commissioning of a safety application based on TE1111 TwinCAT 3 EtherCAT Simulation i

TwinSAFE hardware, I/O						
	Input	Dedicated Logic	Output	Input and Logic	Logic and Output	Input, Logic and Output
EtherCAT Terminals	EK1914	EL6900	EK1914	EL1918	EL2912	EK1960
	4 standard inputs, 4 standard outputs, 2 safe inputs, 2 safe outputs	TwinSAFE Logic	4 standard inputs, 4 standard outputs, 2 safe inputs, 2 safe outputs	TwinSAFE Logic, 8 safe inputs	TwinSAFE Logic, 2 safe outputs	TwinSAFE Logic, 20 safe inputs, 24 safe outputs
	EL1904	EL6910	EL2904			EL1957
EtherCAT Box						
	TwinSAFE, 4 safe inputs	TwinSAFE Logic, PROFIsafe master and slave support	TwinSAFE, 4 safe outputs			TwinSAFE Logic, 8 safe inputs, 4 safe outputs
		EL6930			ELM72xx-9016	EL2911
EtherCAT plug-in modules						
					ELM72xx-9018	
Bus Terminals						
	EP1908-0002			EP1918-0002	EP2918-0032	EP1957-0022
	TwinSAFE, 8 safe inputs			TwinSAFE Logic, 8 safe inputs	TwinSAFE Logic, 8 safe outputs	TwinSAFE Logic, 8 safe inputs, 4 safe outputs
EtherCAT		EJ6910		EJ1914	EJ2914	EJ1957
		TwinSAFE Logic		TwinSAFE Logic, 4 safe inputs	TwinSAFE Logic, 4 safe outputs	TwinSAFE Logic, 8 safe inputs, 4 safe outputs
				EJ1918	EJ2918	
Bus Terminals						
	KL1904		KL2904		KL6904	
	TwinSAFE, 4 safe inputs		TwinSAFE, 4 safe outputs		TwinSAFE Logic, 4 safe outputs	

TwinSAFE hardware, Drive Technology			
	Output		
AX5000, TwinSAFE drive option card	AX5801	AX5805	AX5806
	drive-integrated safety functions: STO, SS1	drive-integrated safety functions: Safe Motion, for AX5x01 to AX5140	drive-integrated safety functions: Safe Motion, for AX5160 to AX5193



