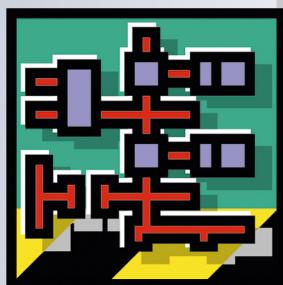


Manual | EN

TS6421-0030

TwinCAT 2 | XML Data Server CE

Supplement | Communication





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# 1 Foreword

## 1.1 Notes on the documentation

This description is only intended for the use of trained specialists in control and automation engineering who are familiar with applicable national standards.

It is essential that the documentation and the following notes and explanations are followed when installing and commissioning the components.

It is the duty of the technical personnel to use the documentation published at the respective time of each installation and commissioning.

The responsible staff must ensure that the application or use of the products described satisfy all the requirements for safety, including all the relevant laws, regulations, guidelines and standards.

### Disclaimer

The documentation has been prepared with care. The products described are, however, constantly under development.

We reserve the right to revise and change the documentation at any time and without prior announcement. No claims for the modification of products that have already been supplied may be made on the basis of the data, diagrams and descriptions in this documentation.

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EP1590927, EP1789857, EP1456722, EP2137893, DE102015105702  
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### Safety regulations

Read the following explanations for your safety.

Always observe and follow product-specific safety instructions, which you may find at the appropriate places in this document.

### Exclusion of liability

All the components are supplied in particular hardware and software configurations which are appropriate for the application. Modifications to hardware or software configurations other than those described in the documentation are not permitted, and nullify the liability of Beckhoff Automation GmbH & Co. KG.

### Personnel qualification

This description is only intended for trained specialists in control, automation, and drive technology who are familiar with the applicable national standards.

### Signal words

The signal words used in the documentation are classified below. In order to prevent injury and damage to persons and property, read and follow the safety and warning notices.

### Personal injury warnings

#### DANGER

Hazard with high risk of death or serious injury.

#### WARNING

Hazard with medium risk of death or serious injury.

#### CAUTION

There is a low-risk hazard that could result in medium or minor injury.

### Warning of damage to property or environment

#### NOTICE

The environment, equipment, or data may be damaged.

### Information on handling the product



This information includes, for example:  
recommendations for action, assistance or further information on the product.

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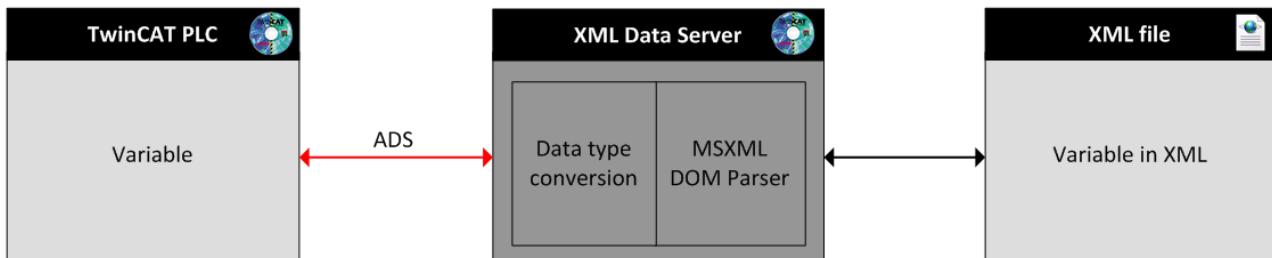
In addition, the recommendations from Beckhoff regarding appropriate protective measures should be observed. Further information regarding information security and industrial security can be found in our <https://www.beckhoff.com/secguide>.

Beckhoff products and solutions undergo continuous further development. This also applies to security functions. In light of this continuous further development, Beckhoff expressly recommends that the products are kept up to date at all times and that updates are installed for the products once they have been made available. Using outdated or unsupported product versions can increase the risk of cyber threats.

To stay informed about information security for Beckhoff products, subscribe to the RSS feed at <https://www.beckhoff.com/secinfo>.

## 2 Overview

The TwinCAT XML Data Server enables initializing of TwinCAT PLC variables with data stored in an XML file, or formatted saving of PLC variables in an XML file. The structure of a variable in the XML document matches the structure of the variables in the PLC. This enables individual sub elements of a variable to be accessed directly. Only those sub elements (elements of a structure or an array) are transferred that are also defined in the XML file. When the PLC variables are written, missing elements can optionally be added.



### 3 System Requirements

Technical Data	TS6421 XML Data Server
Programming System	Windows NT/2000/XP/Vista/7 PC (x86-kompatibel)
Target System	Windows CE on x86 or arm
Min. TwinCAT Version	2.10.0
Min. TwinCAT Level	TwinCAT PLC

## 4 Installation

This part of the documentation gives a step-by-step explanation of the TwinCAT 3 XML Data Server setup process for Windows based operating systems. The following topics are part of this document:

- Downloading the setup file
- Installation on a host computer
- Transferring the setup file to the Windows CE device
- Executing the setup on the Windows CE device

### Downloading the setup file

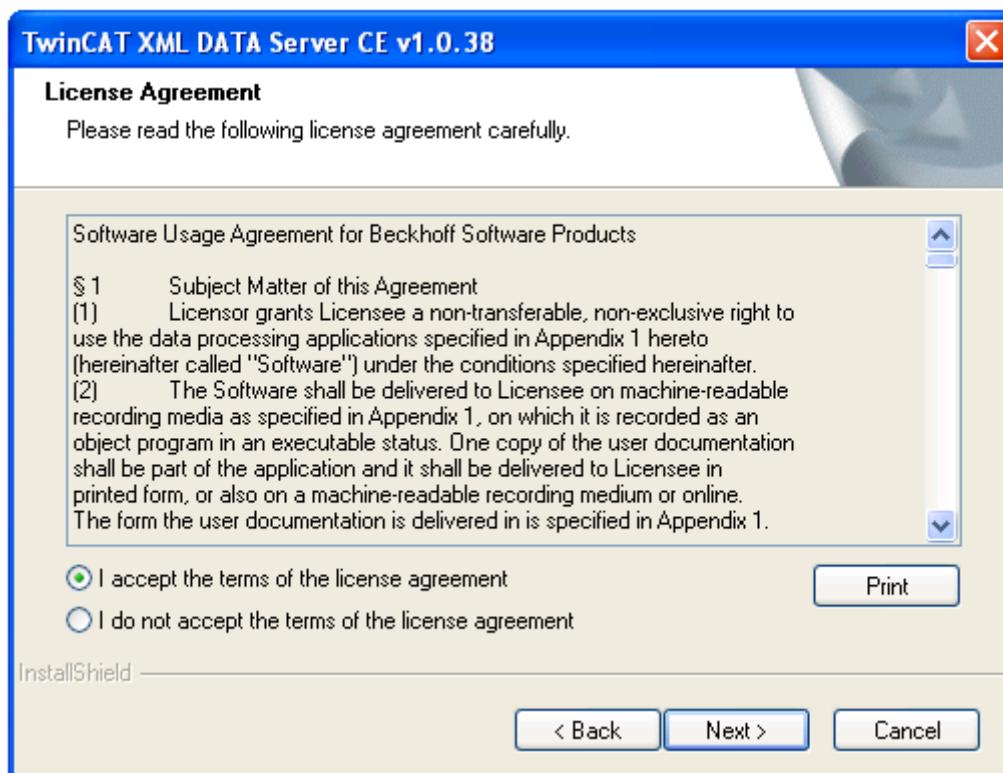
Like many other TwinCAT Supplement products, XML Data Server CE is available for download via the Beckhoff FTP-Server. The download represents the latest version. To download the setup file, please perform the following steps:

- Start a FTP-Client software of your choice, for example FileZilla or Total Commander
- Open a connection to [TwinCAT Supplement System](#).
- Select TS6421-0030 TwinCAT XML Data Server CE and download the file via the download-cart.