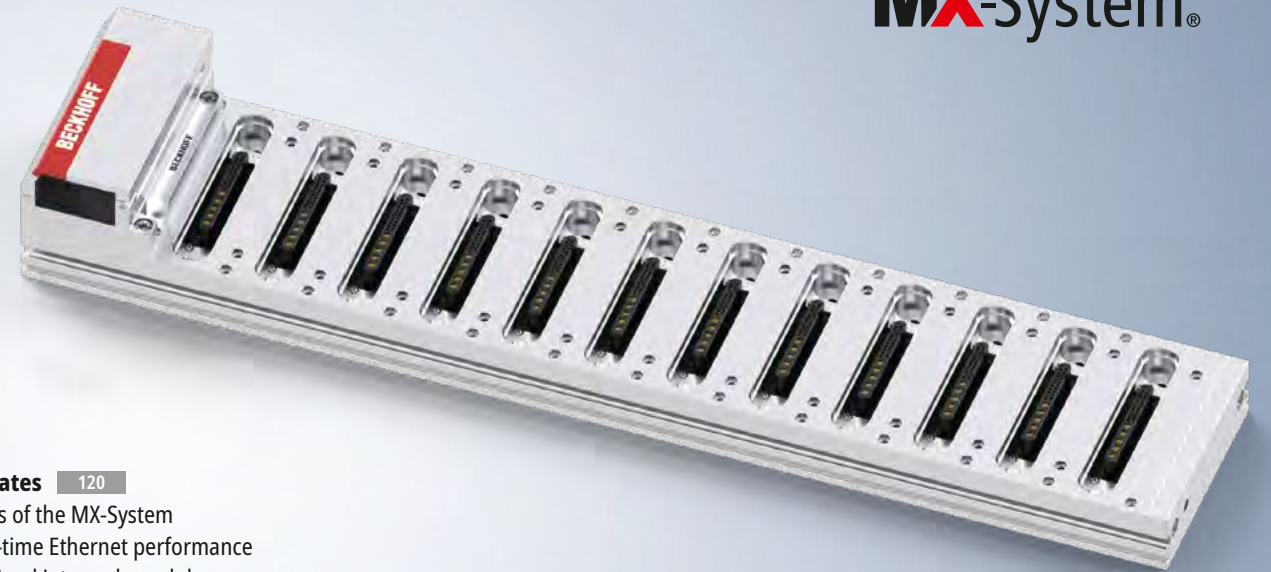
TwinSAFE hardware, Drive Technology				
	Input, Logic and Output			
AF1000, economy variable frequency drives	AF1103-1xxx	AF1107-1xxx	AF1115-1xxx	AF1203-1xxx
	single-axis module, 1 x 110...240 V AC, 0.37 kW	single-axis module, 1 x 110...240 V AC, 0.75 kW	single-axis module, 1 x 110...240 V AC, 1.5 kW	dual-axis module, 1 x 110...240 V AC, 0.37 kW
	AF1207-1xxx	AF1107-3xxx	AF1115-3xxx	AF1130-3xxx
AX1000, economy servo drives	dual-axis module, 1 x 110...240 V AC, 0.75 kW	single-axis module, 3 x 208...480 V AC, 0.75 kW	single-axis module, 3 x 208...480 V AC, 1.5 kW	single-axis module, 3 x 208...480 V AC, 3 kW
	AF1155-3xxx	AF1207-3xxx	AF1215-3xxx	AF1222-3xxx
	single-axis module, 3 x 208...480 V AC, 5.5 kW	dual-axis module, 3 x 208...480 V AC, 0.75 kW	dual-axis module, 3 x 208...480 V AC, 1.5 kW	dual-axis module, 3 x 208...480 V AC, 2.2 kW
AX8000, multi-axis servo drives	AX1101-1xxx	AX1103-1xxx	AX1106-1xxx	AX1201-1xxx
	single-axis module, 1 x 110...240 V AC, 1.65 A	single-axis module, 1 x 110...240 V AC, 3.4 A	single-axis module, 1 x 110...240 V AC, 6.9 A	dual-axis module, 1 x 110...240 V AC, 2 x 1.65 A
	AX1203-1xxx	AX1103-3xxx	AX1106-3xxx	AX1112-3xxx
AMI8000, compact integrated servo drives	dual-axis module, 1 x 110...240 V AC, 2 x 3.4 A	single-axis module, 3 x 208...480 V AC, 3.4 A	single-axis module, 3 x 208...480 V AC, 6.9 A	single-axis module, 3 x 208...480 V AC, 12 A
	AX1203-3xxx	AX1206-3xxx		
	dual-axis module, 3 x 208...480 V AC, 2 x 3 A	dual-axis module, 3 x 208...480 V AC, 2 x 6 A		
AMP8000, distributed servo drives	AX8108	AX8118	AX8128	AX8206
	single-axis module 8 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	single-axis module 18 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	single-axis module 28 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	dual-axis module 2 x 6 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion
	AX8525	AX8540		
AMP8500, distributed servo drives, higher rotor inertia	combined power supply and axis module 25 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	combined power supply and axis module 40 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion		
	AMI8121	AMI8122	AMI8123	
	M ₀ = 0.48 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1	M ₀ = 0.78 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1	M ₀ = 1.00 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1	
AMP8553, distributed servo drives, higher rotor inertia	AMI8131	AMI8132	AMI8133	
	M ₀ = 1.20 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1	M ₀ = 2.18 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1	M ₀ = 2.85 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1	
	AMP8031	AMP8032	AMP8033	
AMP8555, distributed servo drives, higher rotor inertia	M ₀ = 1.36...1.38 Nm, nn = 3000...9000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 2.35...2.37 Nm, nn = 3000...9000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 3.10...3.15 Nm, nn = 3000...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	
	AMP8041	AMP8042	AMP8043	
	M ₀ = 2.35...2.40 Nm, nn = 3000...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 3.84...4.10 Nm, nn = 2500...7000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 5.30...5.40 Nm, nn = 2500...5000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	
AMP8555, distributed servo drives, higher rotor inertia	AMP8051	AMP8052	AMP8053	AMP8054
	M ₀ = 4.40...4.60 Nm, nn = 2500...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 7.60 Nm, nn = 2000...4000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 9.60...10.20 Nm, nn = 2000...4000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 11.8 Nm, nn = 2000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion
	AMP8531	AMP8532	AMP8533	
AMP8555, distributed servo drives, higher rotor inertia	M ₀ = 1.36...1.38 Nm, nn = 3000...9000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 2.35...2.37 Nm, nn = 3000...9000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 3.10...3.15 Nm, nn = 3000...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	
	AMP8541	AMP8542	AMP8543	
	M ₀ = 2.35...2.40 Nm, nn = 3000...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 3.84...4.10 Nm, nn = 2500...7000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 4.70...5.40 Nm, nn = 2500...7000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	
AMP8555, distributed servo drives, higher rotor inertia	AMP8551	AMP8552	AMP8553	
	M ₀ = 4.40...4.60 Nm, nn = 2500...8000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 5.60...7.60 Nm, nn = 2000...7300 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	M ₀ = 9.60...10.20 Nm, nn = 2000...4000 min ⁻¹ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	

The System Company

MX-System®

For the first time in machine and system engineering, the MX-System enables completely control cabinet-free automation solutions. By consistently combining, applying and further developing Beckhoff's expertise, a holistic, modular pluggable system has been created. The combination of MX-System baseplate and MX-System function modules resulting from the modular construction kit combines all tasks and features of a control cabinet: energy supply, fuse protection and distribution, generation and monitoring of auxiliary voltages, sequence control with the inputs and outputs, control of motors and actuators as well as the connection level for the field devices. The full system integration of all machine functionalities is achieved via freely selectable IPC, I/O, drive, relay and system modules, which can be configured and combined suitable for the specific application.

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Baseplates 120

- basis of the MX-System
- real-time Ethernet performance retained into each module
- standardized interfaces
- integrated housekeeping functions

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IPC modules 122

- robust industrial PCs of various performance classes
- control of the function modules
- fanless design
- Microsoft Windows or TwinCAT/BSD

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I/O modules 123

- modules for all signal types and directions
- integrated electronic fuse
- diagnostic functions as well as diverse setting options

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Drive modules 125

- compact multi-axis systems for drives of all kinds
- frequency inverter for controlling three-phase asynchronous motors
- servo drives for controlling synchronous servomotors
- DC link power supplies and capacitors

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Relay modules 126

- direct switching of high outputs
- relay modules for direct switching of lighting or fans
- direct motor starters and reversing starters for operating three-phase asynchronous motors
- solid-state relay

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System modules 127

- power distribution and fieldbus connection
- modules for power infeed and power output
- power supplies, switches and UPS

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- designed for the greatest possible resistance over a long period of time
- distribution of voltage and EtherCAT via standardized connectors
- assembly and wiring in the shortest possible time thanks to the modular design principle
- flexible and precisely adaptable to production requirements
- advantages throughout the entire machine life cycle with the MX-System