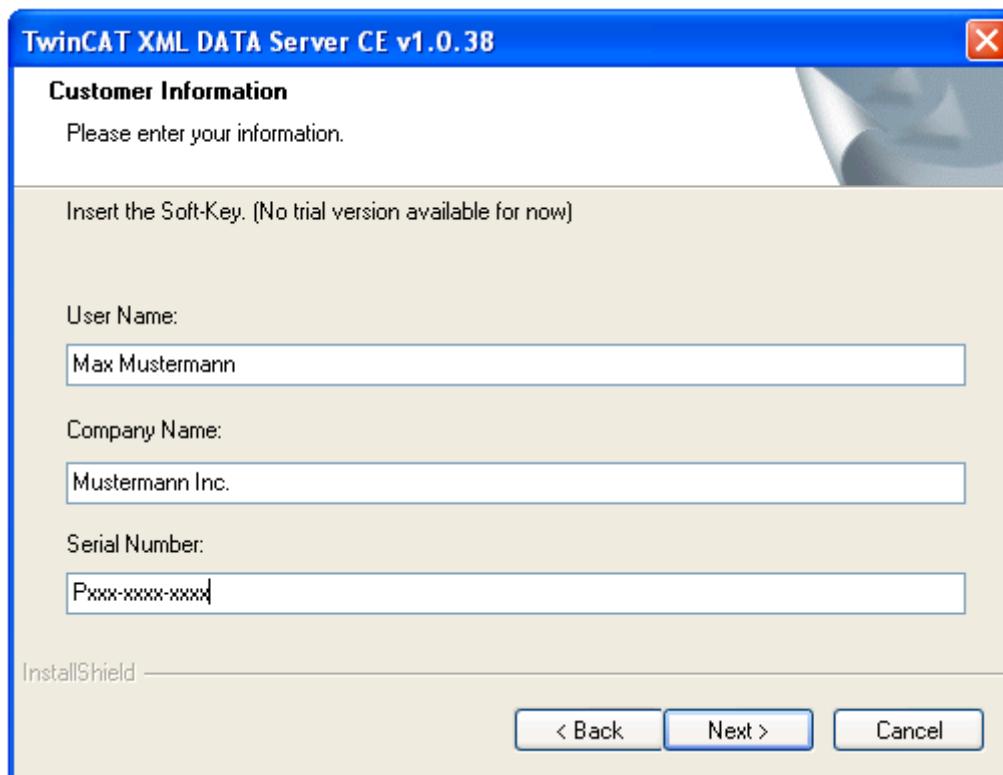
### Installation on a host Computer

To install the Supplement, please perform the following steps:

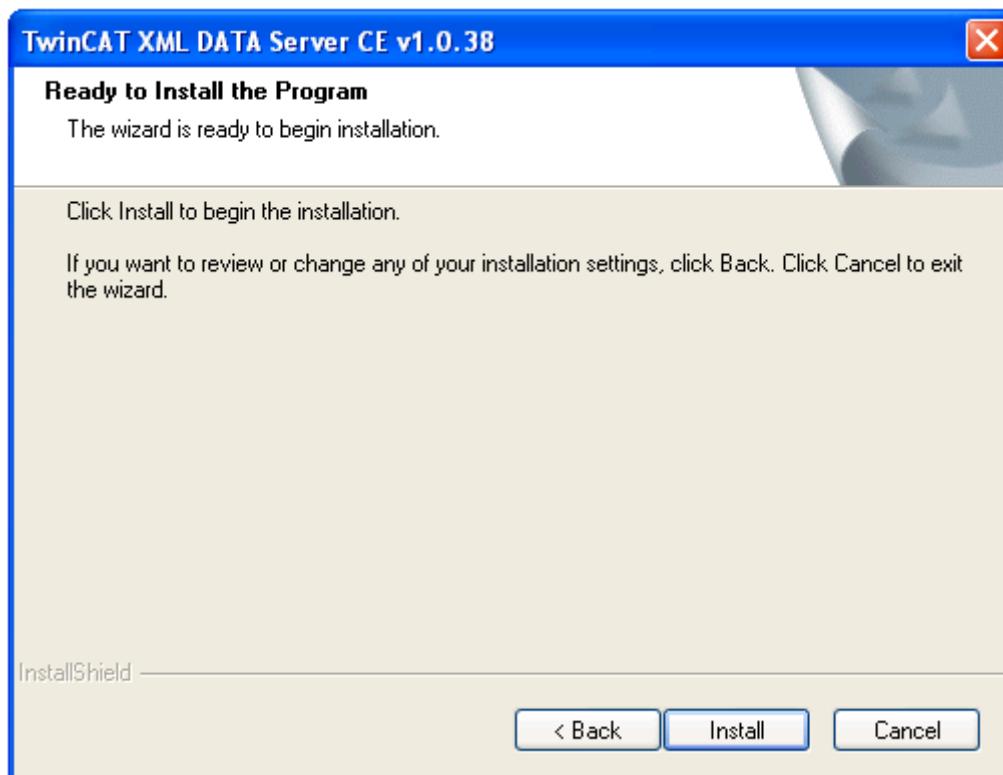
- Double-click the downloaded setup file. **Please note:** Under Windows 32-bit/64-bit, please start the installation with "Run as Administrator" by right-clicking the setup file and selecting the corresponding option in the context menu.
- Click on "Next" and accept the license agreement.



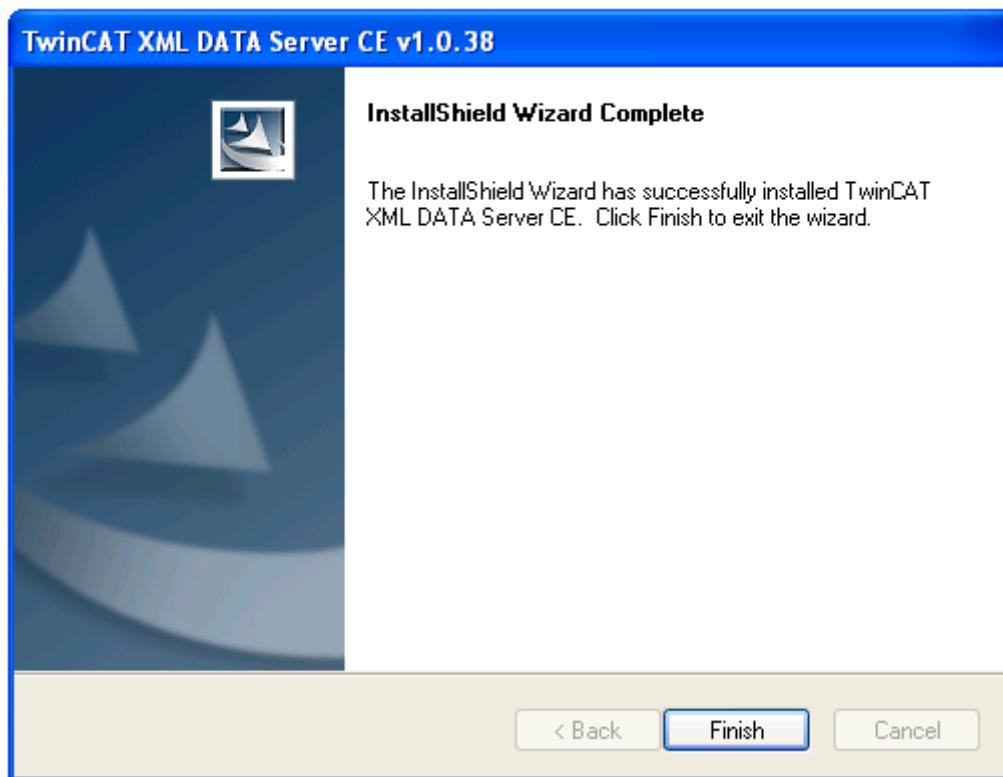
- Enter your user information:



- Click on "Next" to start the installation.