Baseplates

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MBxxxx Baseplates				
Slots	1-row	2-row		3-row
6	MB1106-0000-0000 data slots	MB2106-0000-0000 data and power slots		
8	MB1108-0000-0000 data slots	MB2108-0000-0000 data and power slots	MB2108-0000-4000 data and power slots (8 + 4, 4)	
10	MB1110-0000-0000 data slots	MB2110-0000-0000 data and power slots	MB2110-0000-4000 data and power slots (10 + 4, 6)	
		MB2110-0000-6000 data and power slots (10 + 6, 4)		
12	MB1112-0000-0000 data slots	MB2112-0000-0000 data and power slots	MB2112-0000-4000 data and power slots (12 + 4, 8)	MB3112-0000-0000 data and power slots (12 + 12, 12)
		MB2112-0000-6000 data and power slots (12 + 6, 6)	MB2112-0000-8000 data and power slots (12 + 8, 4)	
14		MB2114-0000-0000 data and power slots	MB2114-0000-4000 data and power slots (14 + 4, 10)	MB3114-0000-0000 data and power slots (14 + 14, 14)
16		MB2116-0000-0000 data and power slots	MB2116-0000-4000 data and power slots (16 + 4, 12)	MB3116-0000-0000 data and power slots (16 + 16, 16)
18		MB2118-0000-0000 data and power slots	MB2118-0000-4000 data and power slots (18 + 4, 14)	MB3118-0000-0000 data and power slots (18 + 18, 18)
		MB2118-0000-6000 data and power slots (18 + 6, 12)		
20		MB2120-0000-0000 data and power slots	MB2120-0000-4000 data and power slots (20 + 4, 16)	MB3120-0000-0000 data and power slots (20 + 20, 20)
		MB2120-0000-6000 data and power slots (20 + 6, 14)		

MBxxxx Baseplates				
Slots	1-row	2-row		3-row
22		MB2122-0000-0000 data slots	MB2122-0000-4000 data and power slots (22 + 4, 18)	MB3122-0000-0000 data and power slots (22 + 22, 22)
		MB2122-0000-6000 data and power slots (22 + 6, 16)	MB2122-0000-8000 data and power slots (22 + 8, 14)	
24		MB2124-0000-0000 data slots	MB2124-0000-4000 data and power slots (24 + 4, 20)	MB3124-0000-0000 data and power slots (24 + 24, 24)
		MB2124-0000-6000 data and power slots (24 + 6, 18)	MB2124-0000-8000 data and power slots (24 + 8, 16)	
26				MB3126-0000-0000 data and power slots (26 + 26, 26)
28				MB3128-0000-0000 data and power slots (28 + 28, 28)
30				MB3130-0000-0000 data and power slots (30 + 30, 30)
32				MB3132-0000-0000 data and power slots (32 + 32, 32)
34				MB3134-0000-0000 data and power slots (34 + 34, 34)

IPC modules

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MCxxxx IPC modules			
IPC module	Type		
	Intel Atom®	Intel® Celeron® or Intel® Core™	Arm® Cortex®-A53
	MC6015-0030-1217	MC6030-0080-2217	MC9240-0000-1217
	2 or 4 cores	4 or 6 cores	4 cores

I/O modules

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MO1xxx I/O modules, digital input				
Input voltage	8-channel			
24 V DC	MO1008-0000-1111	MO1008-0000-1112		
	M8	M12		

MO2xxx I/O modules, digital output				
Output voltage, type	4-channel		8-channel	16-channel
24 V DC	MO2024-0000-1112		MO2008-0000-1111	MO2008-0000-1112
	2.0 A, M12		0.5 A, M8	0.5 A, M12
			MO2338-0000-1111	MO2338-0000-1112
			0.5 A, M8, digital combi	0.5 A, M12, digital combi
Pneumatics	MO2414-0000-1110	MO2414-0900-1110		
	0.5 A, Festo	0.5 A, Festo, safe switching		
	MO2424-0000-1110	MO2424-0900-1110		
	0.5 A, SMC	0.5 A, SMC, safe switching		

MO3xxx I/O modules, analog input	
Type	4-channel
Multi-function, 12 bit, ±10 V, ±20 mA	MO3004-2255-1112
	single-ended, 1 ksps, M12
Temperature (RTD/TC)	MO3204-6666-1112
	16 bit, 1 ksps, M12

MO5xxx I/O modules, position measurement	
Type	2-channel
Incremental	MO5162-0000-1112
	HTL, 100 kHz, M12

Drive modules

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MO6xxx I/O modules, communication			
Type	1-channel	2-channel	4-channel
IO-Link			MO6224-0020-1112 MO6224-0039-1112 IO-Link, master, Class A, M12 IO-Link, master, Class B, M12
RS485/RS422		MO6021-0000-1112 RS422/RS485, M12, B-coded	
System	MO6071-0000-1110 license key, 2 nd generation	MO6071-0033-1110 license key, 2 nd generation, factory-installed licenses	
	MO6072-0000-1110 license key, 2 nd generation, RTC	MO6072-0033-1110 license key, 2 nd generation, factory-installed licenses, RTC	

MO7xxx I/O modules, compact drive technology			
Type	1-channel	2-channel	
Servomotor	MO7221-9016-1114 24 V DC, 7 A, B17, STO/SS1	MO7221-9016-1124 48 V DC, 7 A, B17, STO/SS1	
	MO7221-9018-1114 24 V DC, 7 A, B17, Safe Motion	MO7221-9018-1124 48 V DC, 7 A, B17, Safe Motion	
Stepper motor		MO7062-0000-1112 24 V DC, 3 A, M12	MO7062-0000-1122 48 V DC, 3 A, M12

MOx9xx I/O modules, TwinSAFE			
	2-channel	4-channel	8-channel
I/O module	MO2962-0000-1112 relay output	MO2914-0000-1112 digital output, 2 A	MO1918-0000-1112 digital input

MD3xxx Drive modules, frequency inverters		
Output current	1-channel	2-channel
1.8 A		MD3202-0100-2254 1.8 A, STO/SS1
3.4 A	MD3104-0100-2254 3.4 A, STO/SS1	

MD6xxx Drive modules, DC link power supplies	
Output current	
20 A	MD6020-0003-2345 20 A
40 A	MD6040-0003-3445 40 A

MD8xxx Drive modules, servo drives					
Output current	1-channel			2-channel	
6 A	MD8106-0100-2254 STO/SS1	MD8106-0190-2254 STO/SS1, multi-feedback interface		MD8206-0100-2254 STO/SS1	MD8206-0200-2254 Safe Motion
	MD8106-0200-2254 Safe Motion	MD8106-0290-2254 Safe Motion, multi-feedback interface			
12 A	MD8112-0100-2254 STO/SS1	MD8112-0190-2254 STO/SS1, multi-feedback interface			
	MD8112-0200-2254 Safe Motion	MD8112-0290-2254 Safe Motion, multi-feedback interface			
28 A	MD8128-0100-3255 STO/SS1	MD8128-0190-3255 STO/SS1, multi-feedback interface			
	MD8128-0200-3255 Safe Motion	MD8128-0290-3255 Safe Motion, multi-feedback interface			

MD9xxx Drive modules, capacitors	
Capacity	
2025 µF	MD9000-2025-2250 2025 µF

Relay modules

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MRxxxx Relay modules			
Category/ version	1-channel	2-channel	3-channel
Relay output			MR1307-0031-2242 7 A
Motor starter	MR3107-2001-2245 7 A	MR3203-1001-2244 2.8 A	
	MR3107-2901-2245 7 A, safe shutdown	MR3203-1901-2244 2.8 A, safe shutdown	
Solid-state relay	MR4107-1041-2245 7 A, residual current measurement		MR4307-1031-2242 7 A, residual current measurement
	MR4107-1941-2245 7 A, residual current measurement, safe shutdown		MR4307-1931-2242 7 A, residual current measurement, safe shutdown