- Select "Finish" to end the setup process.



After installation, the setup files for Windows CE can be found in the directory "...\\TwinCAT\\CE". This directory contains two setup files:

- **TcXmlDataSrvCe.I586**: XML Data Server CE for x86 based CPUs (e.g., CX10xx, CP62xx, C69xx, ...)
- **TcXmlDataSrvCe.ARM**: XML Data Server CE for ARM based CPUs (e.g., CX9001, CX9010, CP6608, ...)

### Transferring the setup file to the Windows CE device

Transfer the corresponding setup file to your CE device. This can be done in the following ways:

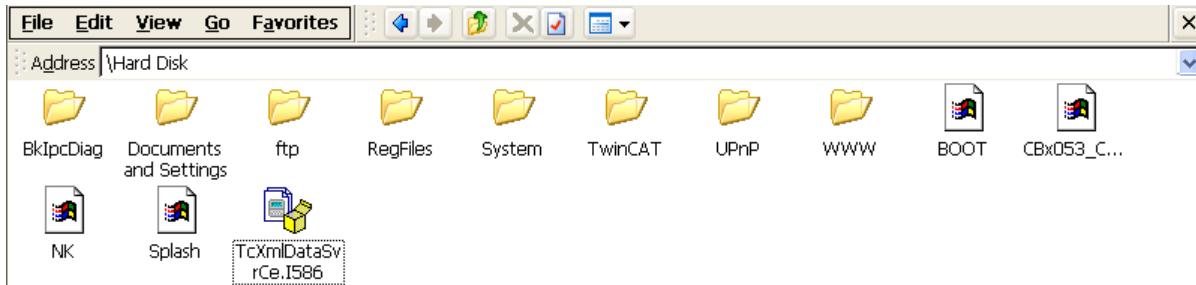
- via a Shared Folder
- via the integrated FTP-Server
- via ActiveSync
- via CF card / SD card / USB flash drive

Further information can be found in the "Windows CE" section in our Infosys documentation system.

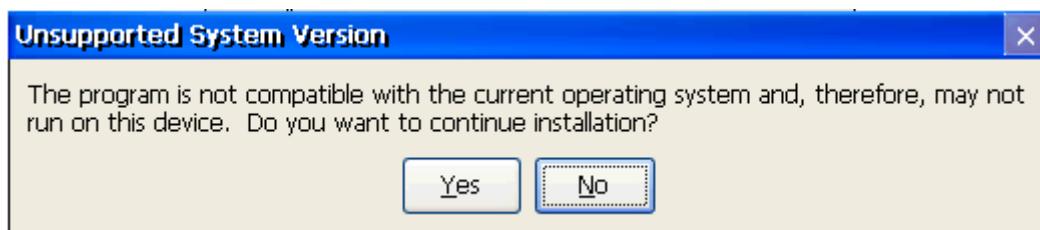
### Executing the setup on the Windows CE device

Now the transferred setup file "**TcXmlDataSrvCe.xxxx.CAB**" needs to be executed on the CE device. Please perform the following steps:

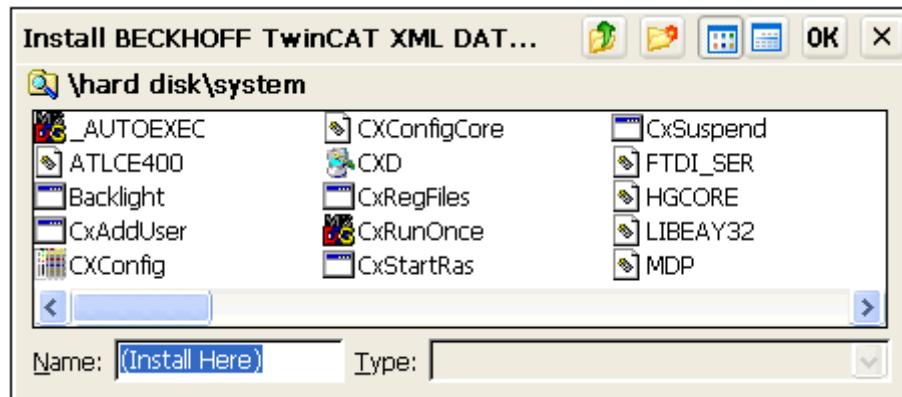
- Navigate to the directory where you transferred the setup file to.



- Double-click the CAB file. If you get a message box stating that this program is not compatible with the current operating system, please re-check if you used the correct CAB-file (ARM, I586) for your IPC/ Embedded-PC.
- If you are sure that the CAB-file corresponds to the Embedded-PC/IPC, please acknowledge this message box with "Yes".



- Select "\Hard Disk\System" as the destination directory.



- To start the installation, click on "Ok".

After installation, the setup file will be deleted automatically. In order to use the XML Data Server you have to restart your CE device.

## 5 PLC API

The PLC library is supplied with the TwinCAT XML Data Server and copied into folder ...\\TwinCAT\\PLC\\Lib during installation.

There are two function blocks for reading variables from the XML file:

- FB\_XmlSrvRead
- FB\_XmlSrvReadByName

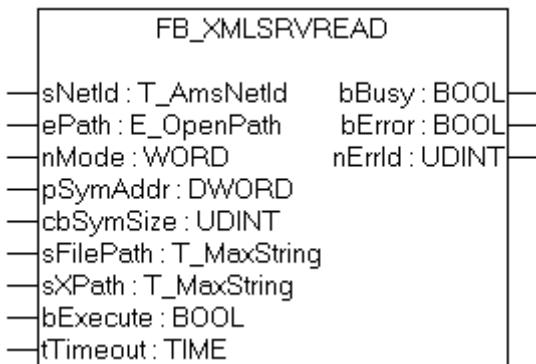
and two function blocks for writing PLC variables to the XML file:

- FB\_XmlSrvWrite
- FB\_XmlSrvWriteByName

The first version (FB\_XMLSrvRead, FB\_XMLSrvWrite) uses the address and the size of the PLC variable for specifying the variable. The second version (FB\_XMLSrvReadByName, FB\_XMLSrvWriteByName) uses the symbol name for specifying the variable. The first version offers higher performance, although it is only supported from Build 1235 of TwinCAT version 2.10. For older TwinCAT versions only the function blocks FB\_XMLSrvReadByName and FB\_XMLSrvWriteByName can be used. In addition, the path of the XML file and the location of the variables within the XML document has to be transferred as input parameter to the function blocks in XPath format.

### 5.1 Function blocks

#### 5.1.1 FB\_XmlSrvRead



The function block FB\_XmlSrvRead can be used to initialize a PLC variable with data from an XML file. The input variable sXPath has to point to a valid node in the XML file specified via sFilePath. The symbol to be initialized is identified unambiguously by the symbol address and size.