System modules

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MSxxxx System modules					
Category/ version					
Power infeed	MS1010-0021-1114 24 V DC/10 A, 48 V DC/10 A	MS1010-1002-1334 230 V AC/10 A		MS1020-0001-1124 48 V DC/20 A	
	MS1025-0001-1145 400 V AC/25 A	MS1025-0011-2245 24 V DC/10A, 400 V AC/25 A		MS1132-2001-2349 400 V AC/32 A	MS1132-2201-2349 400 V AC/32 A, energy measurement, residual current measurement
	MS1163-2001-3449 400 V AC/63 A	 MS1163-2201-3449 400 V AC/63 A, energy measurement, residual current measurement	 MS1332-2001-2349 400 V AC/32 A	MS1332-2201-2349 400 V AC/32 A, energy measurement, residual current measurement	
	MS1363-2001-3449 400 V AC/63 A	 MS1363-2201-3449 400 V AC/63 A, energy measurement, residual current measurement			
EtherCAT power infeed	MS2204-0002-1112 24 V DC/4 A	MS2210-0021-1114 24 V DC/10 A			
	MS2625-0011-2245 24 V DC/10 A, 400 V AC/25 A	MS2625-1001-2245 400 V AC/25 A			
Power output	MS3010-1002-1145 400 V AC/10 A	MS3010-1003-1114 2 x 24 V DC/10 A		MS3010-1023-1114 24 V DC/10 A, 48 V DC/10 A	
	MS3025-1001-2245 400 V AC/25 A	MS3025-1011-2245 24 V DC/10 A, 400 V AC/25 A			
EtherCAT power output	MS4208-2003-1112 24 V DC/2 x 4 A	MS4208-2903-1112 24 V DC/2 x 4 A, safe shutdown	 MS4210-1003-1114 2 x 24 V DC/10 A	MS4210-1023-1114 24 V DC/10 A, 48 V DC/10 A	
	MS4306-2003-1111 24 V DC/2 x 3 A, 2-channel	MS4625-1001-2245 400 V AC/25 A	MS4625-1011-2245 24 V DC/10 A, 400 V AC/25 A		
Power supplies	MS6010-2100-2240 48 V DC/10 A, 400 V AC	MS6010-2100-2250 48 V DC/10 A, 600 V DC	 MS6020-1100-2240 24 V DC/20 A, 400 V AC	MS6020-1100-2250 24 V DC/20 A, 600 V DC	
Ethernet switches	MS7204-0000-1112 24 V DC	 MS7801-0000-1117 CP-Link, 24 V DC			
UPS	MS8132-0120-1212 24 V DC				
Empty housings	MS9100-2020-2209 24 V DC	MS9100-2022-2209 24 V DC, 400/480 V AC			

The Vision Company

As a specialist for PC-based control technology, Beckhoff consistently aims to integrate all machine functionalities into one control platform. With TwinCAT Vision, this has included image processing within software since 2017. The machine vision product spectrum is now complete thanks to the introduction of the comprehensive hardware range. Machine builders and end users thus have a complete image processing system at their disposal that covers all the necessary components from software to illumination which, integrated into the system, provides users with significant competitive advantages.

► www.beckhoff.com/vision



Full scalability of the vision system

All components are optimally matched to each other and can be combined according to the modular principle to suit the vision application.

Cameras 130

- 2.5 Gbit/s area scan cameras
 - robust IP65/67 anodized aluminum housing with flexible mounting options
 - color or monochrome image sensors with a resolution of 2.3 to 24 MP
 - full synchronization with all EtherCAT-based machine processes
 - via distributed clocks
- www.beckhoff.com/cameras

Lenses 131

- robust and universal thanks to C-mount connection
 - vibration/shock resistant up to 10 g
 - for up to 2.0 µm pixel size and image circle diameters of 11 and 19.3 mm
 - broadband anti-reflection coating for the visible spectrum (VIS) and near infrared region (NIR)
- www.beckhoff.com/lenses

Illumination 132

- multicolor LED panel, ring illumination or bar light in IP65/67
 - spectrally complete white light
 - spectrally adjustable pulse mode
 - simple wiring and full EtherCAT integration
 - precisely synchronized through distributed clocks
- www.beckhoff.com/illumination

Units 133

- unit consisting of camera, ring illumination and focusable optics in IP65/67 aluminum anodized housing
 - color or monochrome image sensors with a resolution of 2.3 to 5 MP
 - directly integrated into the PC-based control technology
 - focus adjustment during runtime
- www.beckhoff.com/units

TwinCAT Vision 111

- program and configure vision applications directly in TwinCAT Engineering
 - superior real-time applications: PLC, motion control, robotics, high-end measurement technology and vision on one platform
 - hardware-independent and open
- www.beckhoff.com/twincat-vision



- complete hardware portfolio for industrial image processing
- ultra-fast EtherCAT performance and robust design
- perfect synchronization with any process
- simple, direct integration into the control
- open and scalable machine vision system

Cameras

► www.beckhoff.com/cameras



VCS2000 Area scan cameras, 2.5 Gbit/s				
Number of pixels	Spectral sensitivity monochrome	color	polarization/monochrome	polarization/color
2.3...3.1 MP	VCS2000-0200 2.3 MP, 129 fps, Δpx = 3.45 μm	VCS2001-0200 2.3 MP, 129 fps, Δpx = 3.45 μm		
	VCS2000-0300 3.1 MP, 55 fps, Δpx = 3.45 μm	VCS2001-0300 3.1 MP, 55 fps, Δpx = 3.45 μm		
5.0...8.1 MP	VCS2000-0500 5.0 MP, 35 fps, Δpx = 3.45 μm	VCS2001-0500 5.0 MP, 35 fps, Δpx = 3.45 μm	VCS2002-0500 5.0 MP, 35 fps, Δpx = 3.45 μm	VCS2003-0500 5.0 MP, 35 fps, Δpx = 3.45 μm
	VCS2030-0500 5.1 MP, 58 fps, Δpx = 2.74 μm	VCS2031-0500 5.1 MP, 58 fps, Δpx = 2.74 μm		
	VCS2020-0800 8.1 MP, 35 fps, Δpx = 2.74 μm	VCS2021-0800 8.1 MP, 35 fps, Δpx = 2.74 μm		
12.4...16.2 MP	VCS2020-1200 12.4 MP, 24 fps, Δpx = 2.74 μm	VCS2021-1200 12.4 MP, 24 fps, Δpx = 2.74 μm		
	VCS2030-1600 16.2 MP, 18 fps, Δpx = 2.74 μm	VCS2031-1600 16.2 MP, 18 fps, Δpx = 2.74 μm		
20.4...24.6 MP	VCS2030-2000 20.4 MP, 14 fps, Δpx = 2.74 μm	VCS2031-2000 20.4 MP, 14 fps, Δpx = 2.74 μm		
	VCS2030-2400 24.6 MP, 12 fps, Δpx = 2.74 μm	VCS2031-2400 24.6 MP, 12 fps, Δpx = 2.74 μm		

Specified values for the product: number of pixels, frame rate, pixel size

Lenses

► www.beckhoff.com/lenses



VOS2000



VOS3000

VOS2000 Lenses	
Focal length	Image circle Ø 11 mm
6 mm	VOS2000-0625 2.0 μm, f = 6 mm, f/2.5
8 mm	VOS2000-0822 2.0 μm, f = 8 mm, f/2.2
12 mm	VOS2000-1218 2.0 μm, f = 12 mm, f/1.8
16 mm	VOS2000-1616 2.0 μm, f = 16 mm, f/1.6
25 mm	VOS2000-2516 2.0 μm, f = 25 mm, f/1.6
35 mm	VOS2000-3522 2.0 μm, f = 35 mm, f/2.2
50 mm	VOS2000-5028 2.0 μm, f = 50 mm, f/2.8

VOS3000 Lenses	
Focal length	Image circle Ø 19.3 mm
12 mm	VOS3000-1232 2.0 μm, f = 12 mm, f/3.2
16 mm	VOS3000-1632 2.0 μm, f = 16 mm, f/3.2
25 mm	VOS3000-2532 2.0 μm, f = 25 mm, f/3.2
35 mm	VOS3000-3528 2.0 μm, f = 35 mm, f/2.8

Specified values for the product: pixel size, focal length, starting aperture

Illumination

► www.beckhoff.com/illumination



VIP2000



VIR2000



VIB2000

VIP2000 Panel illumination			
Light emitting surface (W x H)	Light color OGB-IR850		
100 x 100 mm	VIP2000-1010 wide beam, 90°	VIP2010-1010 narrow beam, 50°	i
150 x 150 mm	VIP2000-1515 wide beam, 90°	VIP2010-1515 narrow beam, 50°	i
200 x 200 mm	VIP2000-2020 wide beam, 90°	VIP2010-2020 narrow beam, 50°	i
250 x 250 mm	VIP2000-2525 wide beam, 90°	VIP2010-2525 narrow beam, 50°	i
300 x 300 mm	VIP2000-3030 wide beam, 90°	VIP2010-3030 narrow beam, 50°	i