#### VAR\_INPUT

```

VAR_INPUT
  sNetId      : T_AmsNetId;
  ePath       : E_OpenPath := PATH_GENERIC;
  nMode       : WORD := XMLSRV_SKIPMISSING;
  pSymAddr   : DWORD;
  cbSymSize  : UDINT;
  sFilePath  : T_MaxString;
  sXPath     : T_MaxString;
  bExecute   : BOOL;
  tTimeout   : TIME := T#60s;
END_VAR

```

**sNetId:** String containing the network address of the TwinCAT XML Data Server. For the local computer (default) an empty string may be specified.

**ePath:** This input can be used to select a TwinCAT system path on the target device for opening the file.

**nMode:** This input can be used to influence how the XML file is analyzed. For the XmlSrvRead command, only XMLSRV\_SKIPMISSING mode is currently supported.

**pSymAddr:** Address of the PLC variable to which the data from the XML file are to be written.

**cbSymSize:** Size of the PLC variable to which the data from the XML file are to be written.

**sFilePath:** Contains the path and file name for the file to be opened. Note: The path can only point to the local computer's file system! This means that network paths cannot be used here!

**sXPath:** Contains the address of the tag in the XML document from which the data are to be written. The address must be a valid XPath instruction. The name of the tag must be different from the name of the symbol.

**bExecute:** The block is activated by a rising edge at this input.

**tTimeout:** Maximum time allowed for the execution of the function block.

#### VAR\_OUTPUT

```
VAR_OUTPUT
  bBusy    : BOOL;
  bError   : BOOL;
  nErrId   : UDINT;
END_VAR
```

**bBusy:** This output is set when the function block is activated. It remains set until feedback is received.

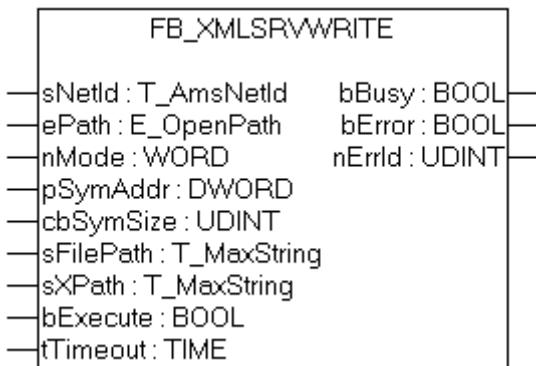
**bError:** This output is set up after the bBusy output has been reset if there has been an error in transmission of the command.

**nErrId :** If the bError output is set, this parameter returns the TwinCAT XML Data Server error number.

#### Requirements

Development environment	Target system type	PLC libraries to be linked
TwinCAT v2.10.0 from Build 1235	PC or CX (x86, ARM)	TcXmlDataSrv.Lib ( Standard.Lib; TcBase.Lib; TcSystem.Lib are included automatically )

### 5.1.2 FB\_XmlSrvWrite



The function block FB\_XmlSrvWrite can be used for writing the value of a PLC variable into an XML file. The input variable sXPath must point to a valid node in the XML file specified via sFilePath. The symbol to be written is identified unambiguously by the symbol address and size.

#### VAR\_INPUT

```
VAR_INPUT
  sNetId      : T_AmsNetId;
  ePath       : E_OpenPath := PATH_GENERIC;
```

```

nMode      : WORD := XMLSRV_SKIPMISSING;
pSymAddr   : DWORD;
cbSymSize  : UDINT;
sFilePath  : T_MaxString;
sXPath     : T_MaxString;
bExecute   : BOOL;
tTimeout   : TIME := T#60s;
END_VAR

```

**sNetId:** String containing the network address of the TwinCAT XML Data Server. For the local computer (default) an empty string may be specified.

**ePath:** This input can be used to select a TwinCAT system path on the target device for opening the file.

**nMode:** This input can be used to specify which data are written to the XML file. XMLSRV\_SKIPMISSING and XMLSRV\_ADDMISSING mode are available for the XmlSrvWrite command. In XMLSRV\_SKIPMISSING mode, only those sub elements of a PLC symbol that already exist in the XML file are written to the XML file. In XMLSRV\_ADDMISSING mode, missing sub elements are added to the XML file.

**pSymAddr:** Address of the PLC variable to be written to the XML file.

**cbSymSize:** Size of the PLC variable to be written to the XML file.

**sFilePath:** Contains the path and file name for the file to be opened. Note: The path can only point to the local computer's file system! This means that network paths cannot be used here!

**sXPath:** Contains the address of the tag in the XML document from which the data are to be written. The address must be a valid XPath instruction. The name of the tag must be different from the name of the symbol.

**bExecute:** The block is activated by a rising edge at this input.

**tTimeout:** Maximum time allowed for the execution of the function block.

## VAR\_OUTPUT

```

VAR_OUTPUT
  bBusy    : BOOL;
  bError   : BOOL;
  nErrId   : UDINT;
END_VAR

```

**bBusy:** This output is set when the function block is activated. It remains set until feedback is received.

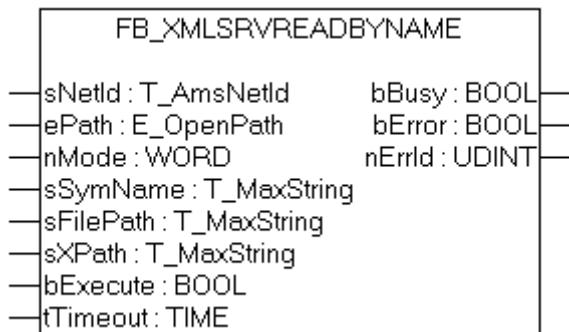
**bError:** This output is set up after the bBusy output has been reset if there has been an error in transmission of the command.

**nErrId :** If the bError output is set, this parameter returns the TwinCAT XML Data Server error number.

## Requirements

Development environment	Target system type	PLC libraries to be linked
TwinCAT v2.10.0 from Build 1235	PC or CX (x86, ARM)	TcXmlDataSrv.Lib ( Standard.Lib; TcBase.Lib; TcSystem.Lib are included automatically )

## 5.1.3 FB\_XmlSrvReadByName



The function block FB\_XmlSrvReadByName can be used to initialize a PLC variable with data from an XML file. The input variable sXPath must point to a valid node in the XML file specified via sFilePath. The symbol to be initialized is identified unambiguously by the symbol name.

### VAR\_INPUT

```

VAR_INPUT
  sNetId      : T_AmsNetId;
  ePath       : E_OpenPath := PATH_GENERIC;
  nMode       : WORD := XMLSRV_SKIPMISSING;
  sSymName    : T_MaxString;
  sFilePath   : T_MaxString;
  sXPath      : T_MaxString;
  bExecute    : BOOL;
  tTimeout    : TIME := T#60s;
END_VAR
  
```

**sNetId:** String containing the network address of the TwinCAT XML Data Server. For the local computer (default) an empty string may be specified.

**ePath:** This input can be used to select a TwinCAT system path on the target device for opening the file.

**nMode:** This input can be used to influence how the XML file is analyzed. For the XmlSrvReadByName command, only XMLSRV\_SKIPMISSING mode is currently supported.

**sSymName:** Name of the PLC symbol to which the data from the XML file are to be written.

**sFilePath:** Contains the path and file name for the file to be opened. Note: The path can only point to the local computer's file system! This means that network paths cannot be used here!

**sXPath:** Contains the address of the tag in the XML document from which the data are to be written. The address must be a valid XPath instruction. The name of the tag must be different from the name of the symbol.

**bExecute:** The block is activated by a rising edge at this input.

**tTimeout:** Maximum time allowed for the execution of the function block.

### VAR\_OUTPUT

```

VAR_OUTPUT
  bBusy     : BOOL;
  bError    : BOOL;
  nErrId   : UDINT;
END_VAR
  
```

**bBusy:** This output is set when the function block is activated. It remains set until feedback is received.

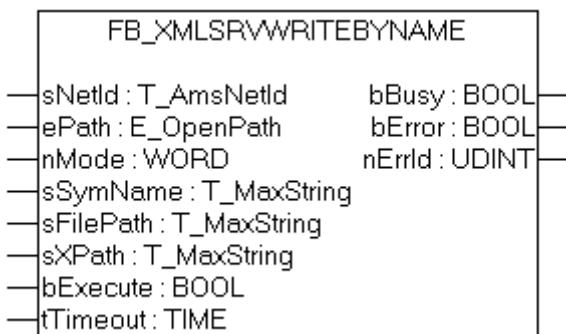
**bError:** This output is set up after the bBusy output has been reset if there has been an error in transmission of the command.

**nErrId :** If the bError output is set, this parameter returns the TwinCAT XML Data Server error number.

## Requirements

Development environment	Target system type	PLC libraries to be linked
TwinCAT v2.10.0	PC or CX (x86, ARM)	TcXmlDataSrv.Lib ( Standard.Lib; TcBase.Lib; TcSystem.Lib are included automatically )

## 5.1.4 FB\_XmlSrvWriteByName



The function block FB\_XmlSrvWriteByName can be used for writing the value of a PLC variable into an XML file. The input variable sXPath must point to a valid node in the XML file specified via sFilePath. The symbol to be written is identified unambiguously by the symbol name.

### VAR\_INPUT

```

VAR_INPUT
  sNetId      : T_AmsNetId;
  ePath        : E_OpenPath := PATH_GENERIC;
  nMode        : WORD := XMLSRV_SKIPMISSING;
  sSymName    : T_MaxString;
  sFilePath   : T_MaxString;
  sXPath      : T_MaxString;
  bExecute    : BOOL;
  tTimeout    : TIME := T#60s;
END_VAR
  
```

**sNetId:** String containing the network address of the TwinCAT XML Data Server. For the local computer (default) an empty string may be specified.

**ePath:** This input can be used to select a TwinCAT system path on the target device for opening the file.

**nMode:** This input can be used to specify which data are written to the XML file. XMLSRV\_SKIPMISSING and XMLSRV\_ADDMISSING mode are available for the XmlSrvWriteByte command. In XMLSRV\_SKIPMISSING mode, only those sub elements of a PLC symbol that already exist in the XML file are written to the XML file. In XMLSRV\_ADDMISSING mode, missing sub elements are added to the XML file.

**sSymName:** Name of the PLC symbol to be written to the XML file.

**sFilePath:** Contains the path and file name for the file to be opened. Note: The path can only point to the local computer's file system! This means that network paths cannot be used here!

**sXPath:** Contains the address of the tag in the XML document from which the data are to be written. The address must be a valid XPath instruction. The name of the tag must be different from the name of the symbol.

**bExecute:** The block is activated by a rising edge at this input.

**tTimeout:** Maximum time allowed for the execution of the function block.

**VAR\_OUTPUT**

```
VAR_OUTPUT
  bBusy    : BOOL;
  bError   : BOOL;
  nErrId   : UDINT;
END_VAR
```

**bBusy**: This output is set when the function block is activated. It remains set until feedback is received.

**bError**: This output is set up after the bBusy output has been reset if there has been an error in transmission of the command.

**nErrId** : If the bError output is set, this parameter returns the TwinCAT XML Data Server error number.

**Requirements**

Development environment	Target system type	PLC libraries to be linked
TwinCAT v2.10.0	PC or CX (x86, ARM)	TcXmlDataSrv.Lib ( Standard.Lib; TcBase.Lib; TcSystem.Lib are included automatically )

## 5.2 Functions

### 5.2.1 F\_GetVersionTcXmlDataSrv



This function can be used to read PLC library version information.

**FUNCTION F\_GetVersionTcXmlDataSrv : UINT**

```
VAR_INPUT
  nVersionElement : INT;
END_VAR
```

**nVersionElement** : Version element to be read. Possible parameters:

- 1 : major number;
- 2 : minor number;
- 3 : revision number;

**Requirements**

Development environment	Target system type	PLC libraries to be linked
TwinCAT 2.10.0	PC or CX (x86, ARM)	TcXmlDataSrv.Lib ( Standard.Lib; TcBase.Lib; TcSystem.Lib are included automatically )

## 5.3 Constants

### 5.3.1 Global Variables

```
VAR_GLOBAL CONSTANT
    XMLSRV_AMSPORT :UINT :=10600;

    XMLSRV_IGR_CLOSE :UDINT := 121;
    XMLSRV_IGR_READ :UDINT := 122;
    XMLSRV_IGR_WRITE :UDINT := 123;
    XMLSRV_IGR_OPENREAD :UDINT := 124;
    XMLSRV_IGR_OPENWRITE :UDINT := 125;

    XMLSRV_SKIPMISSING :WORD := 0;
    XMLSRV_ADDMISSING :WORD := 1; (*for write commands*)

    XMLSRV_MAX_FRAGSIZE :UDINT := 16#40000;

    XMLSRVERROR_INTERNAL :UDINT:= 16#8000;
    XMLSRVERROR_NOTFOUND :UDINT:= 16#8001;
    XMLSRVERROR_PARSERROR :UDINT:= 16#8002;
    XMLSRVERROR_INCOMPATIBLE :UDINT:= 16#8003;
    XMLSRVERROR_NOMEMORY :UDINT:= 16#8004;
    XMLSRVERROR_ADDNODE :UDINT:= 16#8005;
    XMLSRVERROR_INVALIDXPATH :UDINT:= 16#8006;
END_VAR
```

### Requirements

Development Environment	Target System	PLC Libraries to include
TwinCAT v2.10.0	PC or CX (x86, ARM)	TcXmlDataSrv.Lib ( Standard.Lib; TcBase.Lib; TcSystem.Lib are included automatically )

## 6 Samples

In the following you will find Samples that show the handling of the TwinCAT XML Data Server. The samples are consecutively numbered and can be <https://infosys.beckhoff.com/content/1033/tcxmldatasrvce/Resources/11418381067/.zip>.

### Getting Started [▶ 21]

The basic handling of the TwinCAT XML Data Server is shown. Besides you get to know how to work with structures and arrays.

### Function Blocks [▶ 23]

Four samples show the usage and configuration of the function blocks included in TcXmlDataSrv.Lib. (Sample 1-4)

### Further Samples [▶ 25]

This document includes further samples which show an initialization once at program startup and cyclic as well as event-driven writing. (Sample 5-6)

### Production Sample [▶ 27]

This sample shows the processing of a small production order. It makes use of FB\_XmlSrvReadByName and FB\_XmlSrvWriteByName. (Sample 7)

## 6.1 Getting Started

In the following you will get to know the basics in working with the TwinCAT XML Data Server.