VIR2000 Ring illumination			
Light emitting surface (W x H)	Light color OGB-IR850		
100 x 100 mm	VIR2000-1010 wide beam, 90°	i VIR2010-1010 narrow beam, 50°	i
150 x 150 mm	VIR2000-1515 wide beam, 90°	i VIR2010-1515 narrow beam, 50°	i
200 x 200 mm	VIR2000-2020 wide beam, 90°	i VIR2010-2020 narrow beam, 50°	i
250 x 250 mm	VIR2000-2525 wide beam, 90°	VIR2010-2525 narrow beam, 50°	
300 x 300 mm	VIR2000-3030 wide beam, 90°	VIR2010-3030 narrow beam, 50°	

VIB2000 Bar light			
Light emitting surface (W x H)	Light color OGB-IR850		
150 x 50 mm	VIB2000-0155 wide beam, 90°	i VIB2010-0155 narrow beam, 50°	i
200 x 50 mm	VIB2000-0205 wide beam, 90°	i VIB2010-0205 narrow beam, 50°	i
250 x 50 mm	VIB2000-0255 wide beam, 90°	i VIB2010-0255 narrow beam, 50°	i
300 x 50 mm	VIB2000-0305 wide beam, 90°	i VIB2010-0305 narrow beam, 50°	i
400 x 50 mm	VIB2000-0405 wide beam, 90°	i VIB2010-0405 narrow beam, 50°	i
500 x 50 mm	VIB2000-0505 wide beam, 90°	i VIB2010-0505 narrow beam, 50°	i
600 x 50 mm	VIB2000-0605 wide beam, 90°	i VIB2010-0605 narrow beam, 50°	i
800 x 50 mm	VIB2000-0805 wide beam, 90°	i VIB2010-0805 narrow beam, 50°	i
1000 x 50 mm	VIB2000-1005 wide beam, 90°	i VIB2010-1005 narrow beam, 50°	i

Specified values for the product: light distribution, beam angle

Units

► www.beckhoff.com/units



VUI2000 Units		
Number of pixels	Spectral sensitivity monochrome	color
2.3 MP	VUI2000-0208 2.3 MP, f = 8 mm, 129 fps, Δpx = 3.45 μm	VUI2001-0208 2.3 MP, f = 8 mm, 129 fps, Δpx = 3.45 μm
	VUI2000-0212 2.3 MP, f = 12 mm, 129 fps, Δpx = 3.45 μm	VUI2001-0212 2.3 MP, f = 12 mm, 129 fps, Δpx = 3.45 μm
	VUI2000-0216 2.3 MP, f = 16 mm, 129 fps, Δpx = 3.45 μm	VUI2001-0216 2.3 MP, f = 16 mm, 129 fps, Δpx = 3.45 μm
3.1 MP	VUI2000-0308 3.1 MP, f = 8 mm, 55 fps, Δpx = 3.45 μm	VUI2001-0308 3.1 MP, f = 8 mm, 55 fps, Δpx = 3.45 μm
	VUI2000-0312 3.1 MP, f = 12 mm, 55 fps, Δpx = 3.45 μm	VUI2001-0312 3.1 MP, f = 12 mm, 55 fps, Δpx = 3.45 μm
	VUI2000-0316 3.1 MP, f = 16 mm, 55 fps, Δpx = 3.45 μm	VUI2001-0316 3.1 MP, f = 16 mm, 55 fps, Δpx = 3.45 μm
5.0 MP	VUI2000-0512 5.0 MP, f = 12 mm, 35 fps, Δpx = 3.45 μm	VUI2001-0512 5.0 MP, f = 12 mm, 35 fps, Δpx = 3.45 μm
	VUI2000-0516 5.0 MP, f = 16 mm, 35 fps, Δpx = 3.45 μm	VUI2001-0516 5.0 MP, f = 16 mm, 35 fps, Δpx = 3.45 μm

Specified values for the product: number of pixels, focal length, frame rate, pixel size



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