### Primitive data types

The table below shows the supported primitive data types

Data type	PLC example	Xml example
UDINT, DINT, UINT, INT, USINT, SINT, DWORD, WORD, BYTE	value1 : DINT := -1;  value2 : UDINT := 65535;	<dataentry> <MAIN.value1>-1</MAIN.value1> <MAIN.value2>65535</MAIN.value2> </dataentry>
LREAL, REAL	value1 : LREAL = 1.2;	<dataentry> <MAIN.value1>1.2</MAIN.value1> </dataentry>
STRING	str1 : STRING = 'hallo';	<dataentry> <MAIN.str1>hallo</MAIN.str1> </dataentry>
TIME, DATE, TOD,DT	date1:DATE :=D#2005-05-04 ; (* Time-Typen werden in der XML- Datei als DWORD gespeichert*)	<dataentry> <MAIN.date1>1115164800</MAIN.date1> </dataentry>
BOOL	bool1:BOOL := TRUE;  bool2:BOOL := FALSE;	<dataentry> <MAIN.bool1>true</MAIN.bool1> <MAIN.bool2>false</MAIN.bool2> </dataentry>

Example: The plc global variable Var1 ist typed as DINT. This is the XML structure

```
<dataentry>
  <Var1>10</Var1>
</dataentry>
```

The input parameters of the function block FB\_XmlSrvRead must be set as follows:

```

fbRead.pSymAddr      := ADR(value1);
fbRead.cbSymSize     := SIZEOF(value1);
fbRead.sFilePath      := 'C:\Test.xml';
fbRead.sXPath         := '/dataentry/Var1';

```

The root element in the XML file and the name of the variable are freely selectable in the XML file. These values must be specified in the input parameters `sXPath`, `sFilePath`. Also, multiple variable definitions can be stored in a single xml file:

```

<dataentry>
  <Var1>10</Var1>
  <Var2>100</Var2>
  <Var3>
    <a>100</a>
    <b>10</b>
  </Var3>
</dataentry>

```

To access the definition vor `Var3.a` set `sxpath:='dataentry/Var3.a'`

## Structures

Structures in the XML file have the same hierarchical structure as in the PLC. However, there is the possibility to skip individual sub elements in the XML file. The individual sub elements of the structure must have the same names as in the PLC, otherwise they are skipped. If sub elements in the XML file cannot be converted to the correct data type, they will also be skipped.

Example: The global variable `Var2` is typed as `ST_MYSTRUCT`:

```

TYPE ST_MYSTRUCT:
STRUCT
  a:  UINT;
  b:  DINT;
  c:  LREAL;
  d:  STRING;
END_STRUCT
END_TYPE

```

A possible xml file representation:

```

<variables>
  <Var1>10</Var1>
  <Var2>                                <!-- sXPath := '\variables\Var2' --!>
    <a>100</a>
    <b>-10</b>
    <c>1.2</c>
    <d>Hallo</d>
  </Var2>
</variables>

```

In this case, all sub elements are completely and correctly defined, so the variable is fully initialized. In the following example, however, only the sub element `c` is serialized:

```

<variables>
  <Var1>10</Var1>
  <Variable2>                            <!-- sXPath := '\variables\Variable2' --!>
    <Info>Test entry</Info>
    <a>-100</a>
    <c>1.2</c>
  </Variable2>
</variables>

```

Sub element `a` cannot be converted because it is negative and a `UINT` is required. The sub-element `b` is completely missing. The `<Info>` tag is skipped because it is not defined in the PLC file.

## Arrays

To specify the index of arrays, the "Index" attribute must be used for the individual array elements. Individual array elements can also be omitted. These are then simply skipped.

Example: the plc variable `array1` is defined as: `ARRAY[1..4] OF DINT`.

A possible xml file representation:

```
<dataentry>
  <array1 index="1">10</array1>
  <array1 index="2">10</array1>
  <array1 index="3">10</array1>
  <array1 index="4">10</array1>
</dataentry>
```

## Requirements

Entwicklungsumgebung	Zielplattform	Einzubindende SPS Bibliotheken
TwinCAT v2.10.0	PC or CX (x86, ARM)	TcXmlDataSrv.Lib

## 6.2 Function blocks

The following samples show the handling of the functionblocks of the tcXmlDataSrv-Library. The PLC projekt, which contains the samples, can be <https://infosys.beckhoff.com/content/1033/tcxmldatasrvce/Resources/11418381067/.zip>.

All samples work with the structure ST\_MYSTRUCT, which in turn includes ST\_INNTERSTRUCT. Both Structures are shown in the following:

### Structures

```
TYPE ST_MYSTRUCT:
STRUCT
  fReal      : REAL;
  bBool      : ARRAY [0..2] OF BOOL;
  stInner   : ST_INNTERSTRUCT;
END_STRUCT
END_TYPE

TYPE ST_INNTERSTRUCT:
STRUCT
  nInteger   : INT;
  sString     : STRING;
END_STRUCT
END_TYPE
```

### Sample 1: Basic printing procedure with FB\_XmlSrvWrite

In the first step the structure ST\_MyStruct shall be written to an XML file. The mode is set to XMLSRV\_ADDMISSING, so that the XML file will be created automatically (if it does not already exist) as well as the structure in it. Folders will not be created automatically! This method is recommended even then, if you do not intend to write but just to read the file. So, the XML file does not have to be created manually, which saves time and avoids mistakes.

```
(* Sample1 creates an XML-file under the path C:\Test.xml and writes value1 to it.
FUNCTIONBLOCK: FB_XmlSrvWrite *)
PROGRAM Sample1
VAR
  value1      : ST_MyStruct;
  fbXmlSrvWrite : FB_XmlSrvWrite;
  bExecute    : BOOL;
  sFilePath   : T_MaxString := 'C:\Test.xml'; (* CE: '\Hard Disk\Test.xml' *)
  sXPath      : T_MaxString := '/dataentry/MAIN.value1';
END_VAR

fbXmlSrvWrite(
  nMode      := XMLSRV_ADDMISSING,
  pSymAddr   := ADR(value1),
  cbSymSize  := SIZEOF(value1),
  sFilePath  := sFilePath,
  sXPath     := sXPath,
  bExecute   := bExecute
);
bExecute:= TRUE;
```

## Sample 2: Basic printing procedure with FB\_XmlSrvWriteByName

Sample 2 has the same result as sample 1, but makes use of FB\_XmlSrvWriteByName. However Sample 1 is more performant.

```
(* Sample2 creates an XML-file under the path C:\Test.xml and writes value1 to it.
FUNCTIONBLOCK: FB_XmlSrvWriteByName *)
PROGRAM Sample2
VAR
    value1      : ST_MyStruct;
    fbXmlSrvWrite : FB_XmlSrvWriteByName;
    bExecute     : BOOL;
    sSymName    : T_MaxString := 'Sample2.value1';
    sFilePath   : T_MaxString := 'C:\Test.xml'; (* CE: '\Hard Disk\Test.xml' *)
    sXPath      : T_MaxString := '/dataentry/MAIN.value1';
END_VAR

fbXmlSrvWrite(
    nMode      := XMLSRV_ADDMISSING,
    sSymName   := sSymName,
    sFilePath  := sFilePath,
    sXPath     := sXPath,
    bExecute   := bExecute
);
bExecute:= TRUE;
```

### XML file

No matter which function block is used, the XML file '*Test.xml*' will be created under *C:\*. For that you get the same XML-content both times, sXPath has to be the same ('/dataentry/MAIN.value1'). It does not matter that value1 is not directly created in the main, but in the specific program. This path in TwinCAT is set by sSymName (Sample 2): 'Sample2.value1'.

```
<dataentry>
    <MAIN.value1>
        <fReal>0</fReal>
        <bBool index="0">false</bBool>
        <bBool index="1">false</bBool>
        <bBool index="2">false</bBool>
        <stInner>
            <nInteger>0</nInteger>
            <sString></sString>
        </stInner>
    </MAIN.value1>
</dataentry>
```

## Sample 3: Basic reading procedure with FB\_XmlSrvRead

In the following the structure created in Sample 1 or Sample 2 shall be read.

```
(* Sample3 reads an XML-file (C:\Test.xml) FUNCTIONBLOCK: FB_XmlSrvRead *)
PROGRAM Sample3
VAR
    value1      : ST_MyStruct;
    fbXmlSrvRead : FB_XmlSrvRead;
    bExecute     : BOOL;
    sFilePath   : T_MaxString := 'C:\Test.xml'; (* CE: '\Hard Disk\Test.xml' *)
    sXPath      : T_MaxString := '/dataentry/MAIN.value1';
END_VAR

fbXmlSrvRead(
    pSymAddr      := ADR(value1),
    cbSymSize     := SIZEOF(value1),
    sFilePath     := sFilePath,
    sXPath        := sXPath,
    bExecute      := bExecute
);
bExecute:= TRUE;
```

## Sample 4: Basic reading procedure with FB\_XmlSrvReadByName

Sample 4 shows the reading procedure under usage of FB\_XmlSrvReadByName.

```
(* Sample4 reads an XML-file (C:\Test.xml) FUNCTIONBLOCK: FB_XmlSrvReadByName *)
PROGRAM Sample4
VAR
    value1      : ST_MyStruct;
    fbXmlSrvRead : FB_XmlSrvReadByName;
```

```

bExecute      : BOOL;
sSymName     : T_MaxString := 'Sample4.value1';
sFilePath    : T_MaxString := 'C:\Test.xml'; (* CE: '\Hard Disk\Test.xml' *)
sXPath       : T_MaxString := '/dataentry/MAIN.value1';
END_VAR

fbXmlSrvRead(
  sSymName      := sSymName,
  sFilePath     := sFilePath,
  sXPath        := sXPath,
  bExecute      := bExecute
);
bExecute:= TRUE;

```

Here again (as in sample 2) you must differentiate between sSymName and sXPath: sXPath sets the path within the XML file - determined in sample 1 and 2. sSymName on the other hand sets the symbol name of the variable in TwinCAT, which is 'Sample4.value1'.

## Requirements

Entwicklungsumgebung	Zielplattform	Einzubindende SPS Bibliotheken
TwinCAT v2.10.0	PC or CX (x86, ARM)	TcXmlDataSrv.Lib

## 6.3 Further Samples

The following samples show different types of application of the TwinCAT XML Data Servers. The PLC-project, which contains the samples, can be <https://infosys.beckhoff.com/content/1033/tcxmldatasrvce/Resources/11418381067/.zip>.

Sample 5 shows an initialization once at program startup, Sample 6 shows cyclic and event-driven printing procedures. Both samples again use the structure ST\_MYSTRUCT, which in turn includes ST\_INNTERSTRUCT. Both Structures are shown in the following:

### Structures

```

TYPE ST_MYSTRUCT:
STRUCT
  fReal      : REAL;
  bBool      : ARRAY [0..2] OF BOOL;
  stInner   : ST_INNTERSTRUCT;
END_STRUCT
END_TYPE

TYPE ST_INNTERSTRUCT:
STRUCT
  nInteger   : INT;
  sString    : STRING;
END_STRUCT
END_TYPE

```

### Sample 5: Initialization once at program startup

Sample 5 shows the initialization of value1 once at program startup. Therefore FB\_XmlSrvRead is used.

```

(* Sample5 reads and initializes value1 when the PLC is started FUNCTIONBLOCK: FB_XmlSrvRead *)
PROGRAM Sample5
VAR
  value1      : ST_MyStruct;
  fbXmlSrvRead : FB_XmlSrvRead;
  bExecute    : BOOL;
  sFilePath   : T_MaxString := 'C:\Test.xml'; (* CE: '\Hard Disk\Test.xml' *)
  sXPath      : T_MaxString := '/dataentry/MAIN.value1';
  nState      : INT := 0;
END_VAR

CASE nState OF
0: (* initialize *)
  fbXmlSrvRead(
    pSymAddr  := ADR(value1),
    cbSymSize := SIZEOF(value1),
    sFilePath := sFilePath,
    sXPath    := sXPath,
    bExecute  := bExecute
  );

```

```

fbXmlSrvRead(bExecute:= TRUE);
nState:= 1;

1: (* wait for read operation *)
fbXmlSrvRead(bExecute:= FALSE);
IF NOT fbXmlSrvRead.bBusy AND NOT fbXmlSrvRead.bError THEN
  nState:= 2;
ELSIF fbXmlSrvRead.bError THEN
  nState:= 100;
END_IF

2: (* operations *)
;

100:(* errorState *)
;

END_CASE

```

### Sample 6: Cyclic and event-driven printing

The following sample creates a new XML file every 20 seconds and writes the above-mentioned structure to it. The filename is made up of the current windows-date, -time and the string sFileName. Furthermore, the printing procedure can be started by pressing a button (or setting the respective variable bButton). If the printing procedure is triggered twice a second, the latest file will be overwritten.

```

(* Sample6: Every 20s value1 will be written into a new XML-File named after the current date and
   time. Furthermore you can activate the printing procedure by pressing a button (or setting the
   corresponding variable *)
PROGRAM Sample6
VAR
  value1          : ST_MyStruct;
  fbXmlSrvWrite  : FB_XmlSrvWrite;

  sFileFolder     : T_MaxString := 'C:\'; (* CE: '\Hard Disk\' *)
  sFileName       : T_MaxString:= '_test.xml';
  sFilePathWrite  : T_MaxString
  (*sFilePathWrite = sFileFolder + time + sFileName*)

  sXPathWrite     : T_MaxString := '/dataentry/MAIN.value1';
  ntGetTime       : NT_GetTime;
  stMyTimestruct  : TIMESTRUCT;
  iState          : INT := 1;
  bTwentySec      : BOOL:= FALSE;
  bButton         : BOOL:= FALSE;
  bTwentySecOver  : BOOL;
  triggerWrite    : R_TRIG;
  triggerButton   : R_TRIG;
END_VAR

triggerButton(CLK:= bButton);

CASE iState OF
 0: (* idle state *)
;

1: (* initialize *)
  fbXmlSrvWrite(nMode:=XMLSRV_ADDMISSING, pSymAddr:= ADR(value1),
    cbSymSize:= SIZEOF(value1));
  ntGetTime(START:= TRUE, TIMESTR=>stMyTimestruct);  (* get Windows time *) IF NOT ntGetTime.BUSY AND NOT ntGetTime.ERR THEN
    iState:= 2;
  ELSIF ntGetTime.ERR THEN
    iState:= 100;
  END_IF

 2: (* working state *)
  (* change some values - replace with production-process *)
  value1.stInner.nInteger:= value1.stInner.nInteger + 1;
  IF value1.stInner.nInteger = 32767 THEN
    value1.stInner.nInteger:= 0;
  END_IF(* get Windows time *)
  ntGetTime(START:= FALSE);
  IF NOT ntGetTime.BUSY AND NOT ntGetTime.ERR THEN
    ntGetTime(START:= TRUE, TIMESTR=>stMyTimestruct);
  ELSIF ntGetTime.ERR THEN
    iState:= 100;
  END_IF(* check if 20s have passed*) IF stMyTimestruct.wSecond = 0 OR stMyTimestruct.wSecond = 20
  OR stMyTimeStruct.wSecond = 40 THEN

```

```

        bTwentySecOver:= TRUE;
    ELSE
        bTwentySecOver:= FALSE;
END_IF(* if 20s have passed => trigger writing-process *)
triggerWrite(CLK:=bTwentySecOver);
IF (triggerWrite.Q OR triggerButton.Q) AND NOT fbXmlSrvWrite.bBusy
    AND NOT fbXmlSrvWrite.bError THEN (* create filename *)
    sFilePathWrite:= CONCAT(sFileFolder, SYSTEMTIME_TO_STRING(stMyTimestruct)); (* set folder + time *)
    sFilePathWrite:= DELETE(STR:= sFilePathWrite, LEN:= 4 ,
                           POS:= LEN(STR:=sFilePathWrite)-3); (* delete milliseconds *)
    sFilePathWrite:= REPLACE(STR1:= sFilePathWrite , STR2:= '.', L:= 1,
                           P:= LEN(STR:=sFilePathWrite)-2); (* replace colon with point *)
    sFilePathWrite:= REPLACE(STR1:= sFilePathWrite , STR2:= '.', L:= 1,
                           P:= LEN(STR:=sFilePathWrite)-5); (* replace colon with point *)
    sFilePathWrite:= CONCAT(sFilePathWrite, sFileName); (* add filename (default: test) *)
(* write *)
    fbXmlSrvWrite(sFilePath:=sFilePathWrite, sXPath:=sXPathWrite, bExecute:= TRUE);
ELSIF fbXmlSrvWrite.bError THEN
    iState:= 100;
END_IF(* reset fbXmlSrvWrite *)IF fbXmlSrvWrite.bBusy AND NOT ntGetTime.ERR THEN
    fbXmlSrvWrite(bExecute:= FALSE);
ELSIF ntGetTime.ERR THEN
    iState:= 100;
END_IF

100: (* error state*)
;

END_CASE

```

## Requirements

Entwicklungsumgebung	Zielplattform	Einzubindende SPS Bibliotheken
TwinCAT v2.10.0	PC or CX (x86, ARM)	TcXmlDataSrv.Lib

## 6.4 Sample 7 (Production Sample)

The production data are read, the production is carried out and, according to the quantity and the production order, completed with an entry in the XML file.

To start the program the XML file needs to be stored at the corresponding place of the data path and the variable bStart needs to be set TRUE in the PLC program.

The **PLC-projekt**, which includes this sample, can be <https://infosys.beckhoff.com/content/1033/tcxmldatasrvce/Resources/11418381067/.zip>.

### Variable declaration

```

PROGRAM Sample7
VAR
    fbXmlSrvReadByName      : FB_XmlSrvReadByName;
    fbXmlSrvWriteByName      : FB_XmlSrvWriteByName;

    value          : ST_MyProductionStruct;

    state          : INT := 0;
    R_Edge         : R_TRIG;
    bStart         : BOOL;
    bError         : BOOL;
    nErrId        : UDINT;
END_VAR

```

### Structure ST\_MyProductionStruct

```

TYPE ST_MyProductionStruct :
STRUCT
    rLength      : REAL;
    rWidth       : REAL;
    rHeight      : REAL;
    iQuantity    : INT;
    iCounter     : INT;

```

```
bReady      : BOOL;
stInfo      : STRING;
END_STRUCTEND_TYPE
```

## PLC Program

```
(* The production data are read, the production is carried out and, according to the
   quantity and the production order, completed with an entry in the XML file.
   To start the program the XML file needs to be stored at the corresponding place
   of the data path and the variable bStart needs to be set TRUE in the PLC program. *)
R_Edge (CLK := bStart);
IF R_Edge.Q THEN
  state := 1;
END_IFCASE state OF
0: (* idle state *)
  ;
1: (* init state *)
  fbXmlSrvReadByName( sNetId      := '',
                      sSymName    := 'Sample7.value',
                      sFilePath   := 'C:\Production1.xml',
                      sXPath     := '/dataentry/MAIN.value',
                      bExecute    := TRUE,
                      tTimeout    := t#10s,
                      bError      => bError,
                      nErrId      => nErrId);
  state := 2;
2:
  fbXmlSrvReadByName(bExecute := FALSE);
  IF NOT fbXmlSrvReadByName.bBusy AND NOT fbXmlSrvReadByName.bError THEN
    state := 3;
  ELSIF fbXmlSrvReadByName.bError THEN
    state := 100;
  END_IF
3: (* working state *)
  IF value.bReady = TRUE THEN
    value.stInfo := 'The order was already processed!';
    (* replace your production XML file! *)
    state := 4;
  RETURN;
  END_IF
(* Call production program with
 new length, width and height here *)

  value.iCounter := value.iCounter + 1;
  IF value.iCounter = value.iQuantity THEN
    value.bReady := TRUE;
    state := 4;
  END_IF
4: (* documentation state *)
  fbXmlSrvWriteByName( sNetId      := '',
                      nMode       := XMLSRV_SKIPMISSING,
                      sSymName    := 'Sample7.value',
                      sFilePath   := 'C:\Production1.xml',
                      sXPath     := '/dataentry/MAIN.value',
                      bExecute    := TRUE,
                      tTimeout    := t#10s,
                      bError      => bError,
                      nErrId      => nErrId);
  state := 5;
5:
  fbXmlSrvWriteByName(bExecute := FALSE);
  IF NOT fbXmlSrvWriteByName.bBusy AND NOT fbXmlSrvWriteByName.bError THEN
    state := 0;
  ELSIF fbXmlSrvWriteByName.bError THEN
    state := 100;
  END_IF
100: (* error state *)
  ;
END_CASE
```

**XML File**

```
<dataentry>
  <MAIN.value>
    <rLength>65.85</rLength>
    <rWidth>30</rWidth>
    <rHeight>2.5</rHeight>
    <iQuantity>500</iQuantity>
    <iCounter>0</iCounter>
    <bReady>false</bReady>
    <stInfo></stInfo>
  </MAIN.value>
</dataentry>
```

**Requirements**

Entwicklungsumgebung	Zielplattform	Einzubindende SPS Bibliotheken
TwinCAT v2.10.0	PC or CX (x86, ARM)	TcXmlDataSrv.Lib

## 7 Appendix

### 7.1 TwinCAT XML Data Server error codes

#### Requirements

Offset + error code	Range	Description
0x00000000 + TwinCAT system error	0x00000000-0x00007800	TwinCAT system error (including ADS error codes)
0x00008000 + <u>internal TwinCAT XML Data Server error</u> [► 30]	0x00008000-0x000080FF	Internal TwinCAT XML Data Server error

### 7.2 Internal error codes of the TwinCAT XML Data Server

#### Requirements

Code	Description	Symbolic name
0x00008000	Internal error	XMLSRVERROR_INTERNAL
0x00008001	Handle not found.	XMLSRVERROR_NOTFOUND
0x00008002	Error during parsing of the XML file	XMLSRVERROR_PARSERERROR
0x00008003	Incompatible data type.	XMLSRVERROR_INCOMPATIBLE
0x00008004	Error during memory allocation	XMLSRVERROR_NOMEMORY
0x00008005	Error during adding of an XML node	XMLSRVERROR_ADDNODE
0x00008006	Invalid sXPath	XMLSRVERROR_INVALIDXPath
0x00008007	Invalid String in TC	XMLSRVERROR_INVALIDSTRING
0x00008800	Invalid Client Handle	XMLSRVERROR_INVALIDCLIENTHANDLE
0x00008900	Wrong Version of TcXmlDataSrv.exe in use (TC2 instead of TC3)	XMLSRVERROR_INVALIDTWINCATVERSION



More Information:  
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